

Real-Time Graphics Architecture

Kurt Akeley

Pat Hanrahan

<http://www.graphics.stanford.edu/courses/cs448a-01-fall>

Ray Tracing

with Tim Purcell

Topics

Why ray tracing?

Interactive ray tracing on multicomputers

Ray tracing hardware

The cost of ray tracing

SHARP architecture

Trends

CS448 Lecture 13

Kurt Akeley, Pat Hanrahan, Fall 2001

Readings

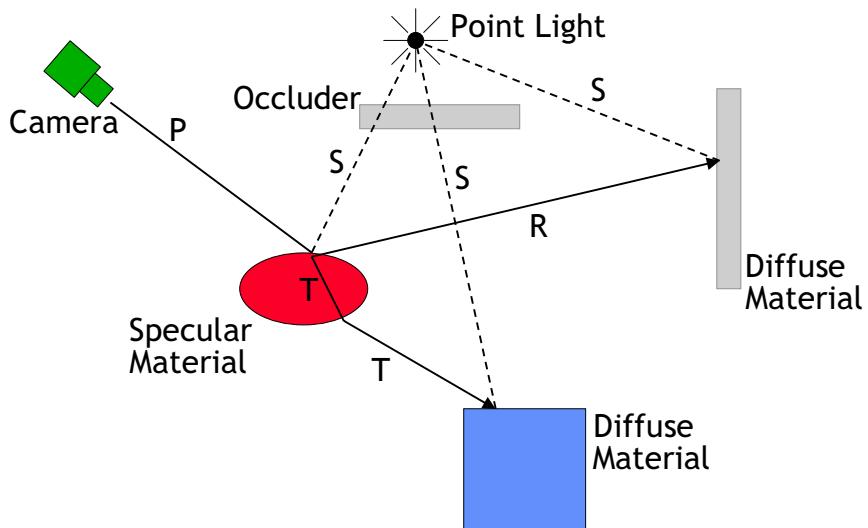
Required

1. I. Wald, P. Slusallek, **State-of-the-art in interactive ray tracing**, Eurographics 2001

CS448 Lecture 13

Kurt Akeley, Pat Hanrahan, Fall 2001

Ray Tracing Algorithm



CS448 Lecture 13

Kurt Akeley, Pat Hanrahan, Fall 2001

Photorealism

Direct light simulation vs. approximations

- True shadows vs. shadow maps
- True reflections vs. environment maps
- Interreflections



