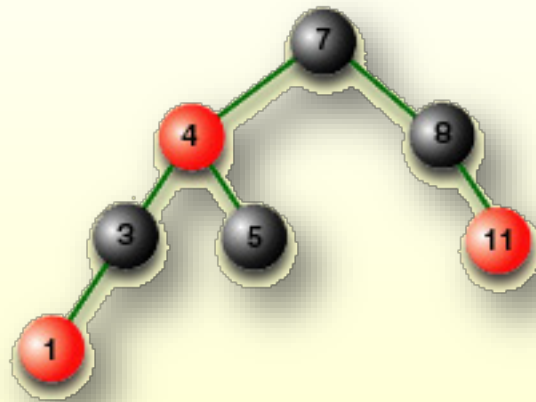


CS161: Design and Analysis of Algorithms



Lecture 10 Leonidas Guibas

Outline

- ◆ Review of last lecture: **Binary Search Trees**
- ◆ Today: **Red-Black Trees**
 - ◆ Properties/Analysis
 - ◆ Insertion/Deletion
- ◆ 2-3, and 2-3-4 Trees

Balanced Trees

Slides modified from

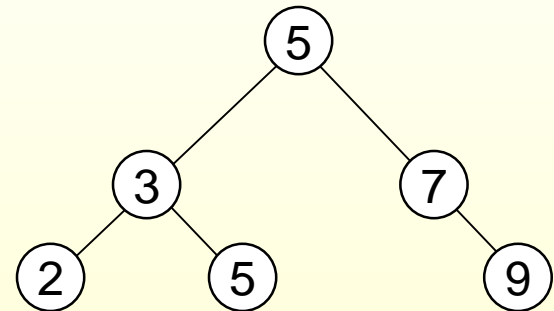
- www.cse.unr.edu/~bebis/CS477/
- <http://www.cs.unc.edu/~lin/COMP122-F99/>
- www.dsm.fordham.edu/~agw/.../Chapter19-BalancedSearchTrees.ppt

Binary Search Tree Property

- Binary search tree order property:

- If y is in left subtree of x ,
then $\text{key}[y] \leq \text{key}[x]$

- If y is in right subtree of x ,
then $\text{key}[y] \geq \text{key}[x]$



Red-black trees are binary search trees.

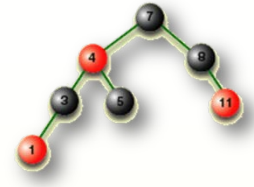
Binary Search Trees - Summary

- ◆ Operations on binary search trees:
 - ◆ SEARCH $O(h)$
 - ◆ PREDECESSOR $O(h)$
 - ◆ SUCCESOR $O(h)$
 - ◆ MINIMUM $O(h)$
 - ◆ MAXIMUM $O(h)$
 - ◆ INSERT $O(h)$
 - ◆ DELETE $O(h)$
- ◆ These operations are fast if the height of the tree is **small** – otherwise their performance is similar to that of a linked list

Tree Height

- ◆ The height h of a binary search tree on n items can be as high as $n-1$
- ◆ However, if it is built by inserting the elements in random order, then the expected height is $O(\lg n)$.
- ◆ With red-black trees, we aim to guarantee that the height is always $O(\lg n)$.

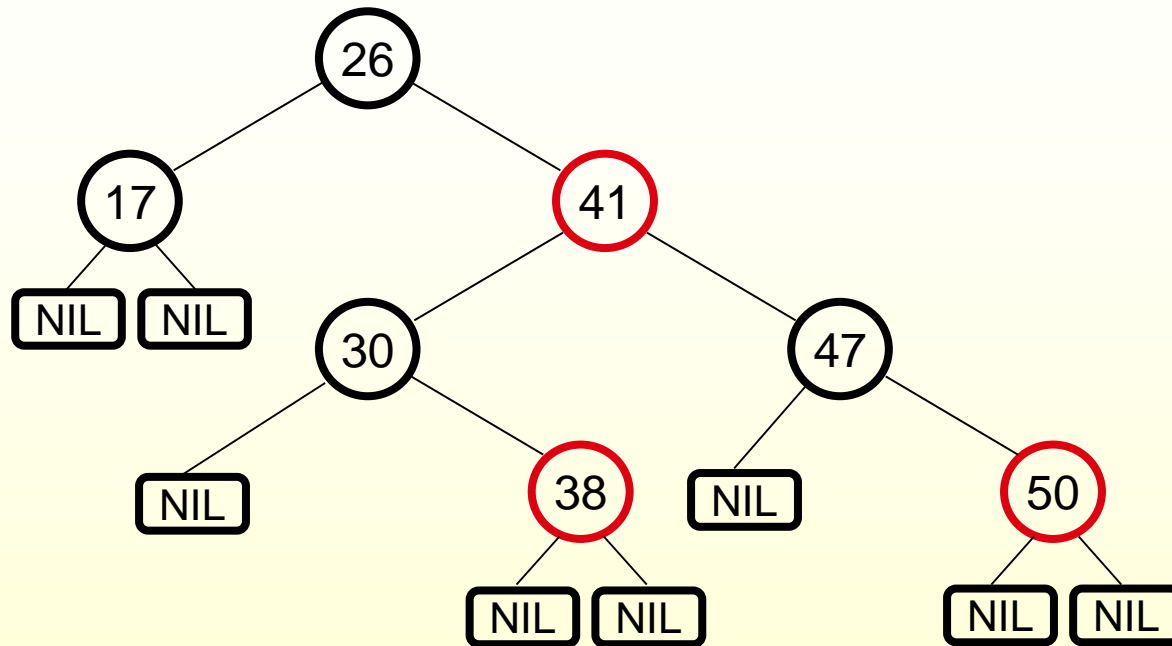
Red-Black Trees



- ◆ Balanced binary search trees that **guarantee** an $O(\lg n)$ running time
- ◆ Red-black-tree
 - ◆ Binary search tree with an additional binary attribute for its nodes: color which can be **red** or **black**
 - ◆ Constrains the way nodes can be colored on any path from the root to a leaf:

Ensures that no path is more than twice as long as any other path \Rightarrow the tree is balanced

Example: RED-BLACK-TREE



- ◆ For convenience we use a sentinel $NIL[T]$ to represent all the null nodes at the leafs
 - ◆ $NIL[T]$ has the same fields as an ordinary node
 - ◆ $Color[NIL[T]] = BLACK$
 - ◆ The other fields may be set to arbitrary values

Red-Black Trees

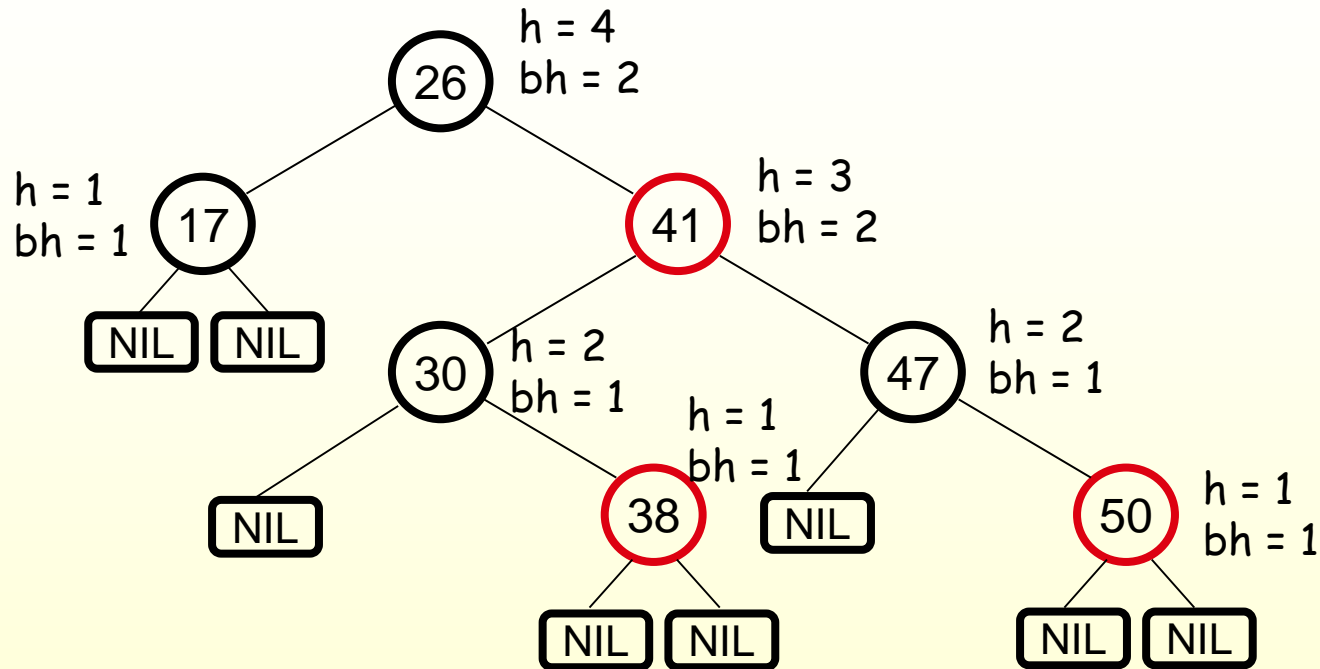
- ◆ Binary search tree + 1 extra bit per node: the attribute *color*, which is either **red** or **black**.
- ◆ All other attributes of BSTs are inherited:
 - ◆ *key*, *left*, *right*, and *p* (parent).
- ◆ All empty trees (leaves) are colored black.
 - ◆ We use a single sentinel, *NIL*, for all the leaves of red-black tree T , with $color[NIL] = \text{black}$.
 - ◆ The root's parent is also $NIL[T]$.

Red-Black-Trees Properties

(**Satisfy the binary search tree property**)

1. Every node is either **red** or **black**
 2. The root is **black**
 3. Every leaf (NIL) is **black**
 4. If a node is **red**, then both its children are **black**
 - No two consecutive red nodes on a simple path from the root to a leaf
 5. For each node, all paths from that node to descendant leaves contain the same number of **black** nodes
- local
- global

Black-Height of a Node



- ◆ **Height of a node:** the number of edges in the longest path to a leaf
- ◆ **Black-height of a node x :** $bh(x)$ is the number of black nodes (including NIL) on the path from x to a leaf, not counting x

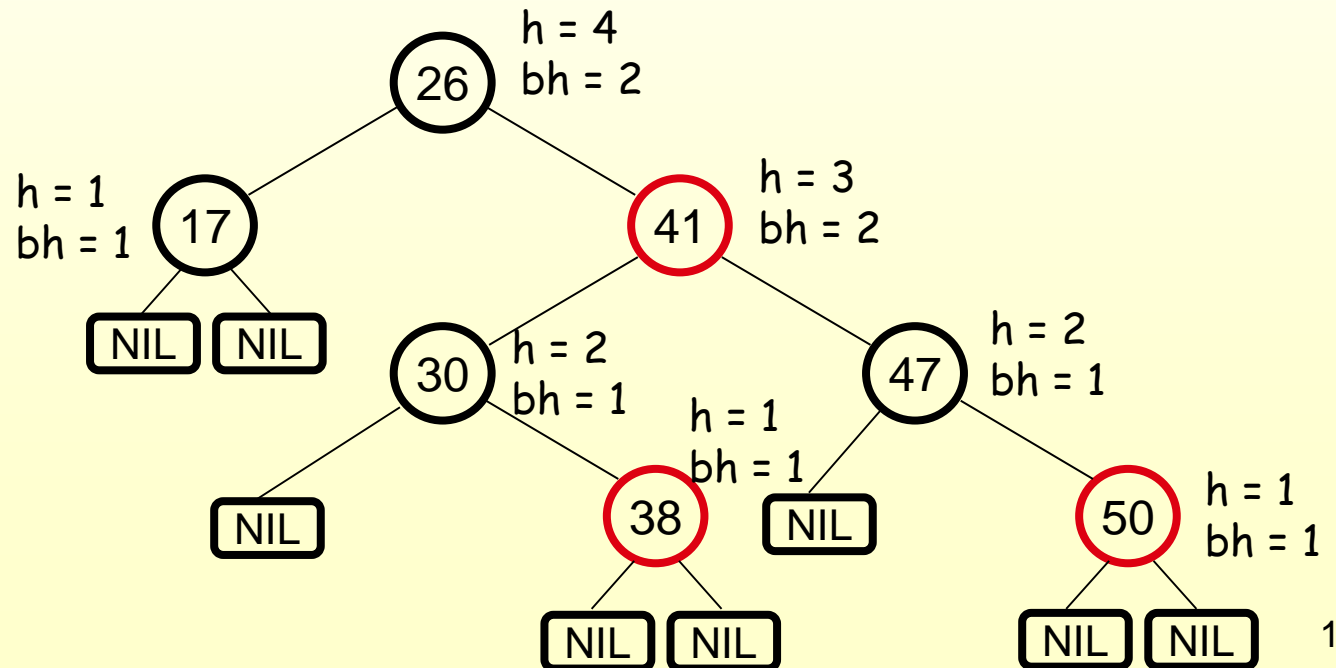
Important Property of Red-Black-Trees

A red-black tree with n internal nodes
has height at most $2\lg(n + 1)$

- ◆ Need to prove two claims first ...

