

Modeling



A Volkswagen Beetle becomes the subject of a 1970 simulation project. Ivan Sutherland(left) and assistants plot coordinates for digitizing the car.

Modeling the Everyday World

Three broad areas:

- **Modeling (Geometric) = Shape**
- **Animation = Motion/Behavior**
- **Rendering = Appearance**

Geometric Modeling

1. How to represent 3d shapes

- Polygonal meshes



Stanford Bunny
69451 triangles

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David, Digital Michelangelo Project
28,184,526 vertices, 56,230,343 triangles

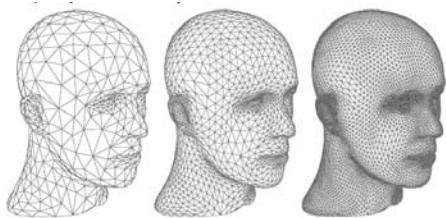
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Geometric Modeling

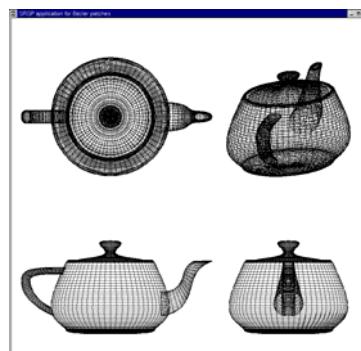
1. How to represent 3d shapes

- Smooth surfaces

- Bicubic spline surfaces
- Subdivision surfaces



Caltech Head



Utah Teapot

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Geometric Modeling

1. How to represent 3D shapes

2. How to create 3D shapes

1. CAD tools

2. Scanners

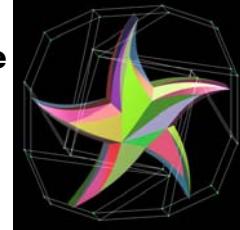
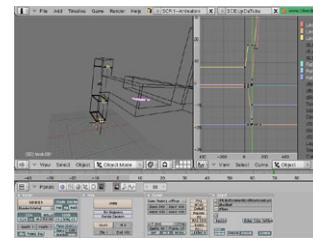
3. Procedurally

3. How to manipulate 3D shapes

1. Deform/skin/morph/animate

2. Smooth/compress

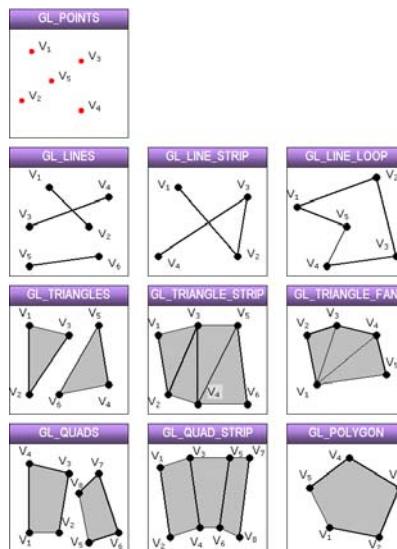
3. Set operations, ...



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OpenGL Primitives



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Primitive API

```
glBegin(GL_POLYGON);
    glVertex3f(-1.0,-1.0,0.0);
    glVertex3f(1.0,-1.0,0.0);
    glVertex3f(1.0,1.0,0.0);
    glVertex3f(-1.0,1.0,0.0);
glEnd();
```

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Polygons

```
float v1[3] = {-1.0,-1.0,0.0};
float v2[3] = { 1.0,-1.0,0.0};
float v3[3] = { 1.0, 1.0,0.0};
float v4[3] = {-1.0, 1.0,0.0};

glBegin(GL_POLYGON);
    glVertex3fv(v1);
    glVertex3fv(v2);
    glVertex3fv(v3);
    glVertex3fv(v4);
glEnd();
```