Henrik Wann Jensen

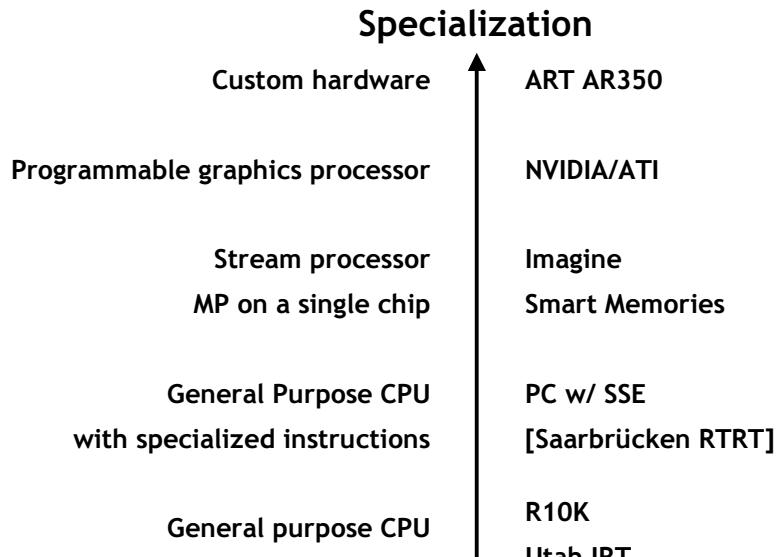
CS448 Lecture 13



Marcos Fajardo

Kurt Akeley, Pat Hanrahan, Fall 2001

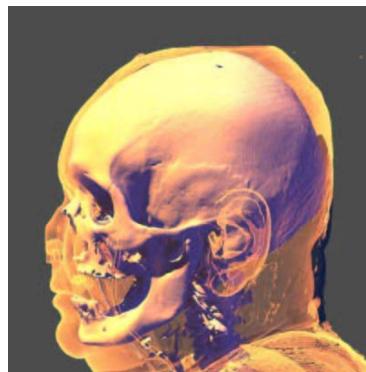
Target Implementation Spectrum



Interactive Ray Tracing

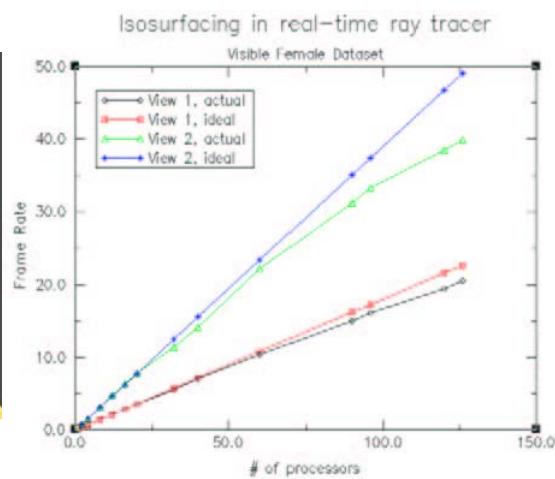
Embarrassingly parallel

Global database



Utah IRT on SGI Origin

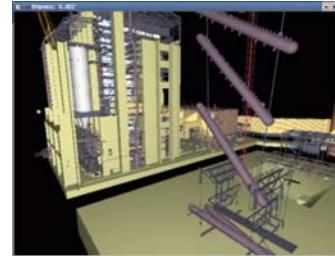
CS448 Lecture 13



Interactive Ray Tracing

Optimized data structures for cache

- Cluster data structures by access
- Pad and block (32B)
- Prefetch triangle data



Optimized code for IA w/ SSE

- Computation

Min 78 22 3.5

Max 148 41 3.7

Univ of Saarbrucken IRT

- Traces 4 rays at a time through BSP tree

Range of speeds 200 KR/s to 1.5 MR/s (800 Mhz PIII)

CS448 Lecture 13

Kurt Akeley, Pat Hanrahan, Fall 2001

Advantages: Output Complexity

Lazy evaluation - need not touch every triangle

Logarithmic search for ray intersection

Scene	Tris	Oct.	Onyx	PC	RT RT
MGF office	40k	>24	>36	12.7	1.8
MGF conf.	256k	>5	>10	5.4	1.6
MGF theater	680k	0.4	6-12	1.5	1.1
Library	907k	1.5	4	1.6	1.1
Soda Floor	2.5m	0.5	1.5	0.6	1.5
Soda Hall	8m	OOM	OOM	OOM	0.8

Table 3: OpenGL rendering performance in frames per second with SGI Performer on three different graphics hardware platforms compared with our software ray tracer at a resolution of 512^2 pixels on a dual processor PC. The ray tracer uses only a single processor, while SGI Performer actually uses all available CPUs.

CS448 Lecture 13

Kurt Akeley, Pat Hanrahan, Fall 2001

Advantages: Selective Sampling

- Adaptive sampling
- Frameless rendering (just-in-time rendering)

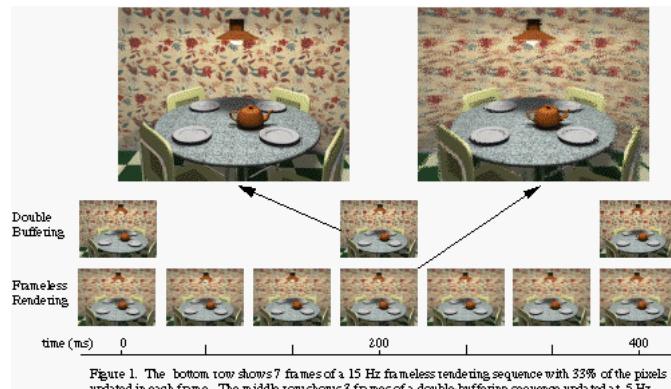


Figure 1. The bottom row shows 7 frames of a 15 Hz frameless rendering sequence with 33% of the pixels updated in each frame. The middle row shows 3 frames of a double-buffering sequence updated at 5 Hz.

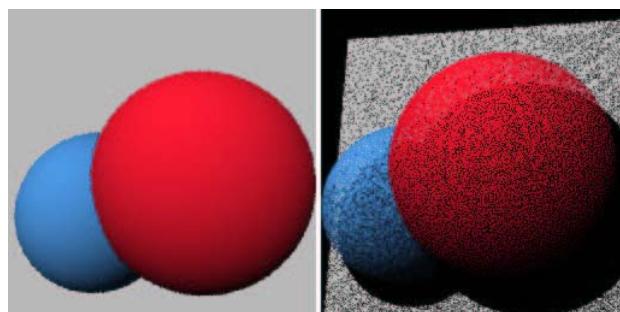
From Bishop et al., Frameless Rendering, SIGGRAPH 94