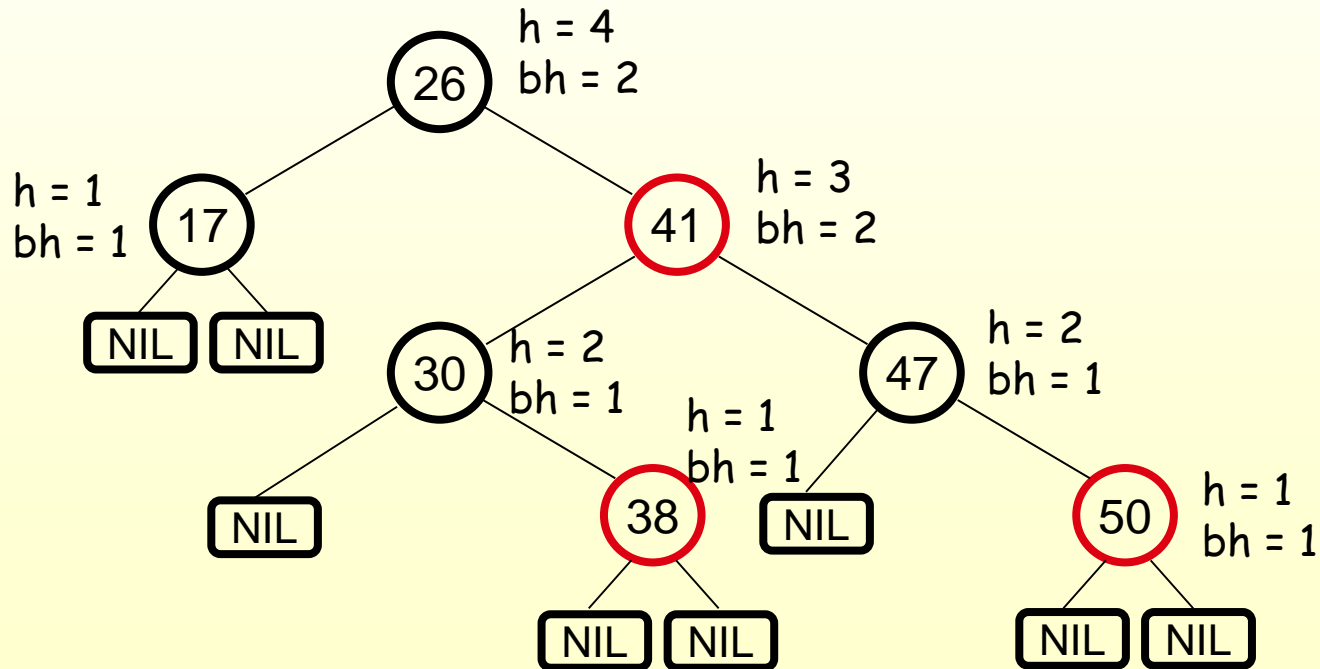
Claim 1

- Any node x with height $h(x)$ has $bh(x) \geq h(x)/2$
- Proof**
 - By property 4, at most $h/2$ **red** nodes on the path from the node to a leaf
 - Hence at least $h/2$ are **black**



Claim 2

- The subtree rooted at any node x contains **at least** $2^{bh(x)} - 1$ internal nodes



Claim 2 (Cont'd)

Proof: By induction on $h[x]$

Basis: $h[x] = 0 \Rightarrow$

x is a leaf ($NIL[T]$) \Rightarrow

$bh(x) = 0 \Rightarrow$



of internal nodes: $2^0 - 1 = 0$

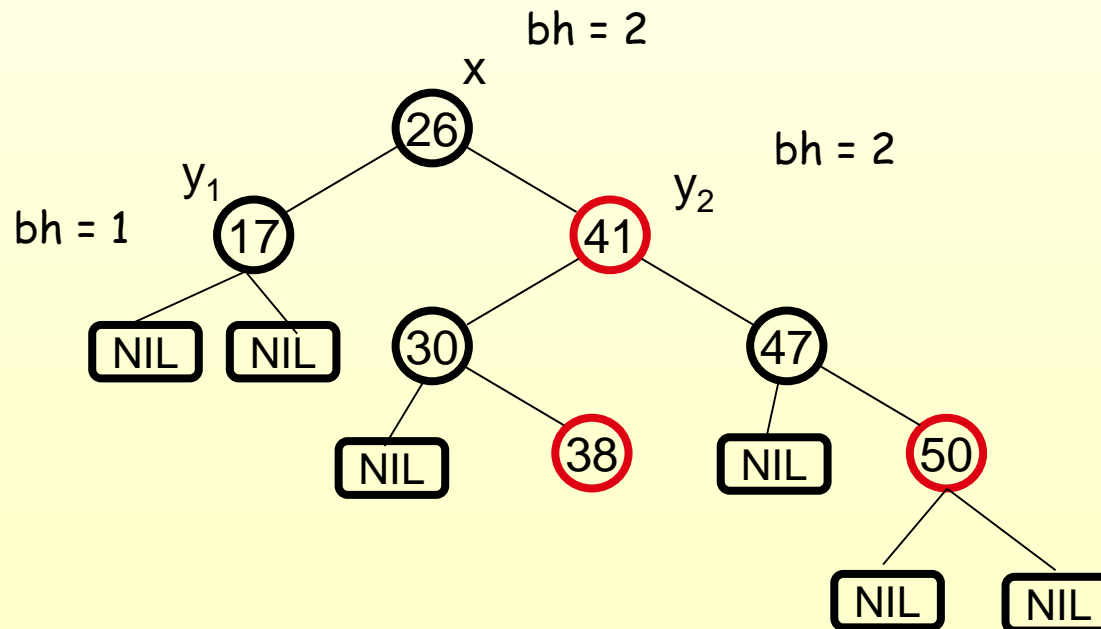
Inductive Hypothesis: assume it is true for

$h[x]=h-1$

Claim 2 (Cont'd)

Inductive step:

- ◆ Prove it for $h[x]=h$
- ◆ Let $bh(x) = b$, then any child y of x has:
 - ◆ $bh(y) = b$ (if the child is **red**), or
 - ◆ $bh(y) = b - 1$ (if the child is **black**)



Claim 2 (Cont'd)

- Using inductive hypothesis, the number of internal nodes for each child of x is at least:

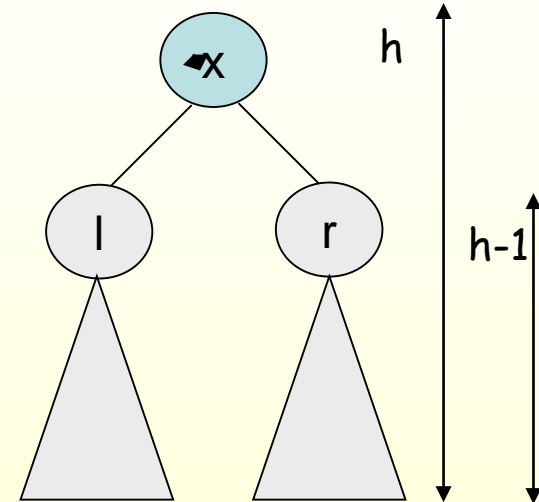
$$2^{bh(x) - 1} - 1$$

- The subtree rooted at x contains at least:

$$(2^{bh(x) - 1} - 1) + (2^{bh(x) - 1} - 1) + 1 =$$

$$2 \cdot (2^{bh(x) - 1} - 1) + 1 =$$

$$2^{bh(x)} - 1 \text{ internal nodes}$$



$$bh(l) \geq bh(x) - 1$$

$$bh(r) \geq bh(x) - 1$$

Height of Red-Black-Trees (Cont'd)

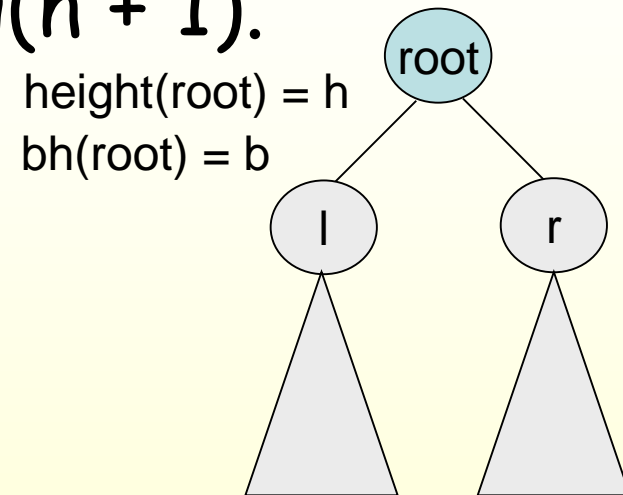
Lemma: A red-black tree with n internal nodes has height at most $2\lg(n + 1)$.

Proof:

$$n \geq 2^b - 1 \geq 2^{h/2} - 1$$

number n of internal nodes

since $b \geq h/2$



◆ Add 1 to both sides and then take logs:

$$n + 1 \geq 2^b \geq 2^{h/2}$$

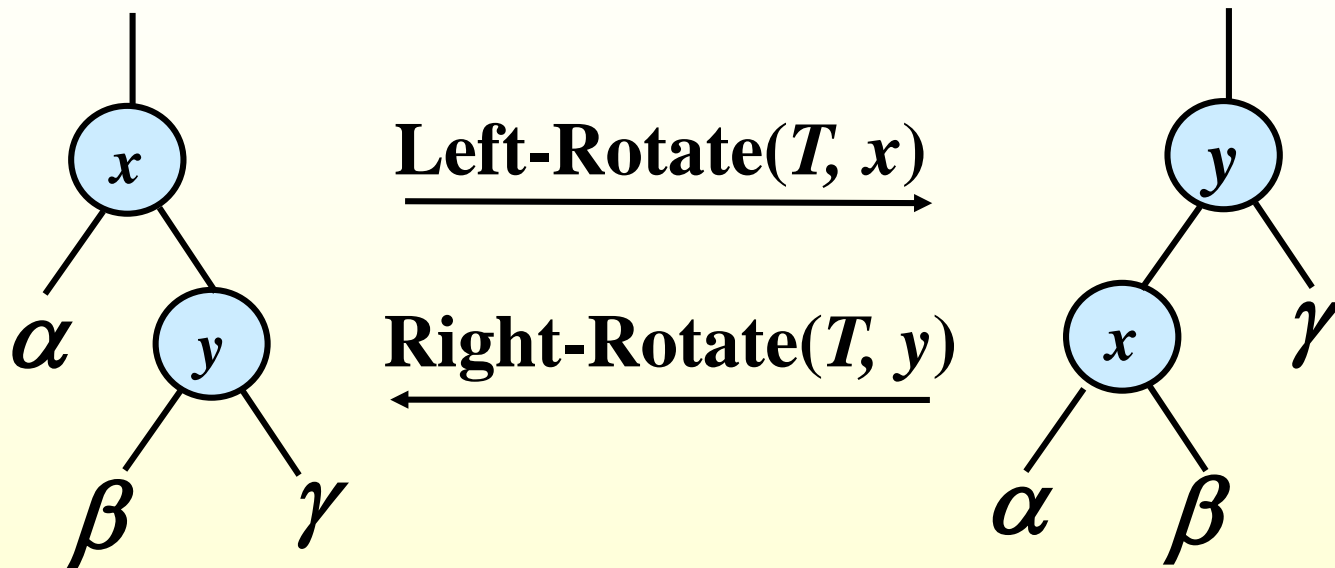
$$\lg(n + 1) \geq h/2 \Rightarrow$$

$$h \leq 2 \lg(n + 1)$$

Operations on RB Trees

- ◆ All operations can be performed in $O(\lg n)$ time.
- ◆ The query operations, which don't modify the tree, are performed in exactly the same way as they are in BSTs.
- ◆ Insertion and Deletion are not straightforward. Why?

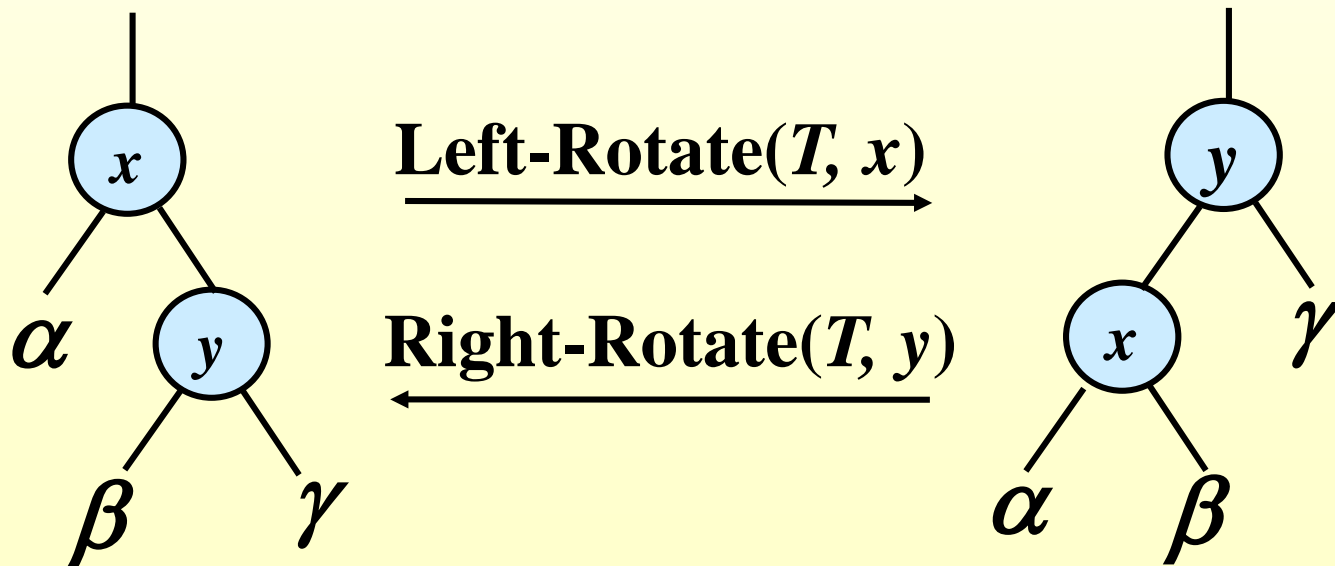
Rotations: Local Tree Rearrangements



Internal tree rebalancing operations

Rotations

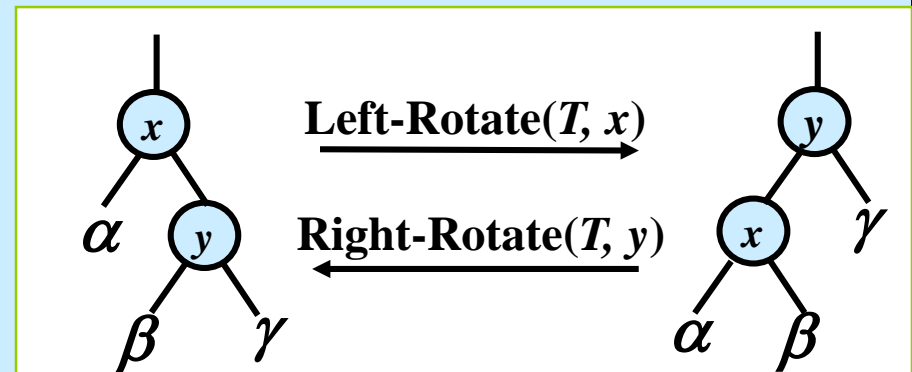
- ◆ Rotations are the basic **tree-restructuring** operations for almost all *balanced* search trees.
- ◆ Rotation takes a red-black-tree and a node,
- ◆ Changes pointers to change the local structure, and
- ◆ Does not violate the binary-search-tree property.
- ◆ Left rotation and right rotation are inverses.