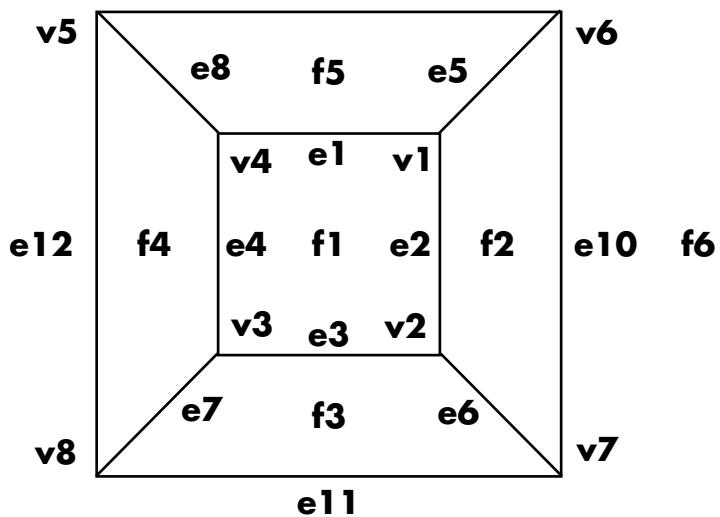
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Topology

$$\#f - \#e + \#v = 2$$

e9



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Points/Polygons

```
typedef float Point[3];
Point verts[6] = {
    {-1.,-1.,-1.},
    { 1.,-1.,-1.},
    { 1., 1.,-1.},
    {-1., 1.,-1.},
    {-1.,-1., 1.},
    { 1.,-1., 1.},
    { 1., 1., 1.},
    {-1., 1., 1.},
};

face(int a, int b, int c, int d) {
    glBegin(GL_POLYGON);
    glVertex3fv(verts[a]);
    glVertex3fv(verts[b]);
    glVertex3fv(verts[c]);
    glVertex3fv(verts[d]);
    glEnd();
}

// Note consistent ccw orientation!
cube() {
    face(0,3,2,1);
    face(2,3,7,6);
    face(0,4,7,3);
    face(1,2,6,5);
    face(4,5,6,7);
    face(0,1,5,4);
}
```

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Points/Polygons

```
typedef float Point[3];
Point verts[6] = {
    {-1., -1., -1.},
    { 1., -1., -1.},
    { 1.,  1., -1.},
    {-1.,  1., -1.},
    {-1., -1.,  1.},
    { 1., -1.,  1.},
    { 1.,  1.,  1.},
    {-1.,  1.,  1.},
};

int polys[6][4] = {
    {0,3,2,1},
    {2,3,7,6},
    {0,4,7,3},
    {1,2,6,5},
    {4,5,6,7},
    {0,1,5,4}
}
```

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```
face(int a, int b, int c, int d) {
    glBegin(GL_POLYGON);
    glVertex3fv(verts[a]);
    glVertex3fv(verts[b]);
    glVertex3fv(verts[c]);
    glVertex3fv(verts[d]);
    glEnd();
}

cube() {
    for( int i = 0; i < n; i++ )
        face(polys[i][0],
              polys[i][1],
              polys[i][2],
              polys[i][3]);
}
```

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Representations

Polygons

- + Simple
- Redundant information

Points/Polygons

- + Share vertices (compress/consistency)

Additional topological information

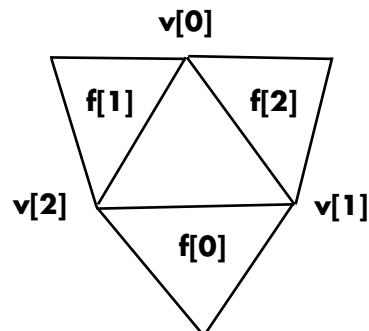
- + Constant time access to neighbors
 - More advanced algorithms such as
surface normal calculation, subdivision ...
- Additional storage for topology
- More complicated data structures

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Triangle Adjacency