CS448 Lecture 13

Kurt Akeley, Pat Hanrahan, Fall 2001

Advantages: Selective Sampling

- Adaptive sampling
- Frameless rendering (just-in-time rendering)
- RenderCache
 - 1. Reproject
 - 2. Ray trace in holes



From Walter et al., RenderCache, Eurographics 97

CS448 Lecture 13

Kurt Akeley, Pat Hanrahan, Fall 2001

Advantages: Selective Sampling

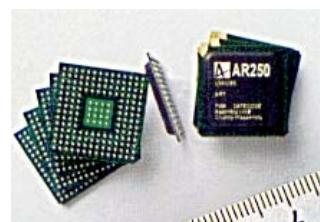
- Adaptive sampling
- Frameless rendering (just-in-time rendering)
- RenderCache
- Holodeck
- Foveal rendering
- Rendering under pressure

CS448 Lecture 13

Kurt Akeley, Pat Hanrahan, Fall 2001

AR250 (newer AR350)

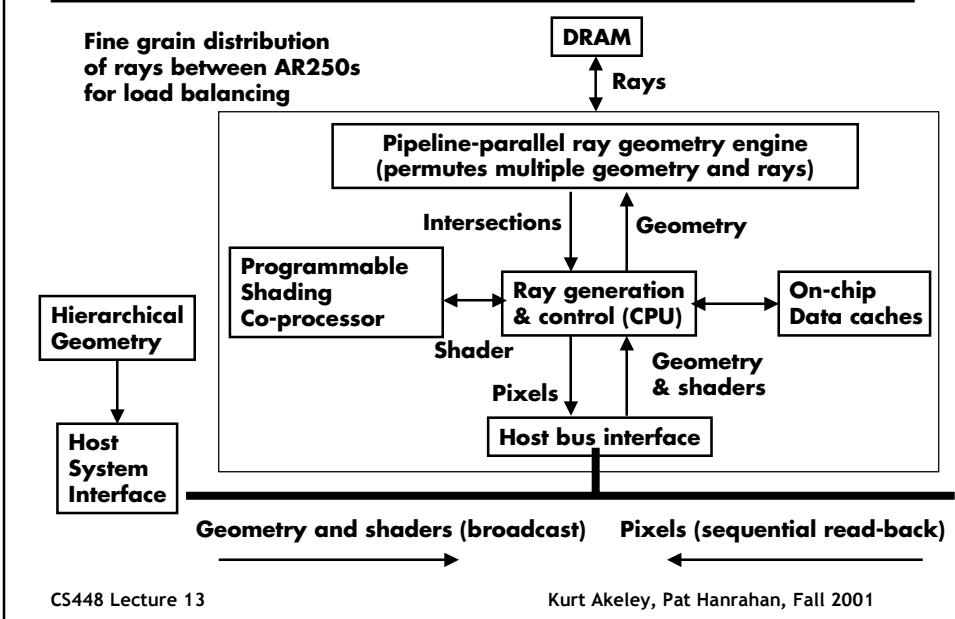
.35 um, 106 mm² die
650K gates
32 single stage IEEE FPUs
50 Mhz