Left Rotation – Pseudocode

Left-Rotate (T, x)

1. $y \leftarrow \text{right}[x]$ // Set y .
2. $\text{right}[x] \leftarrow \text{left}[y]$ // Turn y 's left subtree into x 's right subtree.
3. **if** $\text{left}[y] \neq \text{nil}[T]$
4. **then** $p[\text{left}[y]] \leftarrow x$
5. $p[y] \leftarrow p[x]$ // Link x 's parent to y .
6. **if** $p[x] = \text{nil}[T]$
7. **then** $\text{root}[T] \leftarrow y$
8. **else if** $x = \text{left}[p[x]]$
9. **then** $\text{left}[p[x]] \leftarrow y$
10. **else** $\text{right}[p[x]] \leftarrow y$
11. $\text{left}[y] \leftarrow x$ // Put x on y 's left.
12. $p[x] \leftarrow y$



Rotation

- ◆ The pseudo-code for Left-Rotate assumes that
 - ◆ $right[x] \neq nil[T]$, and
 - ◆ root's parent is $nil[T]$.
- ◆ Left Rotation on x , makes x the left child of y , and the left subtree of y into the right subtree of x .
- ◆ Pseudocode for Right-Rotate is symmetric: exchange *left* and *right* everywhere.
- ◆ **Time:** $O(1)$ for both Left-Rotate and Right-Rotate, since a constant number of pointers are modified.

Reminder: Red-Black Properties

1. Every node is either **red** or black.
2. The **root is** black.
3. Every **leaf (*NIL*) is** black.
4. If a node is **red**, then both its children are black.
5. For each node, all paths from the node to descendant leaves contain the same number of black nodes.

Insertion in RB Trees

- ◆ Insertion must preserve all red-black properties.
- ◆ Should an inserted node be colored **Red?**
Black?
- ◆ **Basic steps:**
 - ◆ Use Tree-Insert from BST (slightly modified) to insert a node x into T .
 - ◆ Procedure **RB-Insert(x)**.
 - ◆ Color the node x red.
 - ◆ Fix the modified tree by re-coloring nodes and performing rotation to preserve RB tree property.
 - ◆ Procedure **RB-Insert-Fixup**.

Insertion

RB-Insert(T, z)

1. $y \leftarrow \text{nil}[T]$
2. $x \leftarrow \text{root}[T]$
3. **while** $x \neq \text{nil}[T]$
4. **do** $y \leftarrow x$
5. **if** $\text{key}[z] < \text{key}[x]$
6. **then** $x \leftarrow \text{left}[x]$
7. **else** $x \leftarrow$
 $\text{right}[x]$
8. $p[z] \leftarrow y$
9. **if** $y = \text{nil}[T]$
10. **then** $\text{root}[T] \leftarrow z$
11. **else if** $\text{key}[z] < \text{key}[y]$
12. **then** $\text{left}[y] \leftarrow z$
13. **else** $\text{right}[y] \leftarrow z$

RB-Insert(T, z) Contd.

14. $\text{left}[z] \leftarrow \text{nil}[T]$
15. $\text{right}[z] \leftarrow \text{nil}[T]$
16. $\text{color}[z] \leftarrow \text{RED}$
17. RB-Insert-Fixup (T, z)

How does it differ from the Tree-Insert procedure of BSTs?

Which of the RB properties might be violated?

Fix the violations by calling RB-Insert-Fixup.

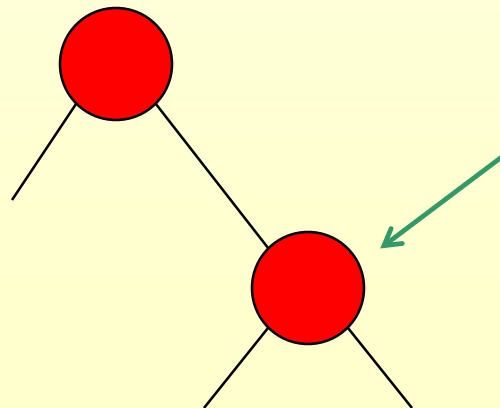
Red-Black-Trees Properties

(**Satisfy the binary search tree property**)

1. Every node is either **red** or **black**
 2. The root is **black**
 3. Every leaf (NIL) is **black**
 4. If a node is **red**, then both its children are **black**
 - No two consecutive red nodes on a simple path from the root to a leaf
 5. For each node, all paths from that node to descendant leaves contain the same number of **black** nodes
- local
- global

Insertion – Fixup

- ◆ Problem: we may have one pair of consecutive reds where we did the insertion.
- ◆ Solution: rotate it up the tree and away...
Three cases have to be handled...



Insertion – Fixup

RB-Insert-Fixup (T, z)

1. **while** $color[p[z]] = \text{RED}$
2. **do if** $p[z] = left[p[p[z]]]$
3. **then** $y \leftarrow right[p[p[z]]]$
4. **if** $color[y] = \text{RED}$
5. **then** $color[p[z]] \leftarrow \text{BLACK}$ // Case 1
6. $color[y] \leftarrow \text{BLACK}$ // Case 1
7. $color[p[p[z]]] \leftarrow \text{RED}$ // Case 1
8. $z \leftarrow p[p[z]]$ // Case 1

Insertion – Fixup

RB-Insert-Fixup(T, z) (Contd.)

9. **else if** $z = \text{right}[p[z]]$ // $\text{color}[y] \neq \text{RED}$
10. **then** $z \leftarrow p[z]$ // Case 2
11. LEFT-ROTATE(T, z) // Case 2
12. $\text{color}[p[z]] \leftarrow \text{BLACK}$ // Case 3
13. $\text{color}[p[p[z]]] \leftarrow \text{RED}$ // Case 3
14. RIGHT-ROTATE($T, p[p[z]]$) // Case 3
15. **else** (if $p[z] = \text{right}[p[p[z]]]$)(same as **10-14**
16. with “right” and “left” exchanged)
17. $\text{color}[\text{root}[T]] \leftarrow \text{BLACK}$

Correctness

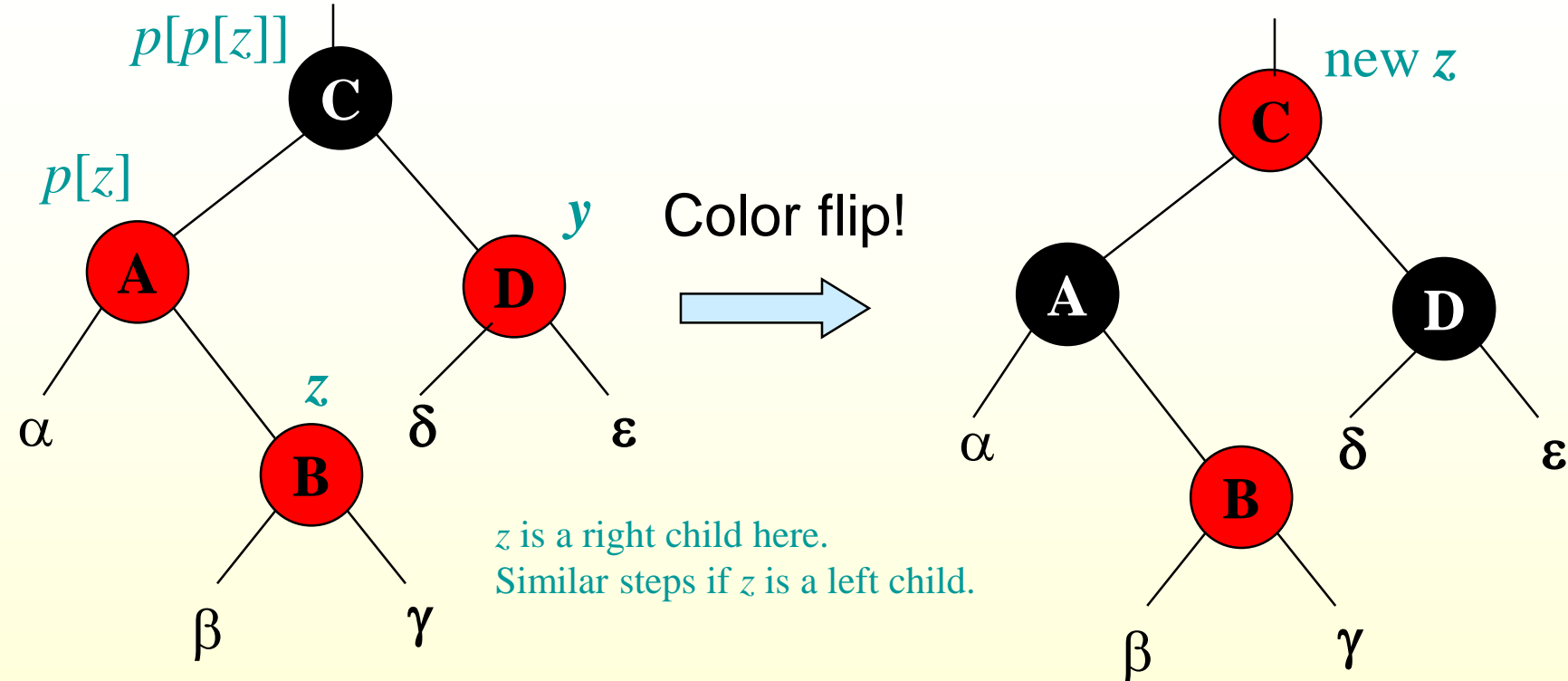
Loop invariant:

- ◆ At the start of each iteration of the **while** loop,
 - ◆ **z is red.**
 - ◆ If $p[z]$ is the root, then $p[z]$ is black.
 - ◆ There is at most one red-black violation:
 - ◆ **Property 2:** z is a red root, or
 - ◆ **Property 4:** z and $p[z]$ are both red.

Correctness – Contd.

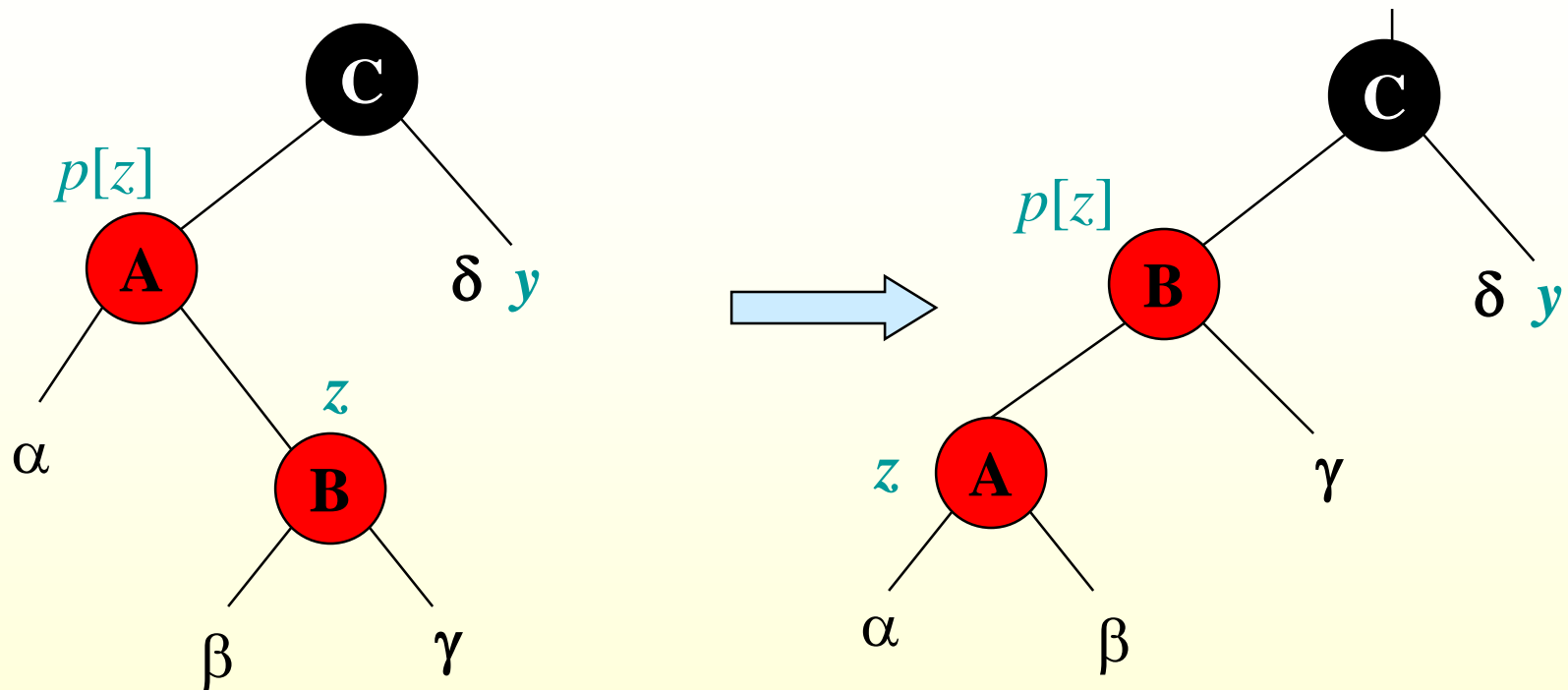
- ◆ **Initialization:** \checkmark
- ◆ **Termination:** The loop terminates only if $p[z]$ is black. Hence, property 4 is OK.
The last line ensures property 2 always holds.
- ◆ **Maintenance:** We drop out when z is the root (since then $p[z]$ is the sentinel $nil[T]$, which is black). When we start the loop body, the only violation is of property 4.
 - ◆ There are 6 cases, 3 of which are symmetric to the other 3. We consider cases in which $p[z]$ is a left child.
 - ◆ Let y be z 's uncle ($p[z]$'s sibling).