```
struct Vert {  
    Point pt;  
    Face *f;  
}  
  
struct Face {  
    Vert *v[3];  
    Face *f[3];  
}
```



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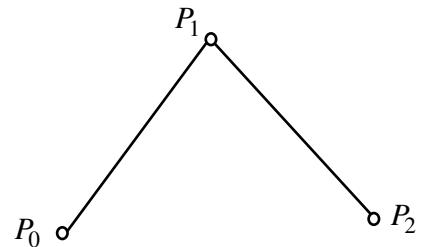
Recursive Subdivision

Bezier curves
Subdivision surfaces
Fractals

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Chaiken's Algorithm

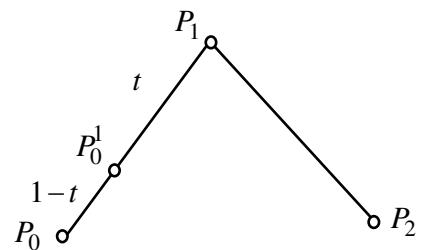


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Chaiken's Algorithm

$$P_0^1 = (1-t)P_0 + tP_1$$



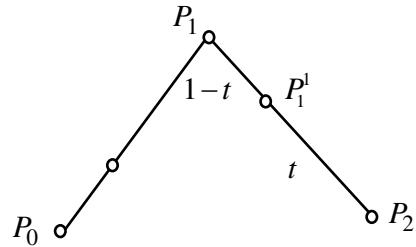
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Chaiken's Algorithm

$$P_0^1 = (1-t)P_0 + tP_1$$

$$P_1^1 = (1-t)P_1 + tP_2$$



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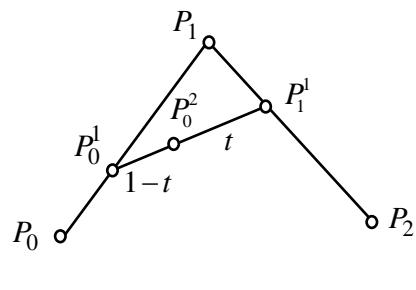
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Chaiken's Algorithm

$$P_0^1 = (1-t)P_0 + tP_1$$

$$P_1^1 = (1-t)P_1 + tP_2$$

$$P_0^2 = (1-t)P_0^1 + tP_1^1$$