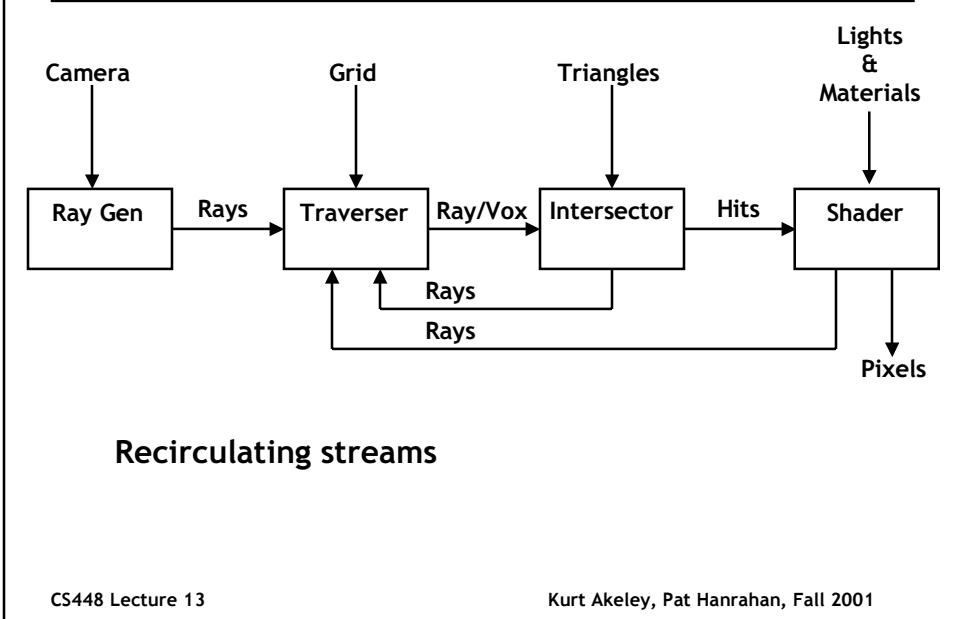
CS448 Lecture 13

Kurt Akeley, Pat Hanrahan, Fall 2001

ART AR250



SHARP Architecture



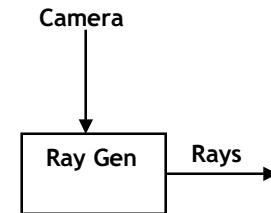
Eye Ray Generator

Computation

- 10+, 13*, 5/, 3 SPC
- 100 MIPS R10K
- 13 VP1.0

```
Ray {  
    vec3f O;  
    vec3f D;  
    float t;  
    vec2f xy;  
    vec3f weight;  
    byte type;  
} // 49 bytes
```

CS448 Lecture 13



Kurt Akeley, Pat Hanrahan, Fall 2001

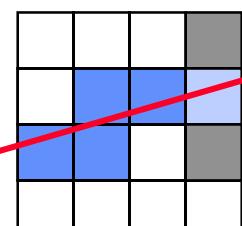
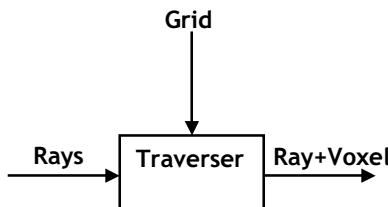
Traverser

Acceleration data struction

- Occupancy bitmap
- No triangle data
- Ray-voxel grid traversal
- 3D-DDA (line drawing)

Computation

- Setup 15+, 6*, 9/, 30 CMP
Traverse 4+, 3*, 8 CMP



CS448 Lecture 13

Kurt Akeley, Pat Hanrahan, Fall 2001

Grid Acceleration Structure

Reasonable: No clear 'best' accel. structure anyway

Optimizations

- Mailboxing (Doesn't parallelize well, don't use)
- Blocking (64bits = 4x4x4)
- Hierarchies (Two-level blocked grid)

Inserting triangles into grid

- Amortize cost for static geometry (display lists)
- Costly for time-varying geometry
- Basically 3D rasterization

CS448 Lecture 13

Kurt Akeley, Pat Hanrahan, Fall 2001

Intersector

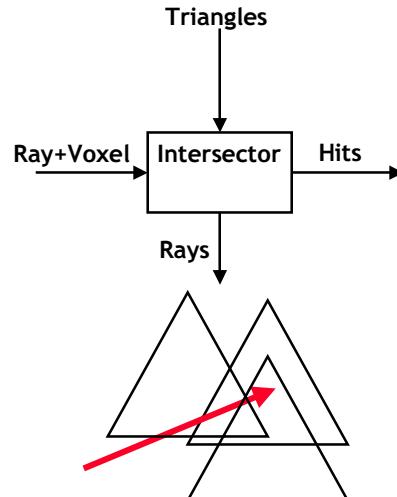
Ray-Triangle Intersection

- Möller-Trumbore algorithm
- Basically point inside triangle
- Rasterization!