Case 1 – Uncle y is Red



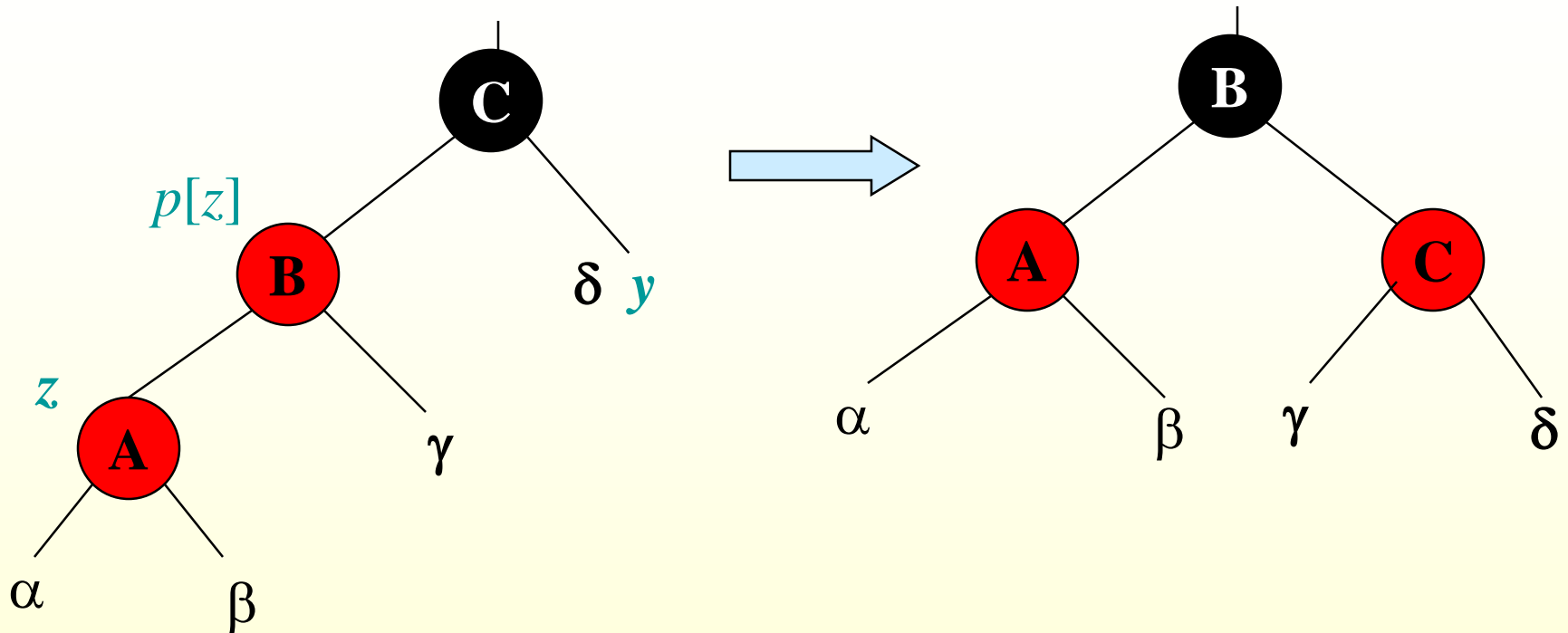
- $p[p[z]]$ (z 's grandparent) must be black, since z and $p[z]$ are both red and there are no other violations of property 4.
- Make $p[z]$ and y black \Rightarrow now z and $p[z]$ are not both red. But property 5 might now be violated.
- Make $p[p[z]]$ red \Rightarrow restores property 5.
- The next iteration has $p[p[z]]$ as the new z (i.e., z moves up 2 levels).

Case 2 – y is Black, z is a Right Child



- ◆ Left rotate around $p[z]$, $p[z]$ and z switch roles \Rightarrow now z is a left child, and both z and $p[z]$ are red.
- ◆ Takes us immediately to case 3.

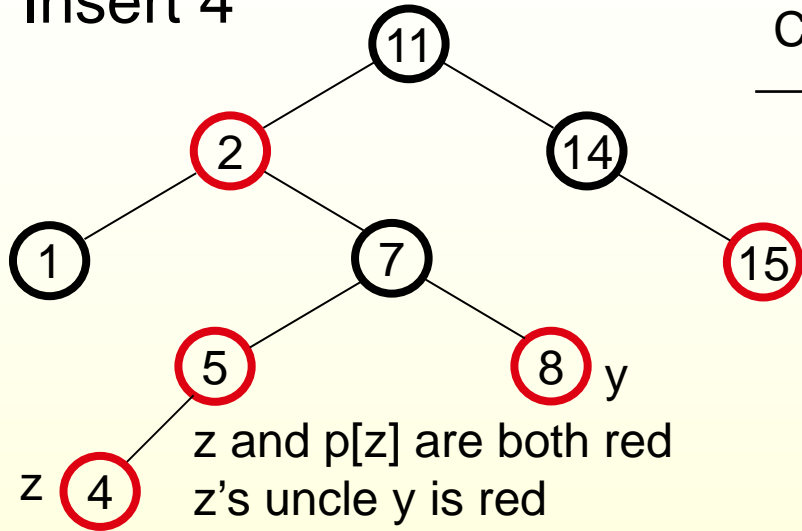
Case 3 – y is Black, z is a Left Child



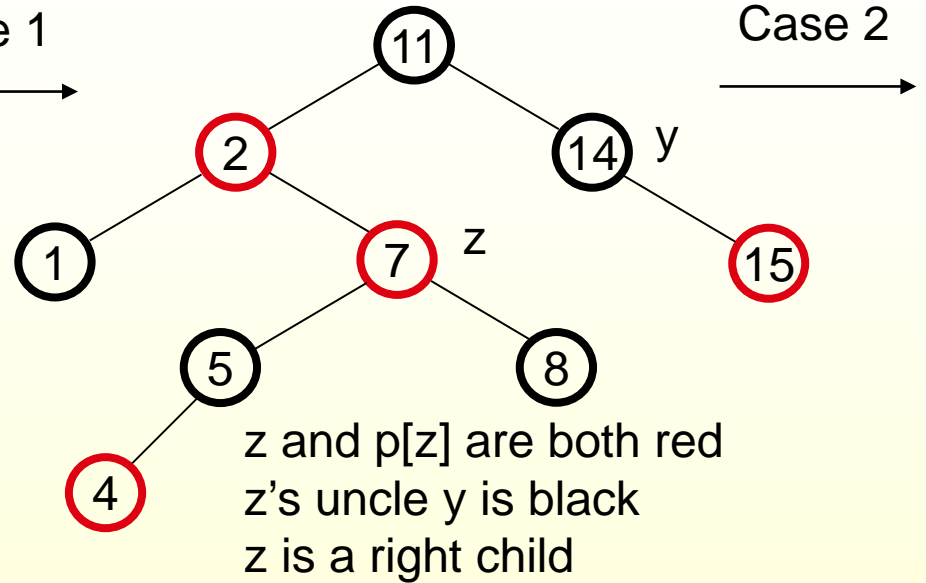
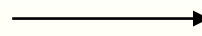
- ◆ Make $p[z]$ black and $p[p[z]]$ red.
- ◆ Then right rotate on $p[p[z]]$. Ensures property 4 is maintained.
- ◆ No longer have 2 reds in a row.
- ◆ $p[z]$ is now black \Rightarrow no more iterations.

Example Insertion

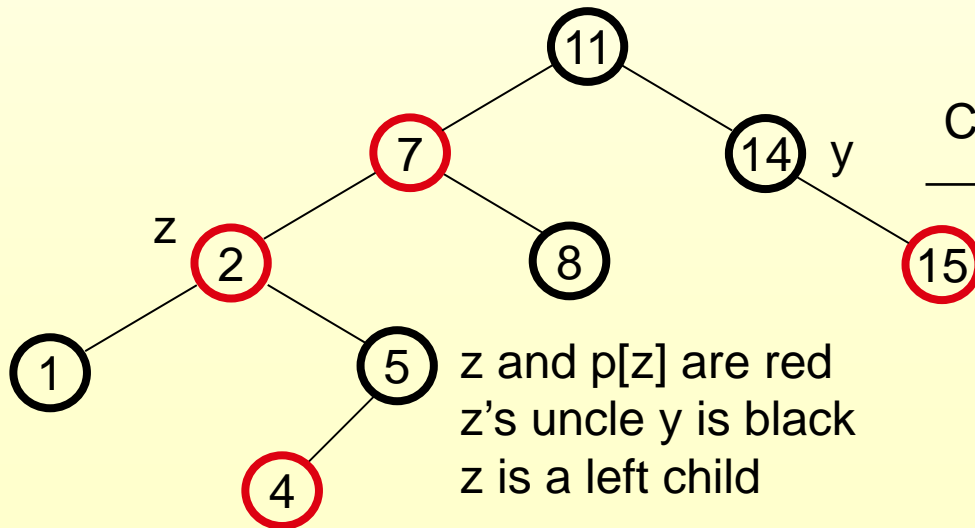
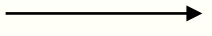
Insert 4



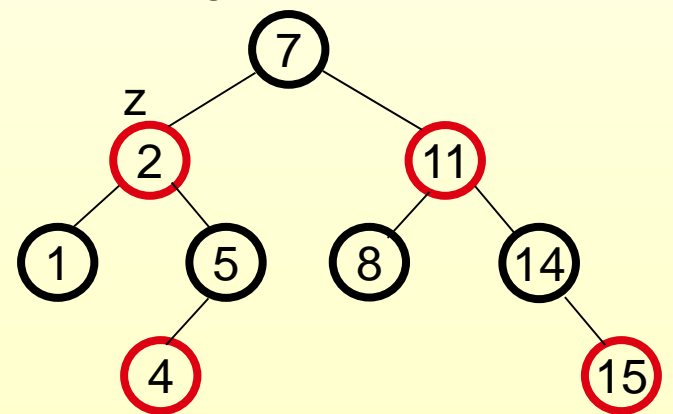
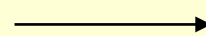
Case 1



Case 2



Case 3



Algorithm Analysis

- ◆ $O(\lg n)$ time to get through RB-Insert up to the call of RB-Insert-Fixup.
- ◆ Within **RB-Insert-Fixup**:
 - ◆ Each iteration takes $O(1)$ time.
 - ◆ Each iteration but the last **moves z up 2 levels**.
 - ◆ $O(\lg n)$ levels $\Rightarrow O(\lg n)$ time.
 - ◆ Thus, insertion in a red-black tree takes $O(\lg n)$ time.
 - ◆ Note: **there are at most 2 rotations overall**.

Animations

- ◆ Animation:
- ◆ <https://www.youtube.com/watch?v=rcDF8lqTnyI>

- ◆ Live demo:
- ◆ <http://www.cs.usfca.edu/~galles/visualization/RedBlack.html>

- ◆ Video explanations
- ◆ http://www.csanimated.com/animation.php?t=Red-black_tree

Deletion

- ◆ Deletion, like insertion, should preserve all the RB properties.
- ◆ The properties that may be violated depends on the color of the deleted node.
 - ◆ Red – OK. Why?
 - ◆ Black?
- ◆ Steps:
 - ◆ Do regular BST deletion.
 - ◆ Fix any violations of RB properties that may result.

Deletion

RB-Delete(T, z)

1. **if** $left[z] = nil[T]$ or $right[z] = nil[T]$
2. **then** $y \leftarrow z$
3. **else** $y \leftarrow \text{TREE-SUCCESSOR}(z)$
4. **if** $left[y] = nil[T]$
5. **then** $x \leftarrow left[y]$
6. **else** $x \leftarrow right[y]$
7. $p[x] \leftarrow p[y]$ // Do this, even if x is $nil[T]$

y is the node we really delete

x is the node that moves into y 's original position

Deletion

RB-Delete (T, z) (Contd.)

8. **if** $p[y] = nil[T]$
9. **then** $root[T] \leftarrow x$
10. **else if** $y = left[p[y]]$
11. **then** $left[p[y]] \leftarrow x$
12. **else** $right[p[y]] \leftarrow x$
13. **if** $y = z$
14. **then** $key[z] \leftarrow key[y]$
15. copy y 's satellite data into z
16. **if** $color[y] = BLACK$
17. **then** RB-Delete-Fixup(T, x)
18. **return** y

The node passed to the fixup routine is the lone child of the spliced up node, or the sentinel.

Red-Black-Trees Properties

(**Satisfy the binary search tree property**)

1. Every node is either **red** or **black**
 2. The root is **black**
 3. Every leaf (NIL) is **black**
 4. If a node is **red**, then both its children are **black**
 - No two consecutive red nodes on a simple path from the root to a leaf
 5. For each node, all paths from that node to descendant leaves contain the same number of **black** nodes
- local
- global

RB Properties Violation

- ◆ If y is black, we could have violations of red-black properties:
 - ◆ Prop. 1. OK.
 - ◆ Prop. 2. If y is the root and x is red, then the root has become red.
 - ◆ Prop. 3. OK.
 - ◆ Prop. 4. Violation if $p[y]$ and x are both red.
 - ◆ Prop. 5. Any path containing y now has 1 fewer black node.

RB Properties Violation

- ◆ Prop. 5. Any path containing y now has 1 fewer black node.
 - ◆ Correct by giving x an “extra black.”
 - ◆ Add 1 to count of black nodes on paths containing x .
 - ◆ Now property 5 is OK, but property 1 is not.
 - ◆ x is either **doubly black** (if $color[x] = \text{BLACK}$) or **red & black** (if $color[x] = \text{RED}$).
 - ◆ The attribute $color[x]$ is still either RED or BLACK. No new values for $color$ attribute.
 - ◆ In other words, the extra blackness on a node is by virtue of x pointing to the node.
- ◆ Remove the violations by calling RB-Delete-Fixup.

Deletion – Fixup

RB-Delete-Fixup(T, x)

1. **while** $x \neq \text{root}[T]$ and $\text{color}[x] = \text{BLACK}$
2. **do if** $x = \text{left}[p[x]]$
3. **then** $w \leftarrow \text{right}[p[x]]$
4. **if** $\text{color}[w] = \text{RED}$
5. **then** $\text{color}[w] \leftarrow \text{BLACK}$ // Case 1
6. $\text{color}[p[x]] \leftarrow \text{RED}$ // Case 1
7. LEFT-ROTATE($T, p[x]$) // Case 1
8. $w \leftarrow \text{right}[p[x]]$ // Case 1

RB-Delete-Fixup(T, x) (Contd.)