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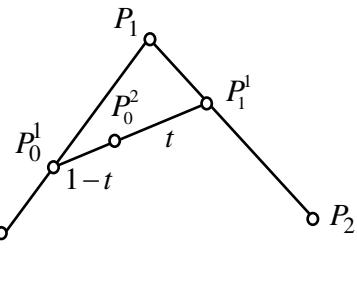
Chaiken's Algorithm

$$P_0^1 = (1-t)P_0 + tP_1$$

$$P_1^1 = (1-t)P_1 + tP_2$$

$$P_0^2 = (1-t)P_0^1 + tP_1^1$$

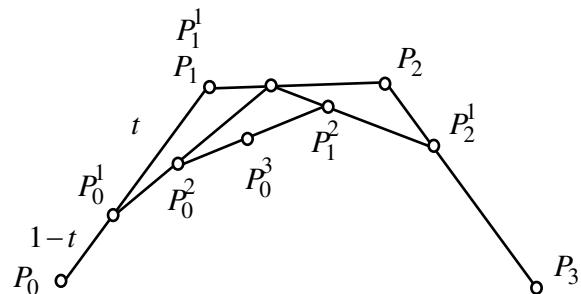
$$P(t) = P_0^2$$



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Bezier Curves

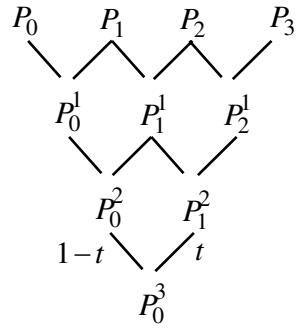


Generalize last algorithm to 4 points

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Bezier Curve = Bernstein Polynomials



$$P(t) = \sum_{i=0}^3 P_i B_i^3(t)$$

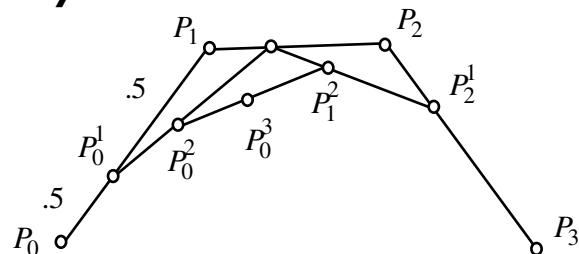
$$B_i^3(t) = \binom{3}{i} t^i (1-t)^{3-i}$$

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Bezier Curves – Midpoint Subdivision

Recursively divide into two curves



Left side

$$Q_0 = P_0$$

$$Q_1 = P_0^1$$

$$Q_2 = P_0^2$$

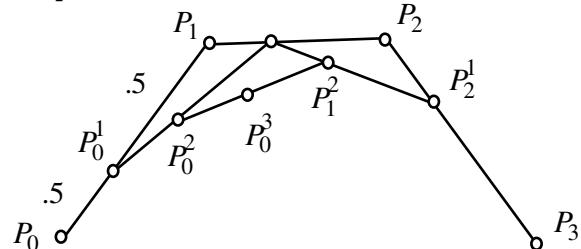
$$Q_3 = P_0^3$$