Computation

23+, 27*, 1/, 14 CMP

```
Triangle {  
    vec3f P[3];  
} // 36 bytes
```



CS448 Lecture 13

Kurt Akeley, Pat Hanrahan, Fall 2001

Total Operations

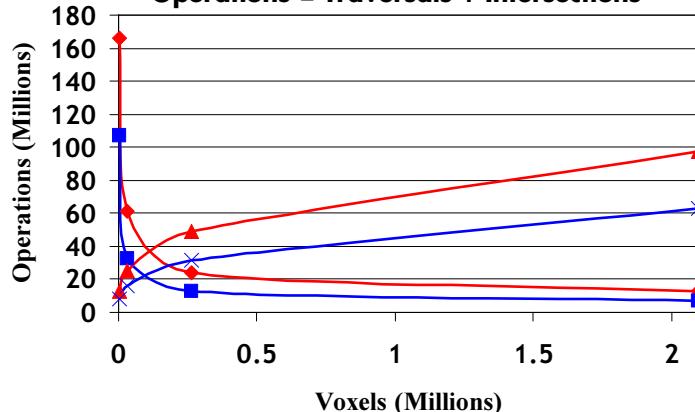


Bunny
69,415 Triangles



Quake 3
35,468 Triangles

Operations = Traversals + Intersections



CS448 Lecture 13

Kurt Akeley, Pat Hanrahan, Fall 2001

Total Instructions

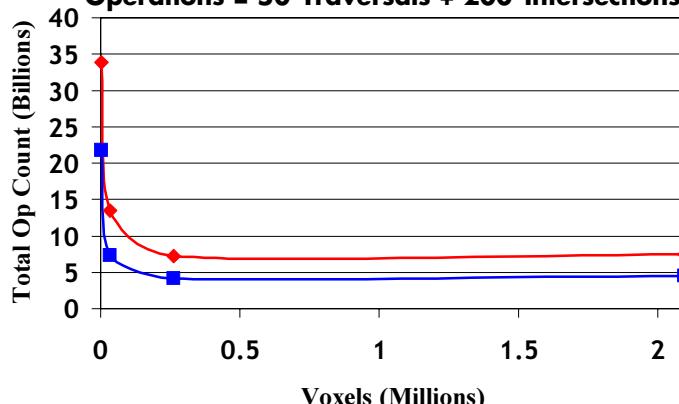


Bunny
69,415 Triangles



Quake 3
35,468 Triangles

Operations = 50*Traversals + 200*Intersections



CS448 Lecture 13

Kurt Akeley, Pat Hanrahan, Fall 2001

Shader

Diffuse shading

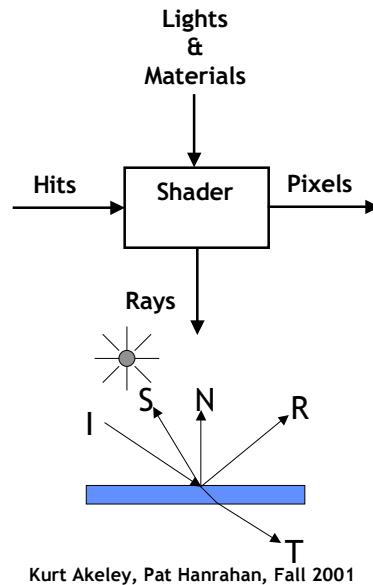
19+, 21*

```
Hit {
    vec3f O, D;
    vec2f xy;
    vec3f weight;
    float t;
    byte type;
    long tri;
    vec2f uv;
} // 99 bytes
```

Shadow and secondary rays generated here

Weighted rays

CS448 Lecture 13



Kurt Akeley, Pat Hanrahan, Fall 2001

Cost Model

$$C = R T + S$$

With acceleration

$$C = RV + RT + S$$

I = average number of ray-voxel traversals

mean free path of the ray

a = average number of triangles per voxel

t = $I a$ (average number of ray-triangle intersections)

$$C = R (I Crv + t Crt + Cs) = R [I * (Crv + a Crt) + Cs]$$

I analogous to depth complexity

CS448 Lecture 13

Kurt Akeley, Pat Hanrahan, Fall 2001

Cost Model

$\text{Ray-Triangle intersections} = r T = t R$

r = average number of rays tested per triangle

t = average number of triangles tested per ray

When $r < 1$, ray tracing wins

- Two effects

- Depth complexity

- Small triangles (might still cost something)

CS448 Lecture 13

Kurt Akeley, Pat Hanrahan, Fall 2001

Cost Model

Deferred Shading

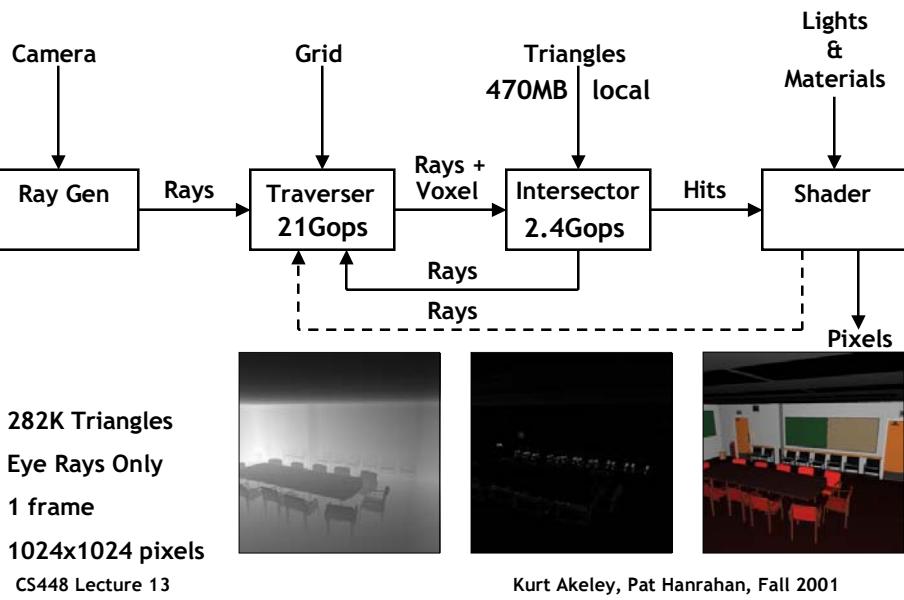
$$R I (C_{rt} + C_s/I) = I d (C_{fv} + C_s)$$