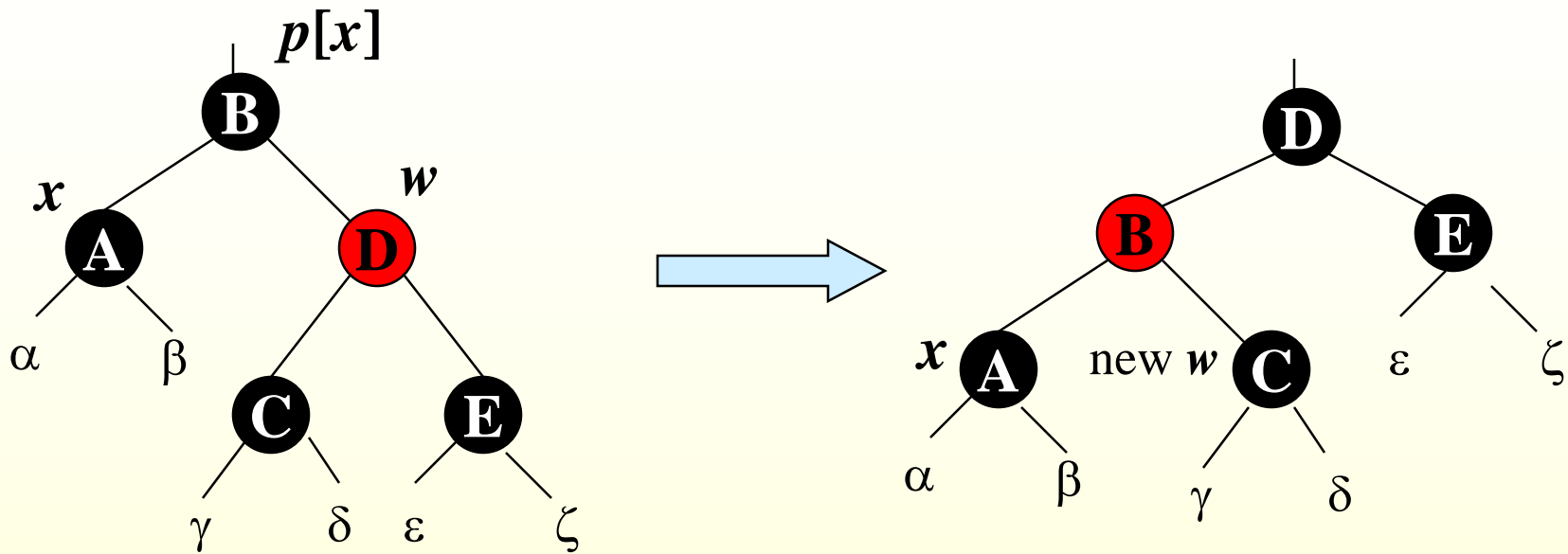
/ x is still left[p[x]] */*

9. **if** $color[left[w]] = \text{BLACK}$ and $color[right[w]] = \text{BLACK}$
10. **then** $color[w] \leftarrow \text{RED}$ // Case 2
11. $x \leftarrow p[x]$ // Case 2
12. **else if** $color[right[w]] = \text{BLACK}$
13. **then** $color[left[w]] \leftarrow \text{BLACK}$ // Case 3
14. $color[w] \leftarrow \text{RED}$ // Case 3
15. RIGHT-ROTATE(T, w) // Case 3
16. $w \leftarrow right[p[x]]$ // Case 3
17. $color[w] \leftarrow color[p[x]]$ // Case 4
18. $color[p[x]] \leftarrow \text{BLACK}$ // Case 4
19. $color[right[w]] \leftarrow \text{BLACK}$ // Case 4
20. LEFT-ROTATE($T, p[x]$) // Case 4
21. $x \leftarrow root[T]$ // Case 4
22. **else** (same as **then** clause with “right” and “left”
 exchanged)
23. $color[x] \leftarrow \text{BLACK}$

Deletion – Fixup

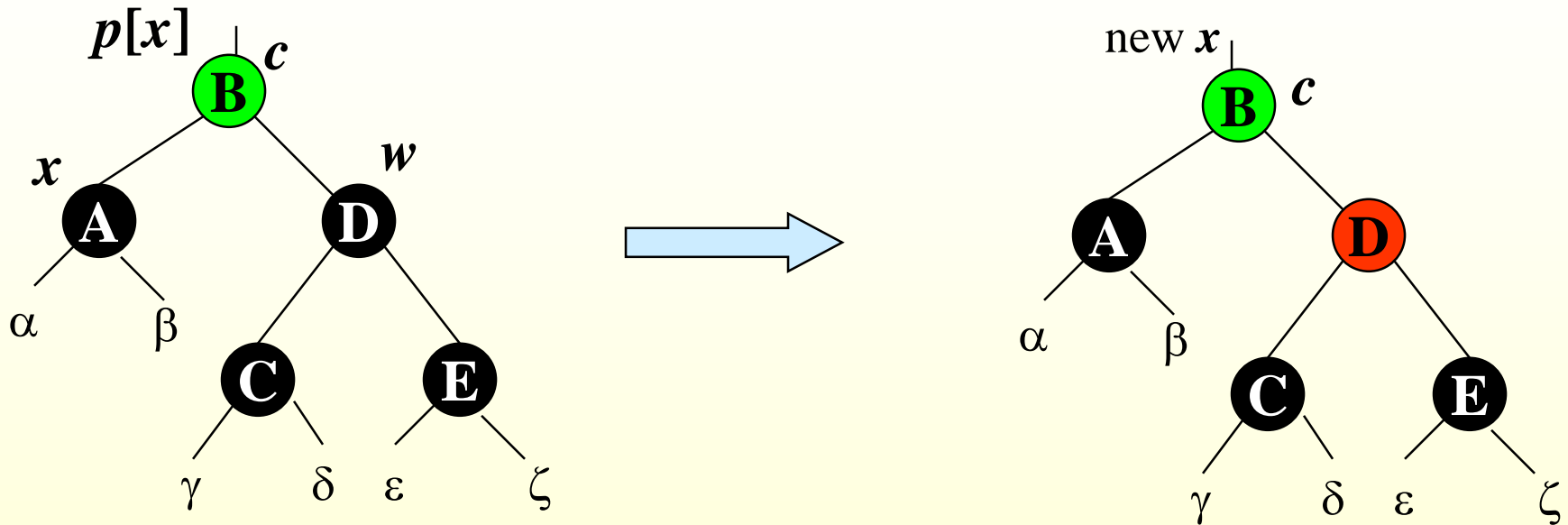
- ◆ **Idea:** Move the extra black up the tree until x points to a red & black node \Rightarrow turn it into a black node,
- ◆ x points to the root \Rightarrow just remove the extra black, or
- ◆ We can do certain rotations and re-colorings to finish.
- ◆ Within the **while** loop:
 - ◆ x always points to a non-root doubly black node.
 - ◆ w is x 's sibling.
 - ◆ w cannot be $nil[T]$, since that would violate property 5 at $p[x]$.
- ◆ 8 cases in all, 4 of which are symmetric to the other.

Case 1 – w is Red



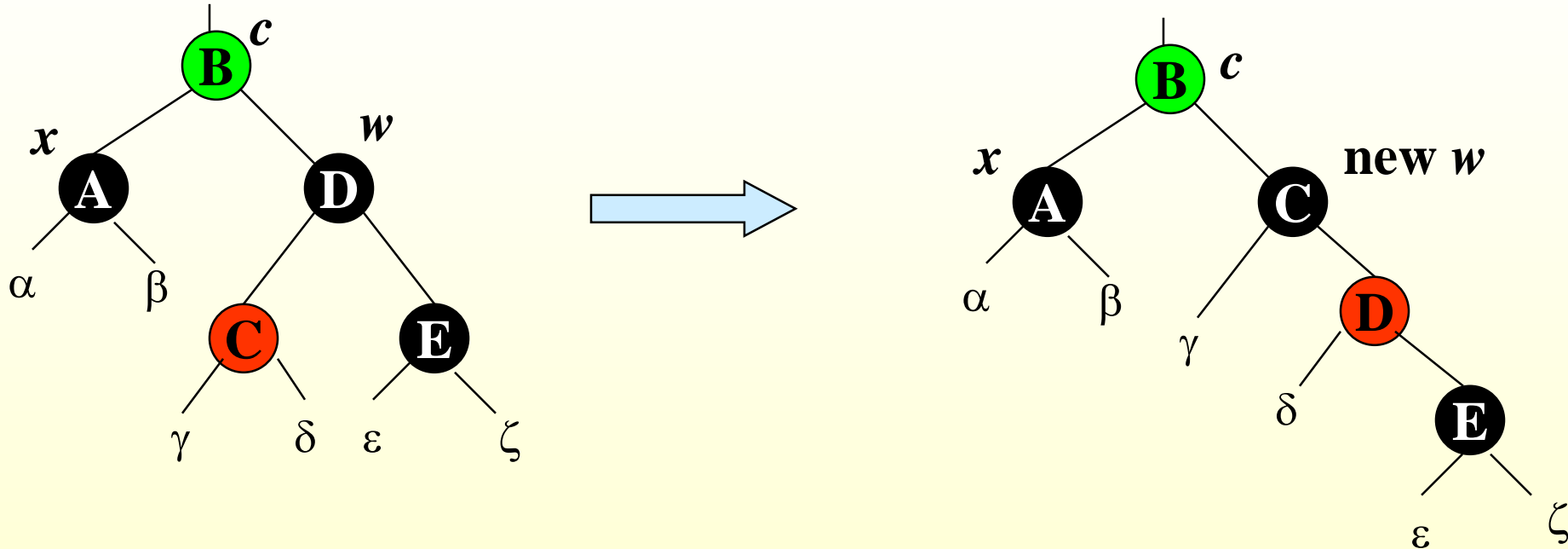
- ◆ w must have black children.
- ◆ Make w black and $p[x]$ red (because w is red $p[x]$ couldn't have been red).
- ◆ Then left rotate on $p[x]$.
- ◆ New sibling of x was a child of w before rotation \Rightarrow must be black.
- ◆ Go immediately to case 2, 3, or 4.

Case 2 – w is Black, Both w 's Children are Black



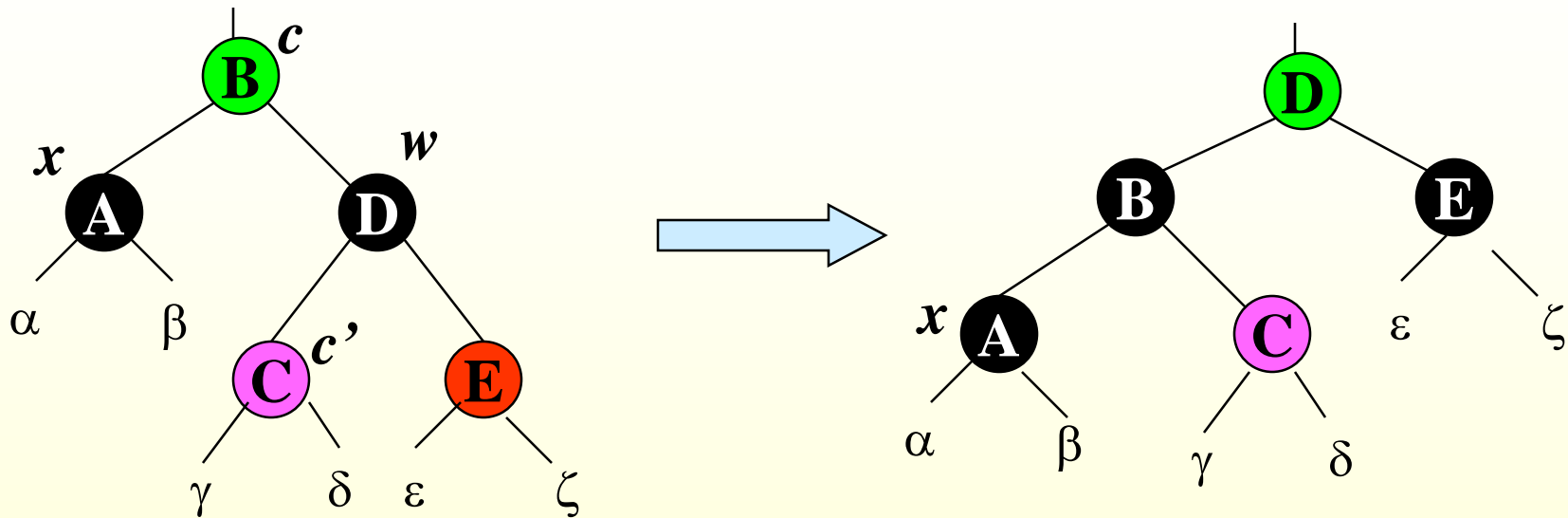
- ◆ Take 1 black off x (\Rightarrow singly black) and off w (\Rightarrow red).
- ◆ Move that black to $p[x]$.
- ◆ Do the next iteration with $p[x]$ as the new x .
- ◆ If entered this case from case 1, then $p[x]$ was red \Rightarrow new x is red & black \Rightarrow color attribute of new x is RED \Rightarrow loop terminates. Then new x is made black in the last line.

Case 3 – w is Black, w 's Left Child is Red, w 's Right Child is Black



- ◆ Make w red and w 's left child black.
- ◆ Then right rotate on w .
- ◆ New sibling w of x is black with a red right child \Rightarrow case 4.

Case 4 – w is Black, w 's Right Child is Red



- ◆ Make w be $p[x]$'s color (c).
- ◆ Make $p[x]$ black and w 's right child black.
- ◆ Then left rotate on $p[x]$.
- ◆ Remove the extra black on x ($\Rightarrow x$ is now singly black) without violating any red-black properties.
- ◆ All done. Setting x to root causes the loop to terminate.

Analysis

- ◆ $O(\lg n)$ time to get through RB-Delete up to the call of RB-Delete-Fixup.
- ◆ Within RB-Delete-Fixup:
 - ◆ Case 2 is the only case in which more iterations occur.
 - ◆ x moves up 1 level.
 - ◆ Hence, $O(\lg n)$ iterations.
 - ◆ Each of cases 1, 3, and 4 has 1 rotation $\Rightarrow \leq 3$ rotations in all.
 - ◆ Hence, $O(\lg n)$ time.