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Bezier Curves – Midpoint Subdivision

Recursively divide into two curves



Left side

$$Q_0 = P_0$$

$$Q_1 = P_0^1 = \frac{1}{2}P_0 + \frac{1}{2}P_1$$

$$Q_2 = P_0^2 = \frac{1}{4}P_0 + \frac{1}{2}P_1 + \frac{1}{4}P_2$$

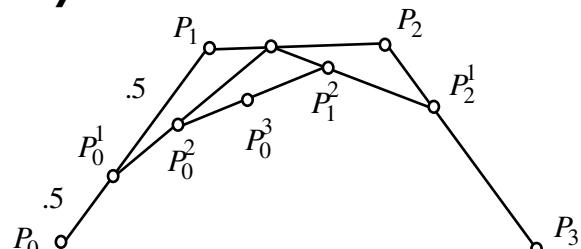
$$Q_3 = P_0^3 = \frac{1}{8}P_0 + \frac{3}{8}P_1 + \frac{3}{8}P_2 + \frac{1}{8}P_3$$

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Bezier Curves – Midpoint Subdivision

Recursively divide into two curves



Right side

$$R_0 = P_0^3$$

$$R_1 = P_1^2$$

$$R_2 = P_2^1$$

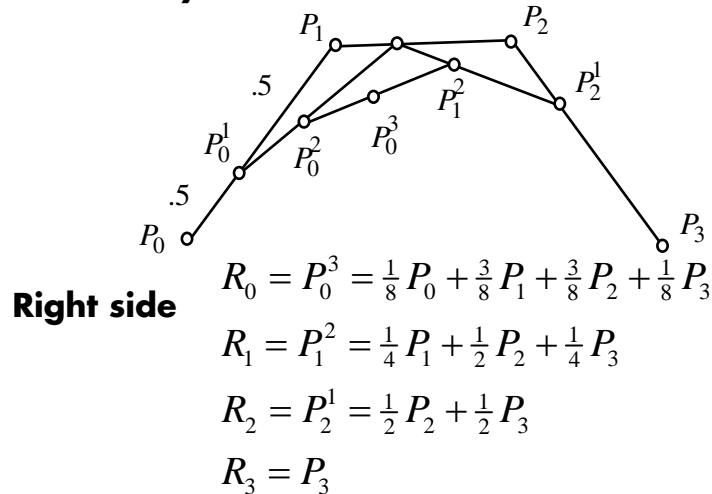
$$R_3 = P_3$$

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Bezier Curves – Midpoint Subdivision

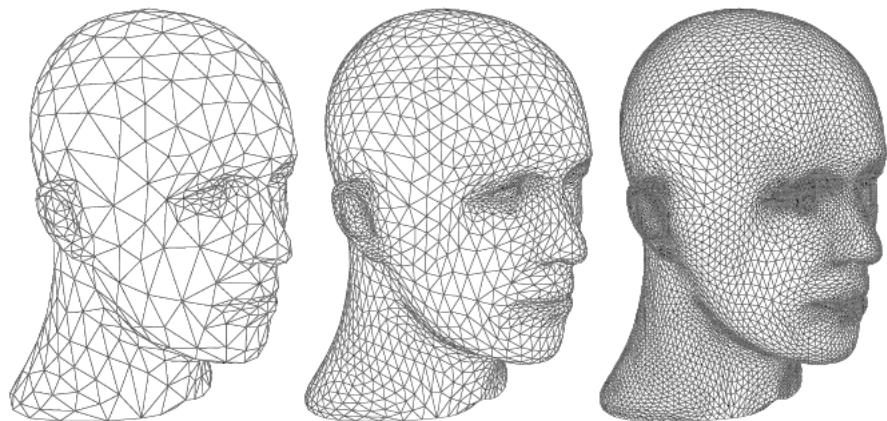
Recursively divide into two curves



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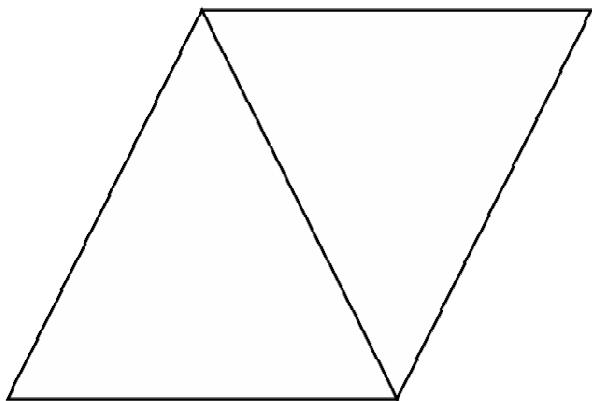
Subdivision Surfaces