When C_s large, ray tracing wins

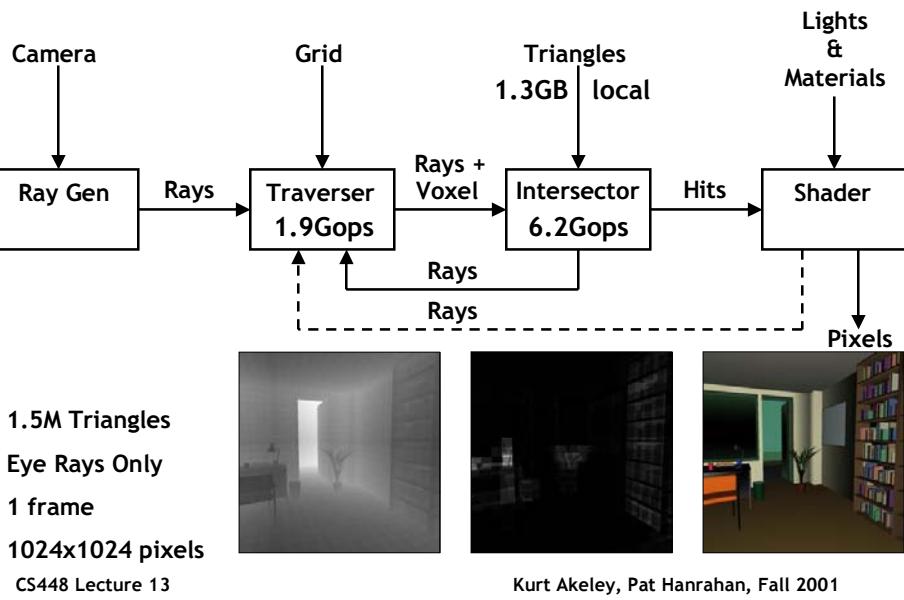
CS448 Lecture 13

Kurt Akeley, Pat Hanrahan, Fall 2001

Architecture Measurements



Architecture Measurements



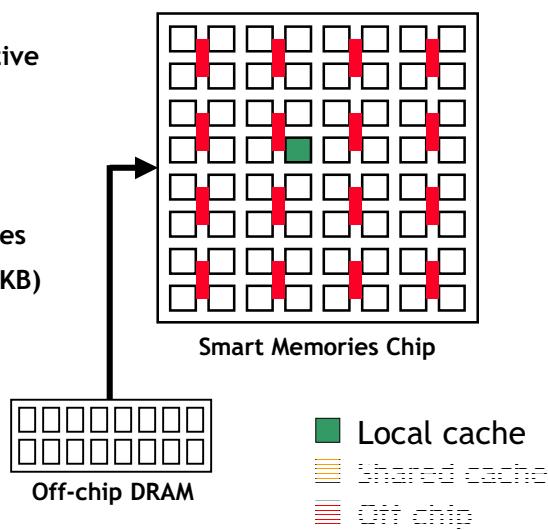
Caching on Smart Memories

Cache Policy

- 4-way set associative
- LRU replacement

System Configuration

- 32 intersection tiles
- 1024 triangle (44 KB) cache size each
- Shared caches



CS448 Lecture 13

Kurt Akeley, Pat Hanrahan, Fall 2001

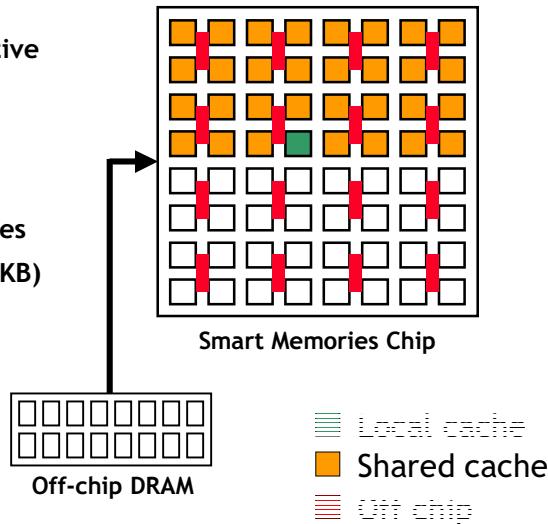
Caching on Smart Memories

Cache Policy

- 4-way set associative
- LRU replacement

System Configuration