Animations

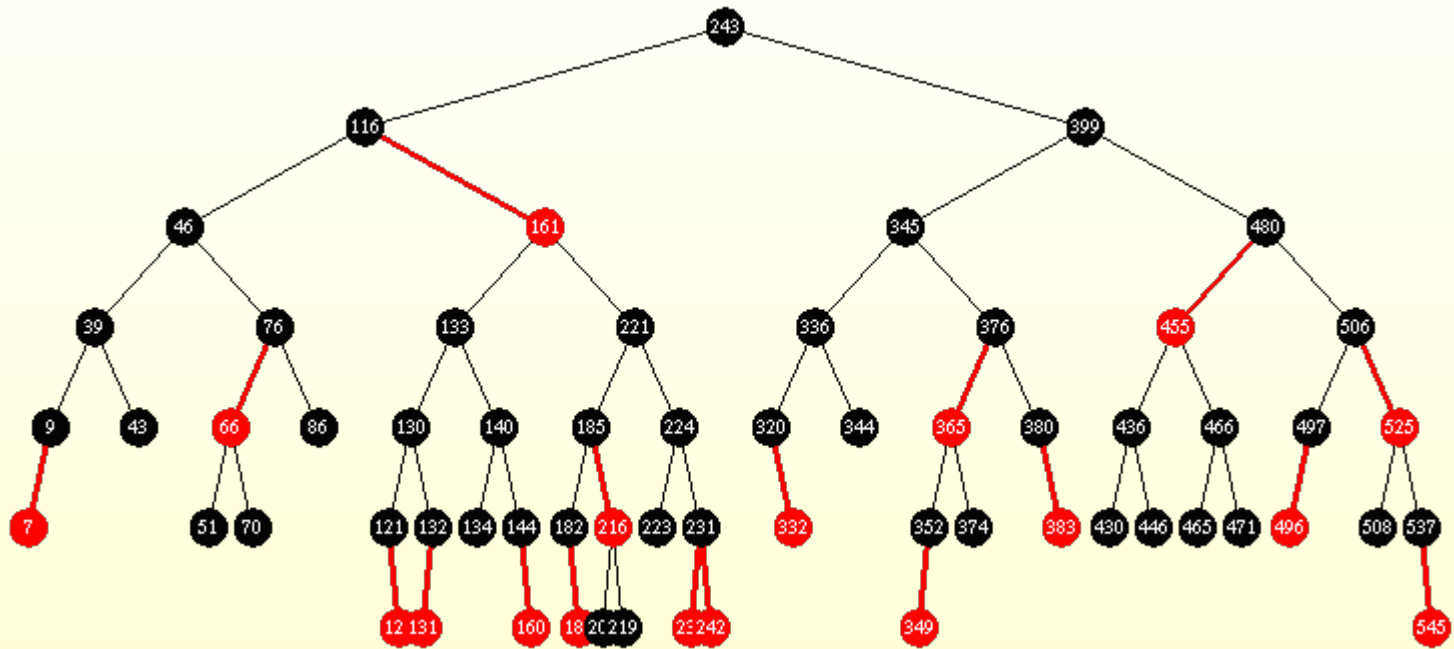
- ◆ Animation:
- ◆ <https://www.youtube.com/watch?v=rcDF8lqTnyI>

- ◆ Live demo:
- ◆ <http://www.cs.usfca.edu/~galles/visualization/RedBlack.html>

- ◆ Video explanations
- ◆ http://www.csanimated.com/animation.php?t=Red-black_tree

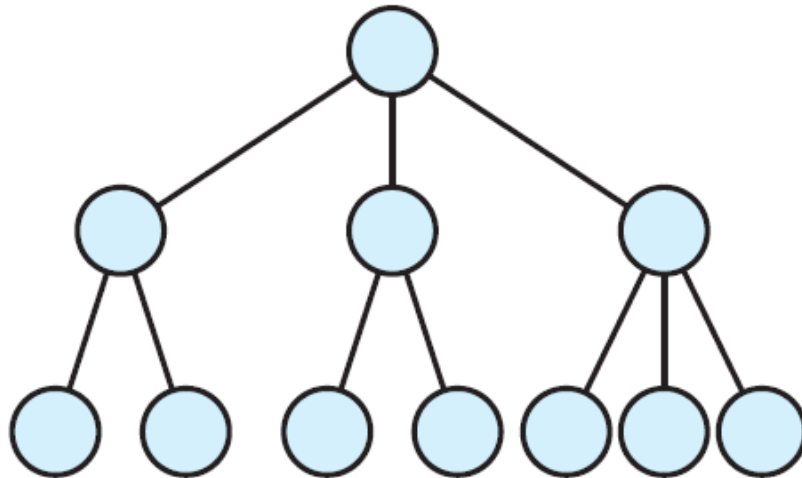
Hysteresis : or the Value of Laziness

- ◆ The red nodes give us some slack – we don't have to keep the tree perfectly balanced.
- ◆ The colors make the analysis and code much easier than some other types of balanced trees.
- ◆ Still, these aren't free – balancing costs some time on insertion and deletion.



2-3 Trees

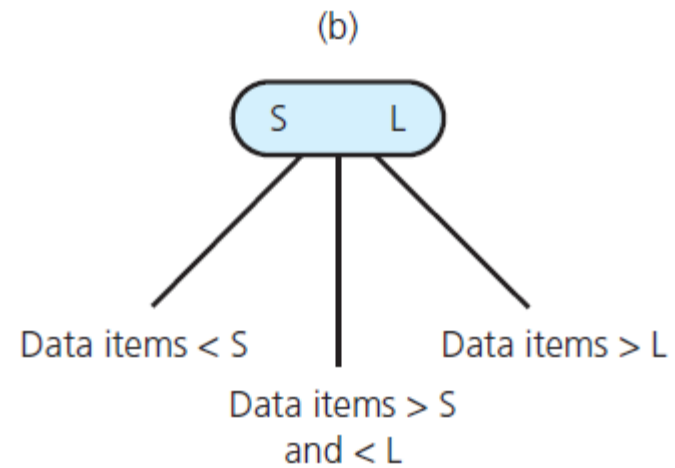
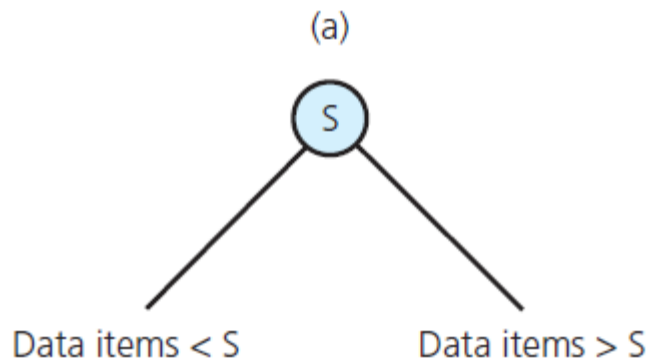
- A 2-3 tree is not a binary tree
- A 2-3 tree is always fully balanced, so height is $O(\lg n)$



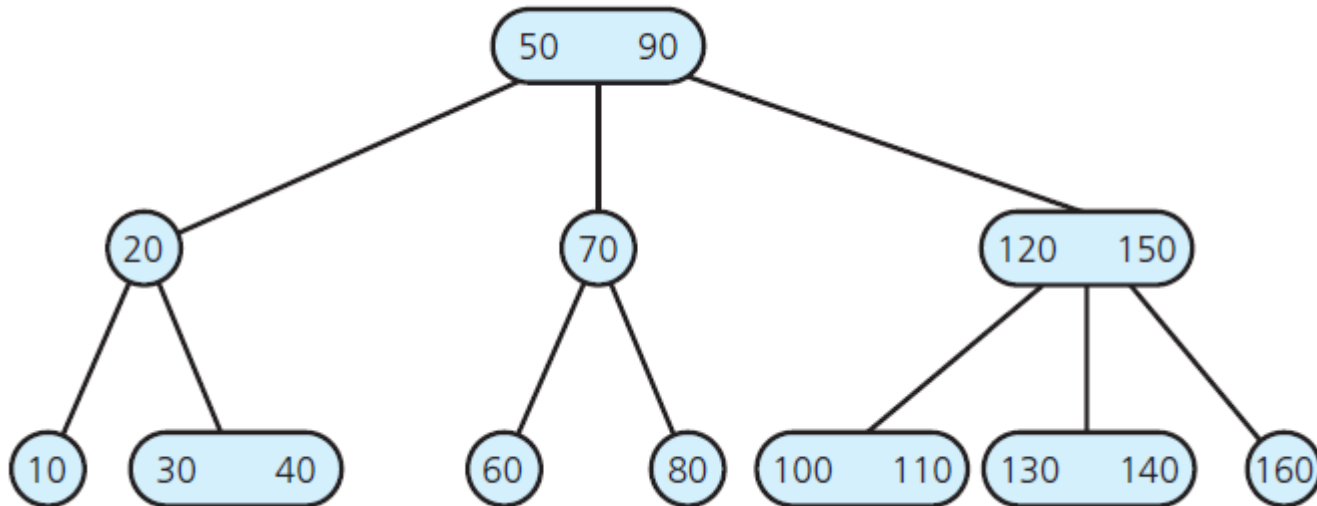
2-3 Trees

- ◆ Placing data items in nodes of a 2-3 tree
 - ◆ A 2-node (has two children) must contain single data item greater than left child's item(s) and less than right child's item(s)
 - ◆ A 3-node (has three children) must contain two data items, S and L , such that
 - ◆ S is greater than left child's item(s) and less than middle child's item(s);
 - ◆ L is greater than middle child's item(s) and less than right child's item(s).
 - ◆ Leaf may contain either one or two data items.

2-3 Trees



2-3 Tree Example



Traversing a 2-3 Tree

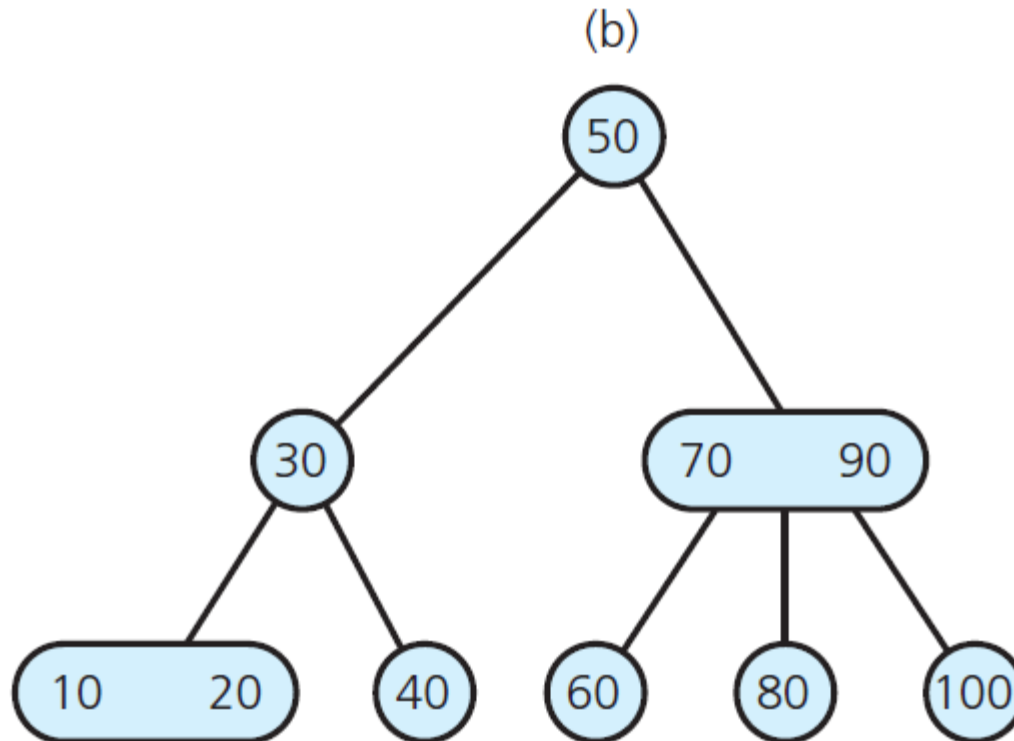
- ◆ Traverse 2-3 tree in sorted order by performing analogue of inorder traversal on binary tree:

```
// Traverses a nonempty 2-3 tree in sorted order.
inorder(23Tree: TwoThreeTree): void

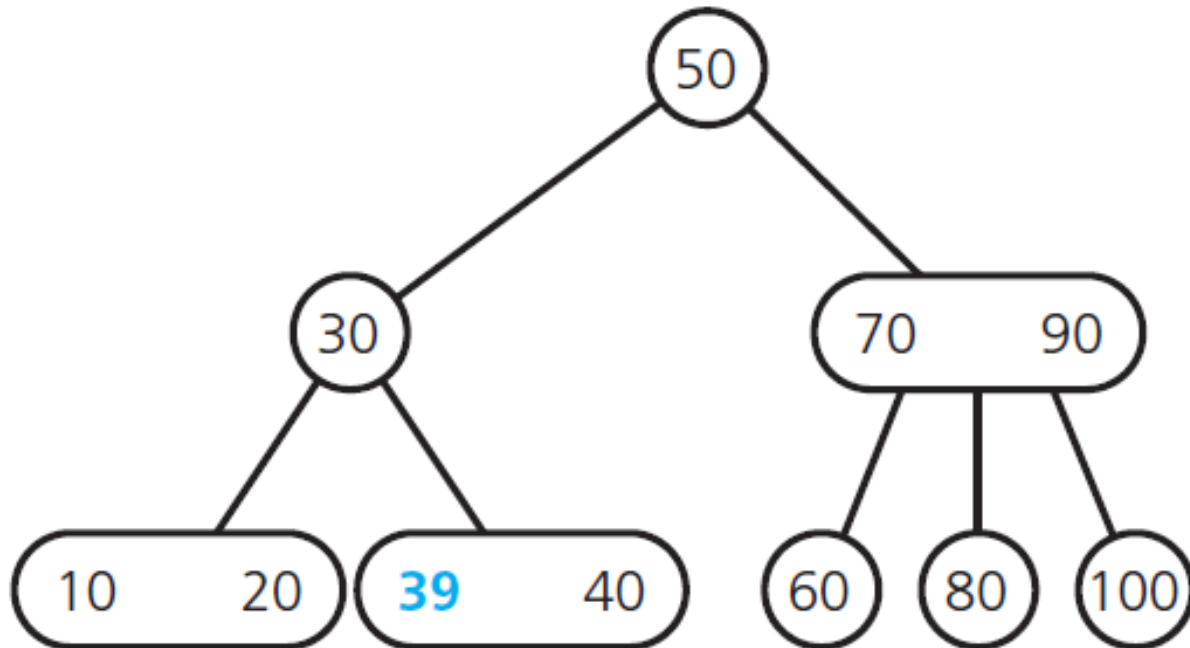
    if (23Tree's root node r is a leaf)
        Visit the data item(s)
    else if (r has two data items)
    {
        inorder(left subtree of 23Tree's root)
        Visit the first data item
        inorder(middle subtree of 23Tree's root)
        Visit the second data item
        inorder(right subtree of 23Tree's root)
    }
    else // r has one data item
    {
        inorder(left subtree of 23Tree's root)
        Visit the data item
        inorder(right subtree of 23Tree's root)
    }
}
```

Searching a 2-3 Tree

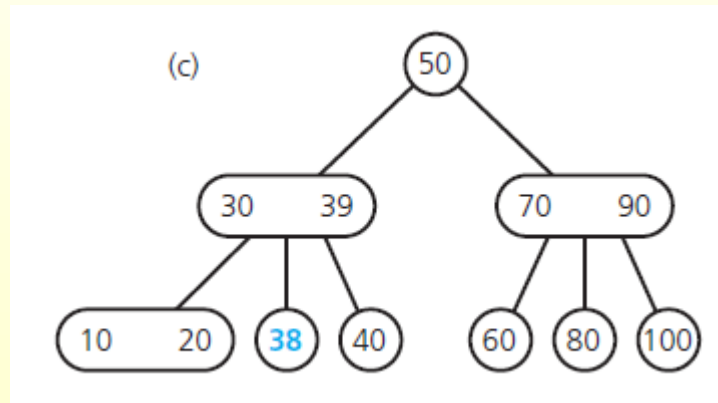
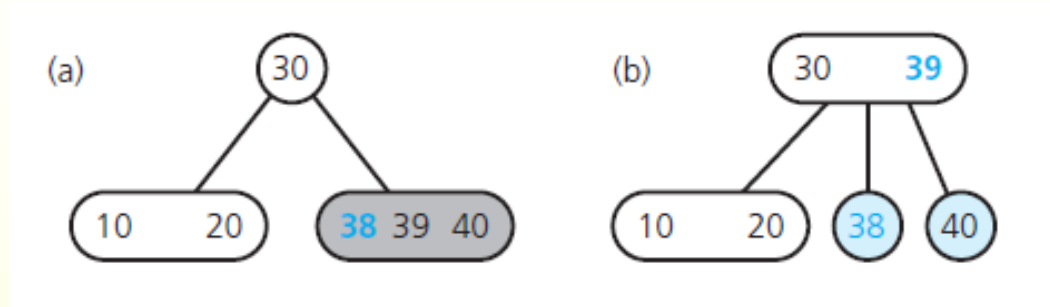
- Retrieval operation for 2-3 tree similar to retrieval operation for binary search tree