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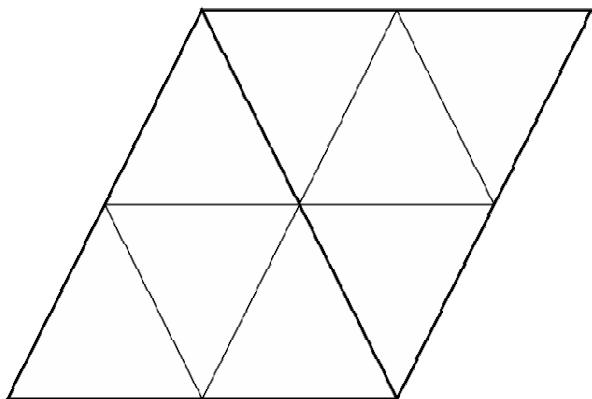
Triangle Mesh



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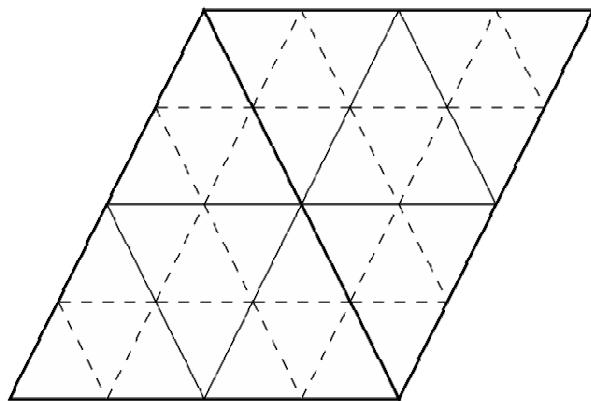
Triangle Mesh – Topological Subdivide



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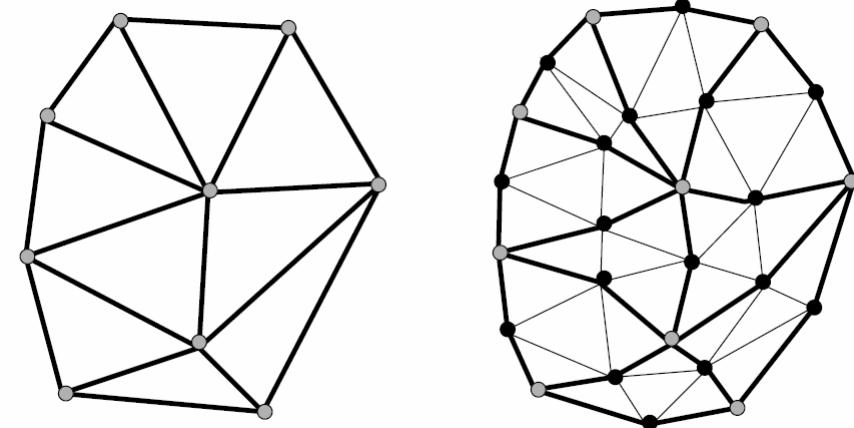
Triangle Mesh – Topological Subdivide



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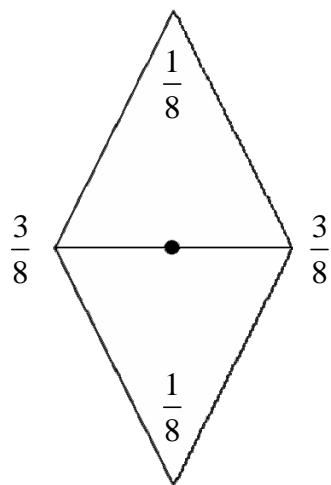
Triangle Mesh – Subdivide



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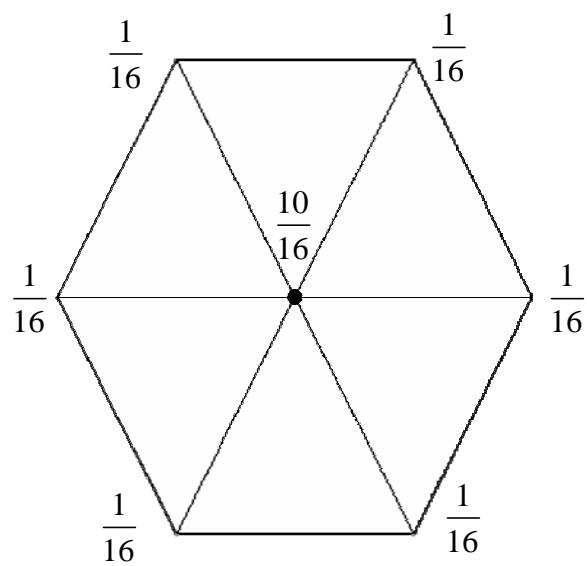
Loop Algorithm - Edge



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Loop Algorithm - Vert

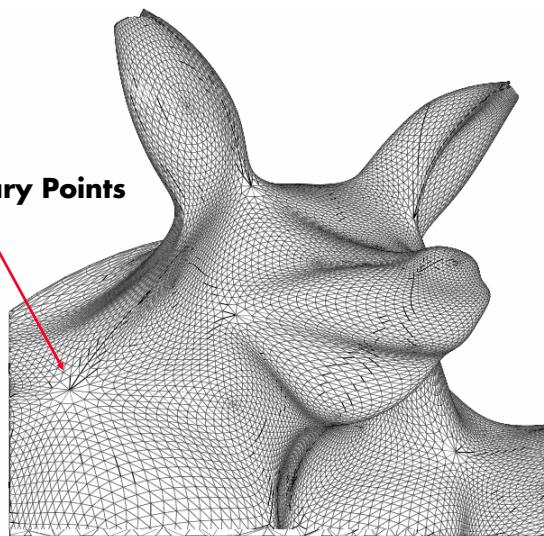


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Semi-Regular Meshes

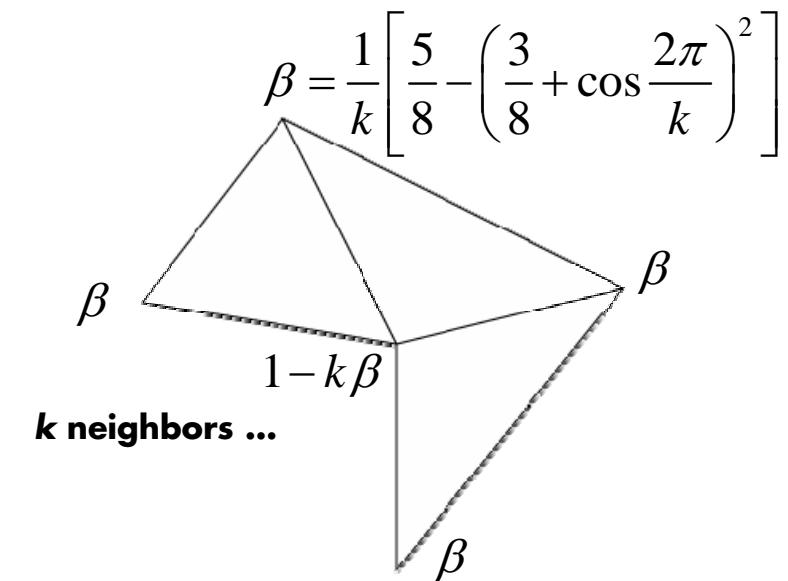
Extraordinary Points



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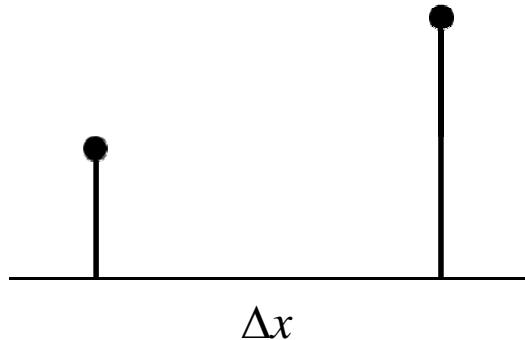