- 32 intersection tiles
- 1024 triangle (44 KB) cache size each
- Shared caches



CS448 Lecture 13

Kurt Akeley, Pat Hanrahan, Fall 2001

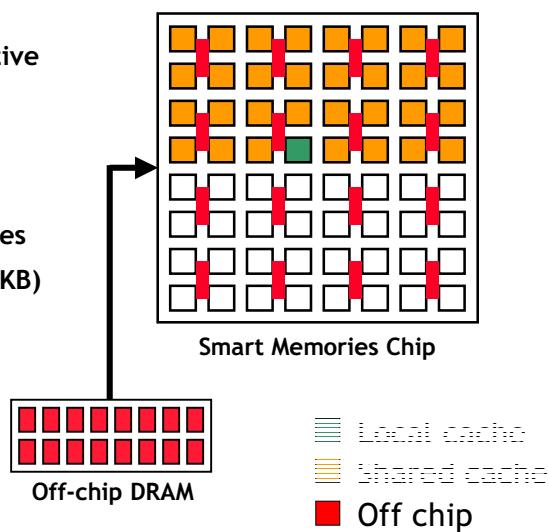
Caching on Smart Memories

Cache Policy

- 4-way set associative
- LRU replacement

System Configuration

- 32 intersection tiles
- 1024 triangle (44 KB) cache size each
- Shared caches

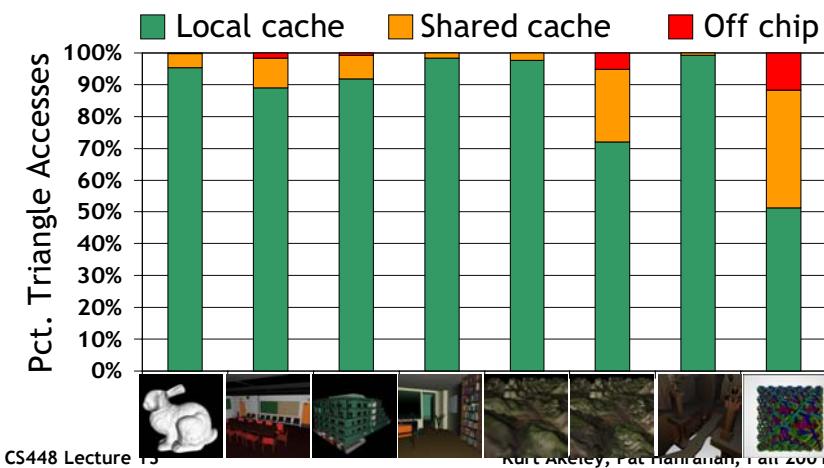


CS448 Lecture 13

Kurt Akeley, Pat Hanrahan, Fall 2001

Small and Simple Caching Suffices

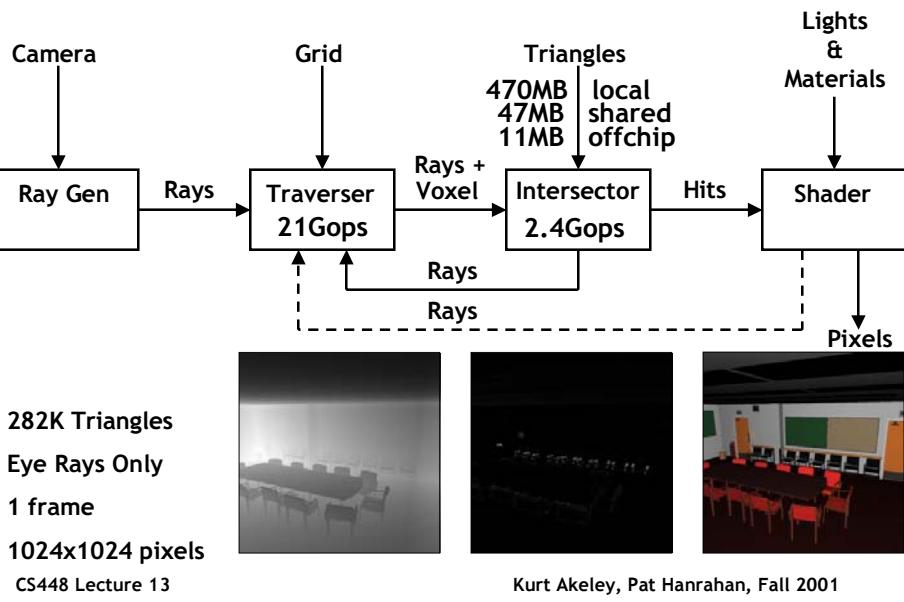
Over 93% of all triangle references are on chip -- stall time < 10% of execution time