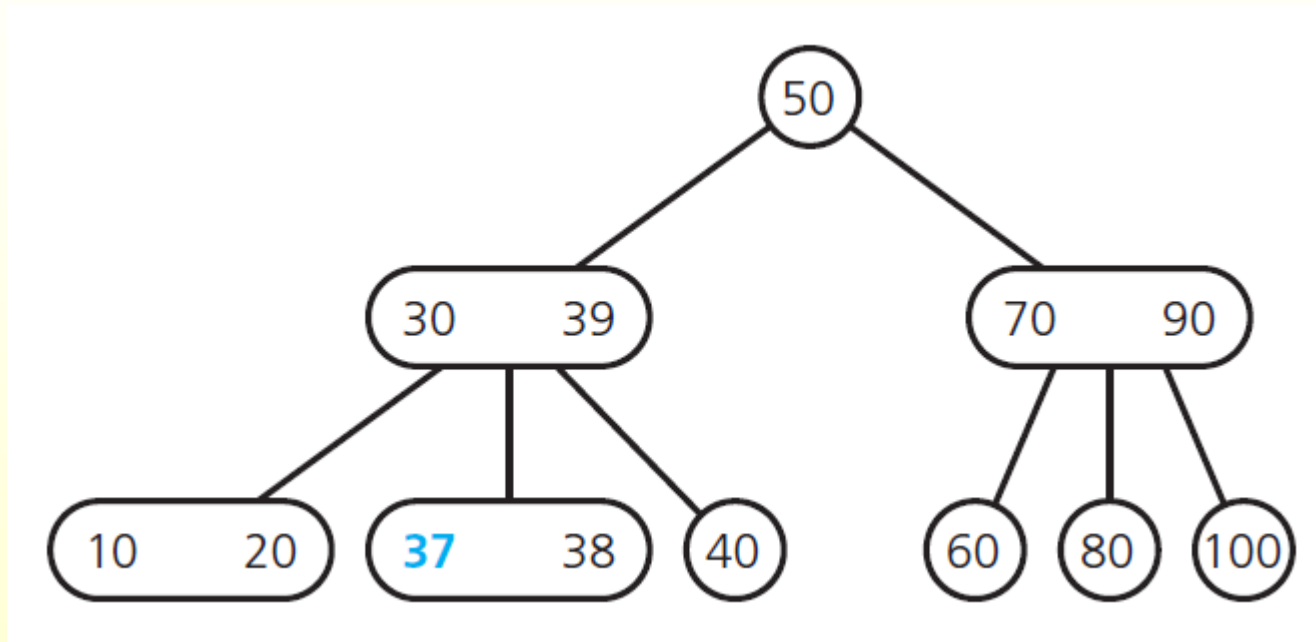
Inserting Data into a 2-3 Tree



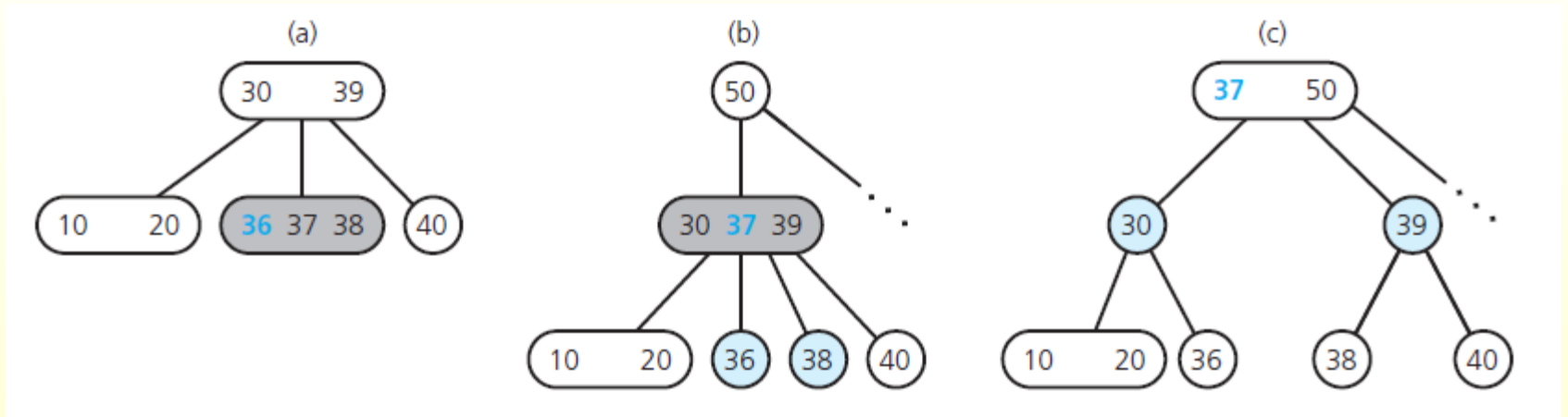
Inserting Data into a 2-3 Tree



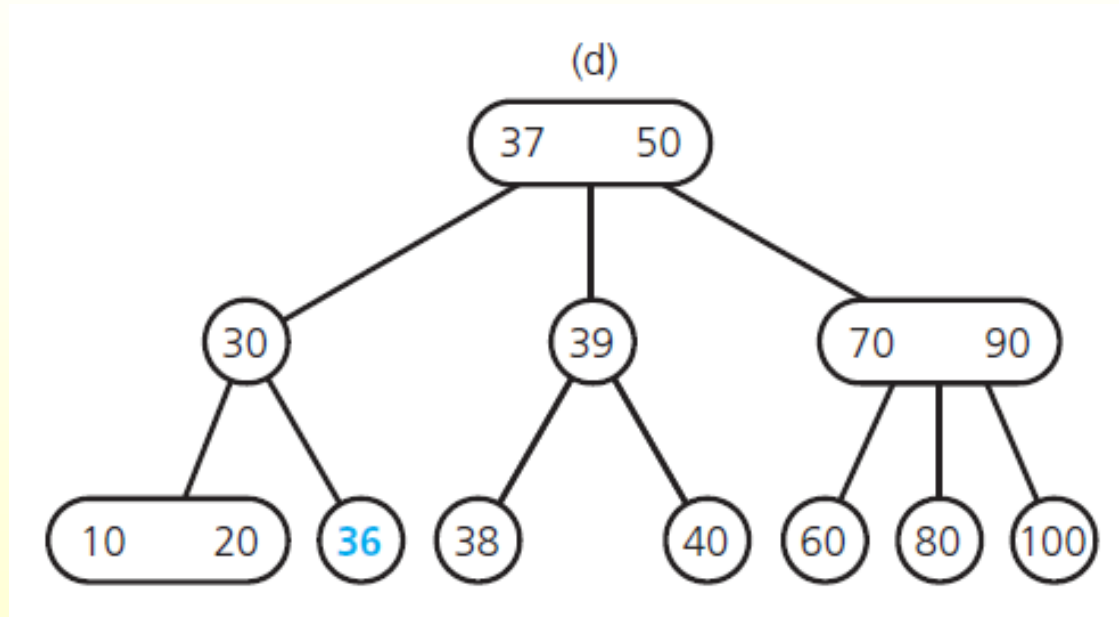
Inserting Data into a 2-3 Tree



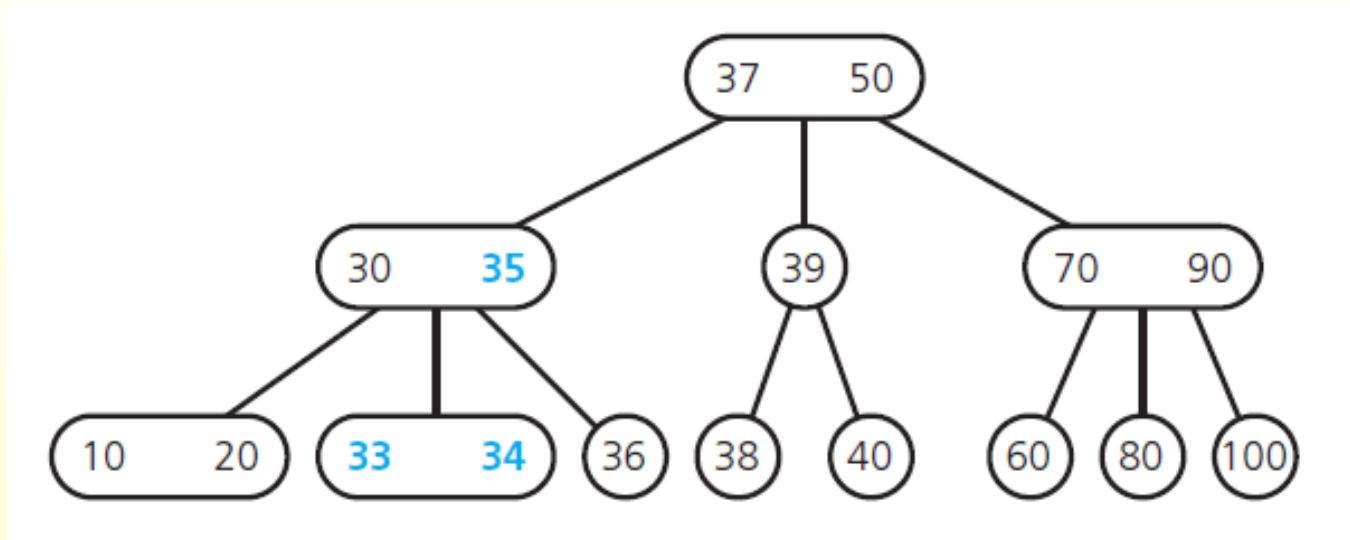
Inserting Data into a 2-3 Tree



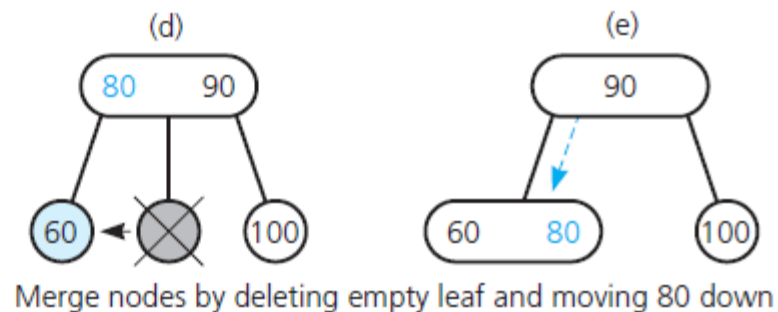
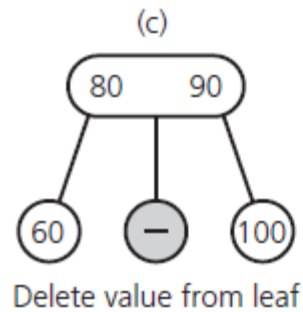
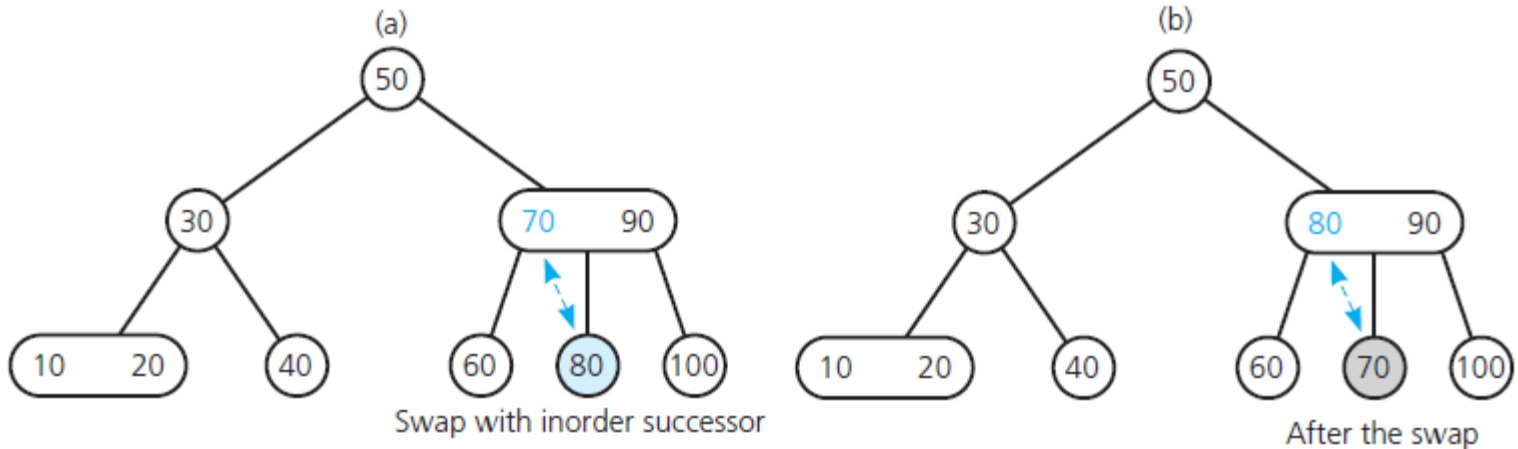
Inserting Data into a 2-3 Tree