Loop Subdivision – Extraordinary Vertex



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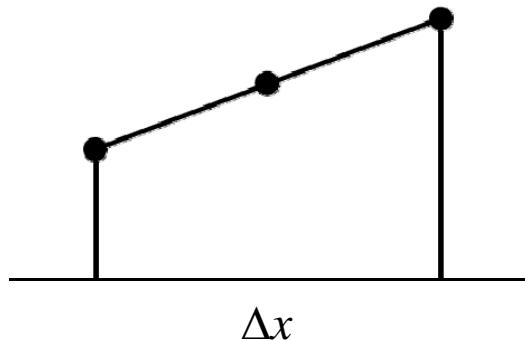
Fractal Subdivision



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Fractal Subdivision

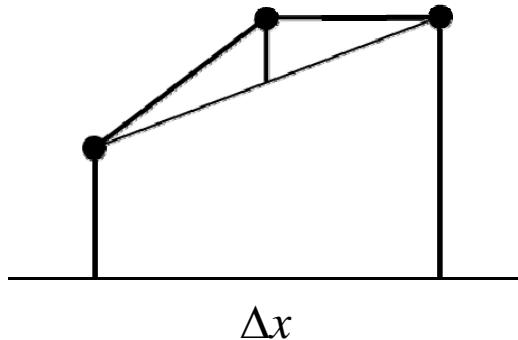


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Fractal Subdivision

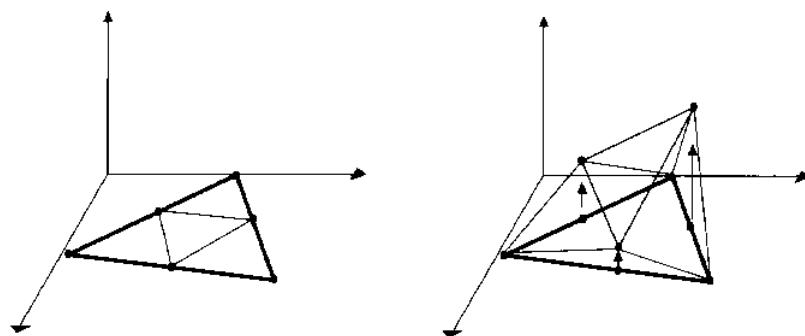
$$\Delta y = \text{random}() \bullet \Delta x$$



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Fractal Subdivision: Height Field



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Summary

Digital geometry processing ala signal processing

Three common representations

- **Dense polygon meshes**
- **Bicubic surfaces**
- **Subdivision surfaces**

Common operations

- **Instancing**
- **Transformation: linear and non-linear (bend)**
- **Compressing and simplifying**
- **...**