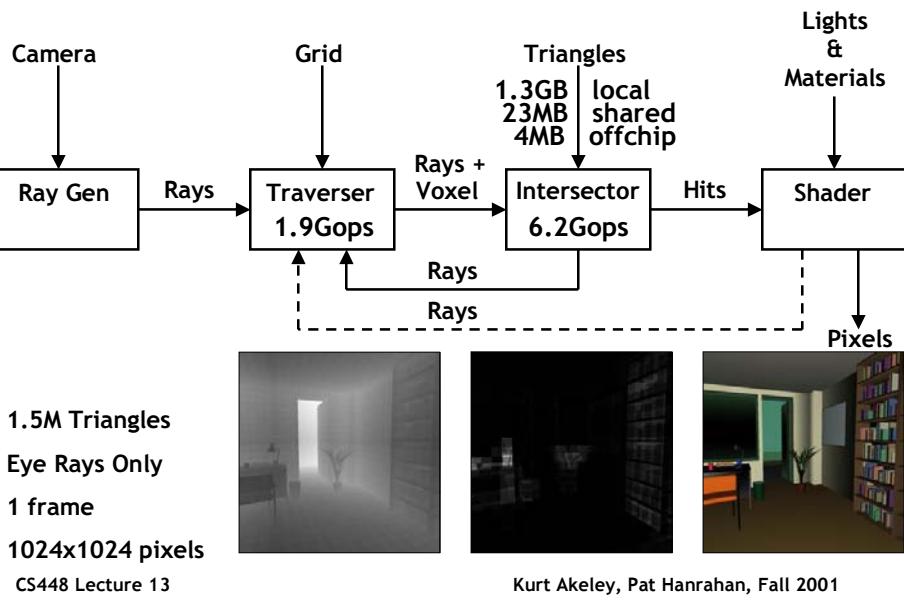
CS448 Lecture 13

Kurt Akeley, Pat Hanrahan, Fall 2001

Architecture Measurements



Architecture Measurements



Performance Analysis

Compute limited

- 3:1 compute to internal bandwidth ratio for intersector
- 10:1 compute to internal bandwidth ratio for traverser
- Ray tracing generally thought to be bandwidth limited

Tuning Smart Memories for ray tracing

- Split FP units (64bit → 2x 32bit) (2x)
- Specialized and/or SSE-like instructions (2-5x)
- Remote data pre-fetching (1.2x)

Excellent performance!

- 32 tiles can perform 1500M intersections/s
- 30 tiles can perform 5000M traversals/s
- 100 times faster than PC with SSE

CS448 Lecture 13

Kurt Akeley, Pat Hanrahan, Fall 2001

Summary and Trends

Summary

Ray tracing algorithm

- Embarrassingly parallel
- Global access to database

Ray tracing kernels not unlike pipeline kernels

- Ray-voxel traversal like line drawing
- Ray-triangle intersection like rasterization

Seems to map well to streaming processor

CS448 Lecture 13

Kurt Akeley, Pat Hanrahan, Fall 2001

Evolution of the Graphics Pipeline

Evolving the graphics pipeline to accommodate RT

Hybrid algorithms (1st pass using conventional pipe)

- Shadows
- Ray-traced reflections

Full ray tracing

- Ray casting
- Monte Carlo path tracing

CS448 Lecture 13

Kurt Akeley, Pat Hanrahan, Fall 2001

Cross-Over

When does ray tracing compete with classic pipeline?

- High model complexity
 - High depth complexity
 - Small triangle size
 - Efficient acceleration structure
- High shading complexity
 - Deferred shading wins

Exactly when?

CS448 Lecture 13

Kurt Akeley, Pat Hanrahan, Fall 2001

Convergence of Geometry/Texture

Different mechanisms

- Define and bind textures
- Render immediate mode geometry

Complexity

- Detail in texture
- Detail in geometry

Static vs. dynamic

- Textures static
- Geometry dynamic

CS448 Lecture 13

Kurt Akeley, Pat Hanrahan, Fall 2001