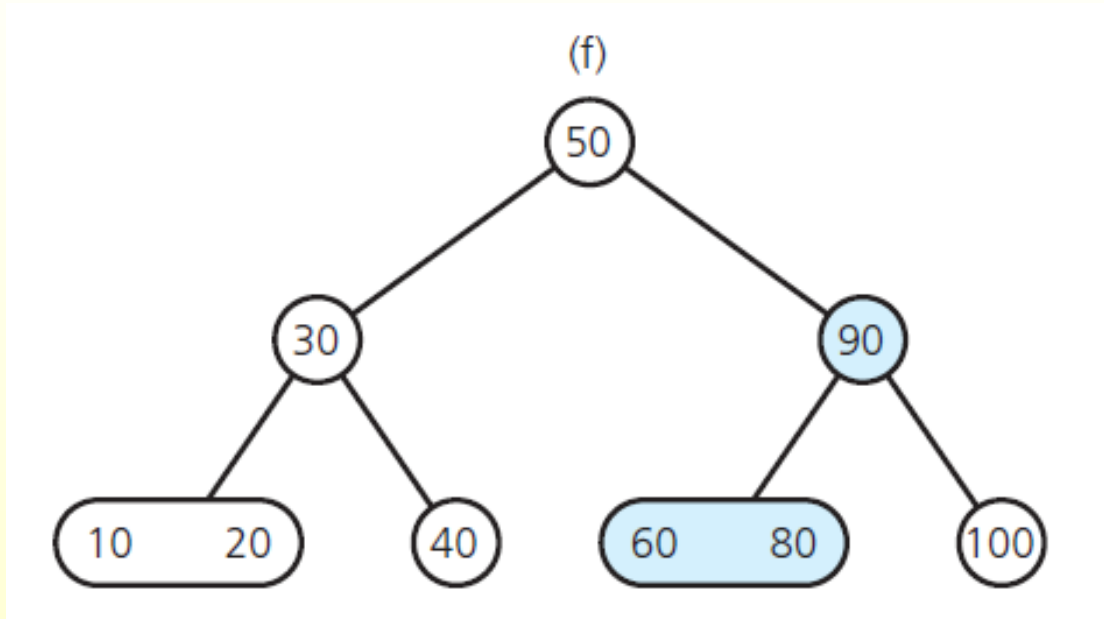
Inserting Data into a 2-3 Tree



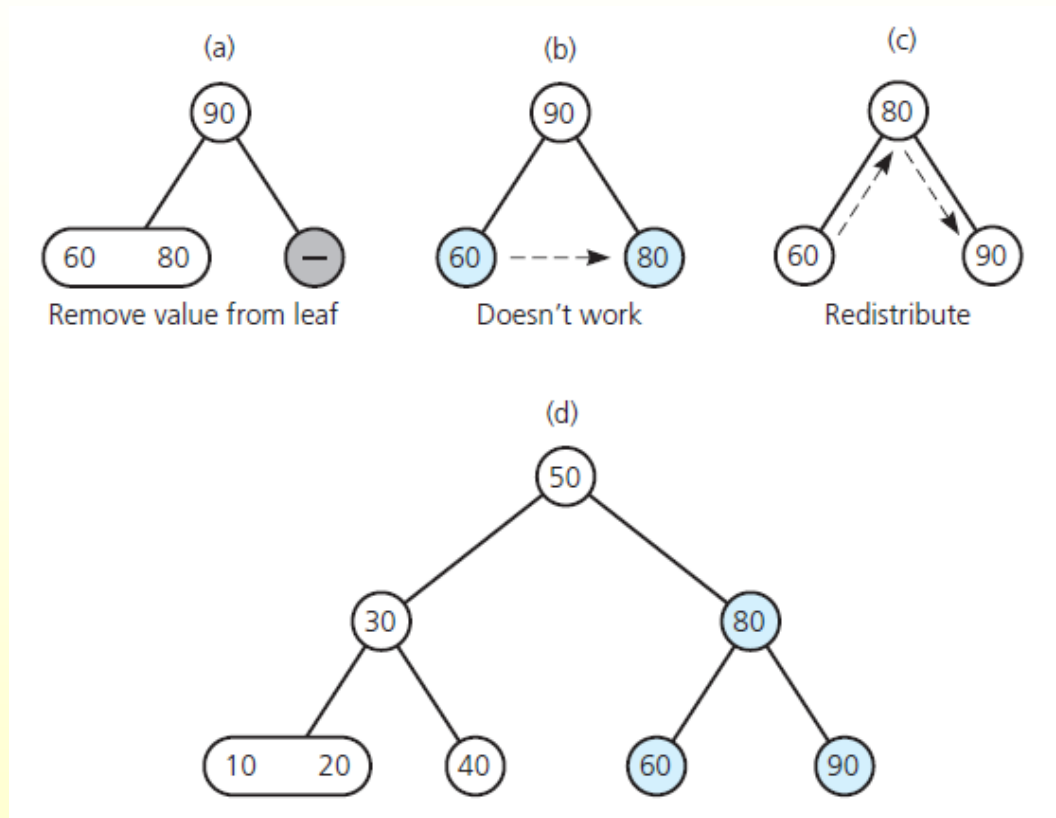
Deleting Data from a 2-3 Tree



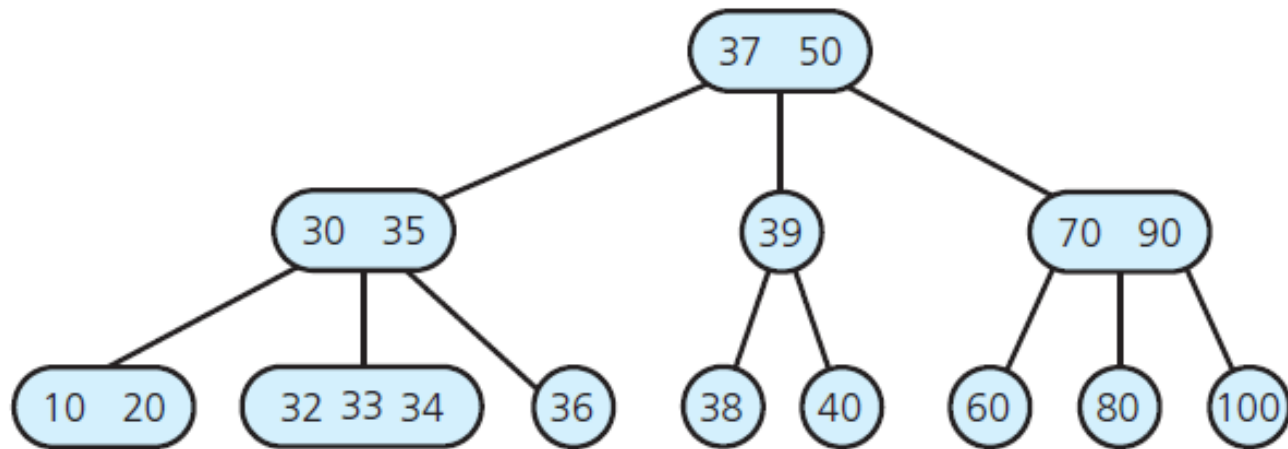
Deleting Data from a 2-3 Tree



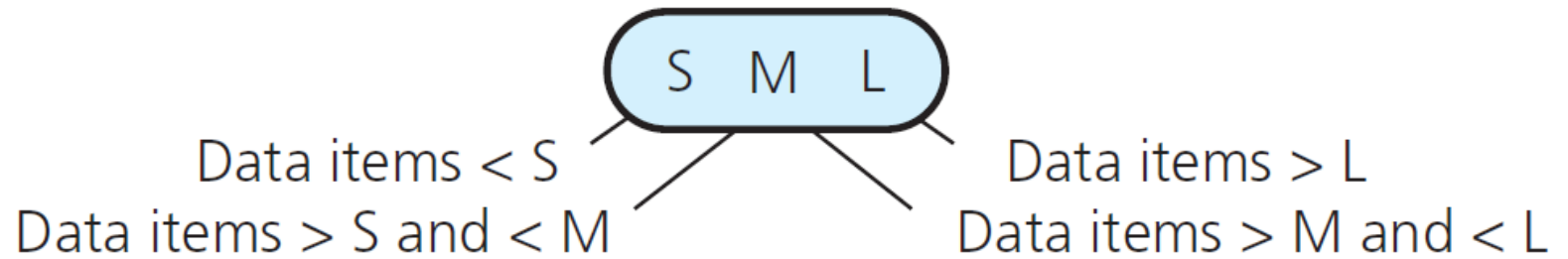
Deleting Data from a 2-3 Tree



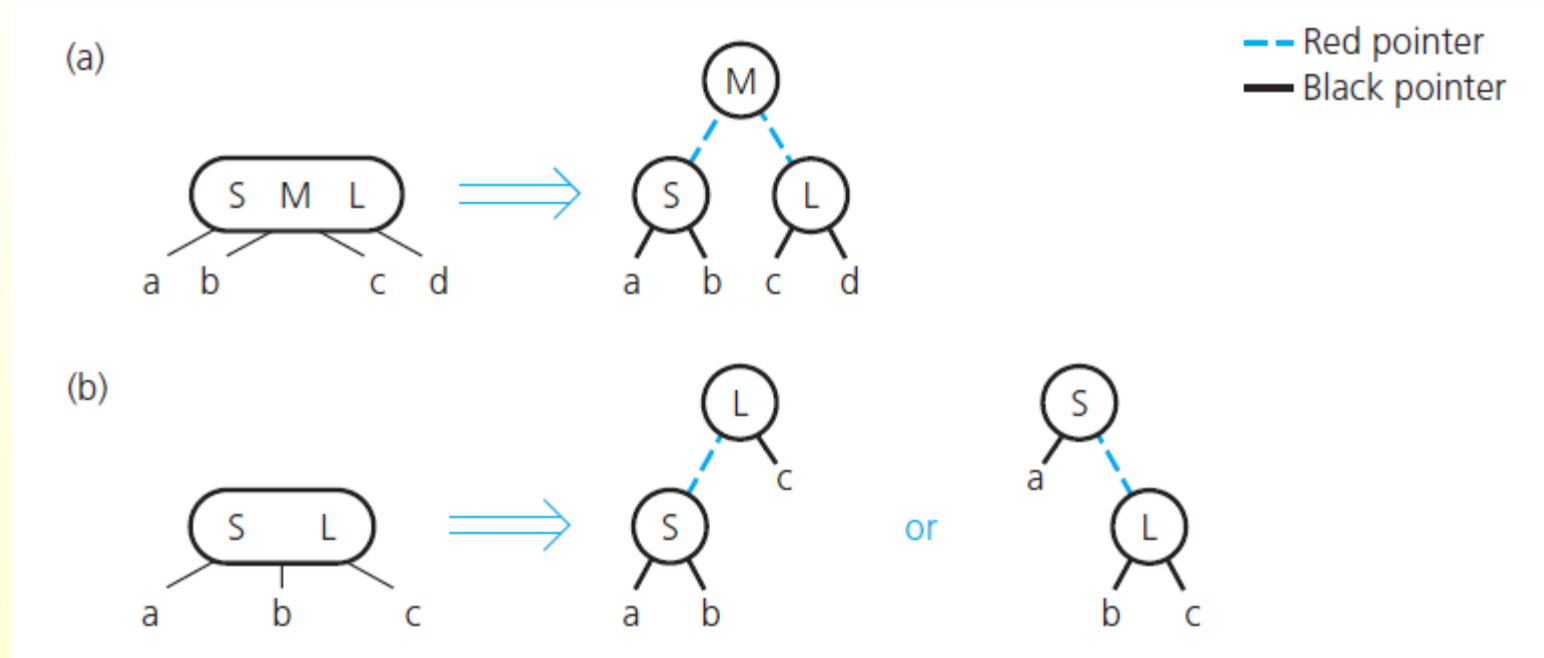
2-3-4 Trees



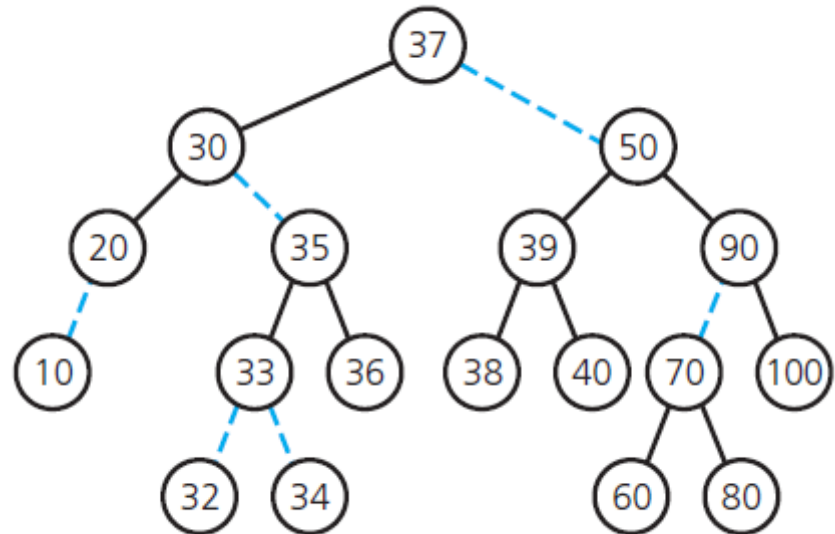
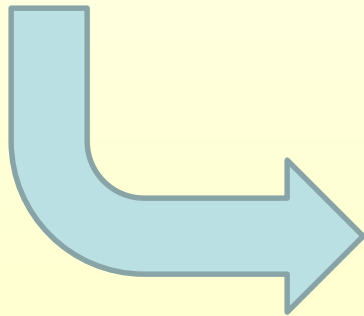
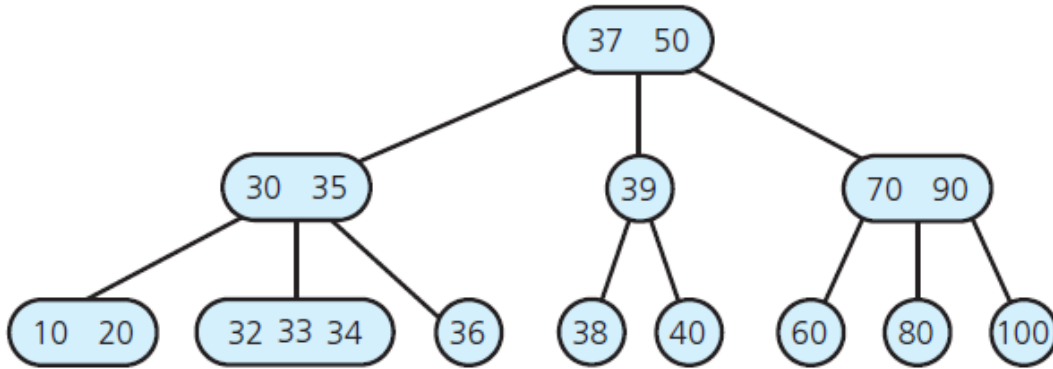
2-3-4 Trees



Red-Black Trees = 2-3-4 Trees



Red-Black Trees



AVL Trees

- ◆ Named for inventors, Adel'son-Vel'skii and Landis
- ◆ A balanced binary search tree
 - ◆ any node in an AVL tree has left and right subtrees whose heights differ by more than 1
- ◆ Has guaranteed $O(\lg n)$ height
- ◆ Not as efficient as red-black trees