

# Realistic Animation of Fluids

Nick Foster and Dimitri Metaxas

# Overview

- Problem Statement
- Previous Work
- Navier-Stokes Equations
- Explicit solving
- Results

# Problem Statement

- Simulate fluids for graphics applications
- Scalability
- Usability
  - Easy to setup
  - Controllable

# Related Work

- Non-physics based
  - Parametric functions
  - Sinusoidal phase functions
- Physics based
  - CFD
    - Too expensive
    - Not controllable
  - Kass and Miller
    - Shallow water
  - Chen and Lobo
    - Navier-Stokes in 2-D
    - Fluid zero depth
    - Use instantaneous pressure

# Navier-Stokes Equation

- Conservation of Momentum

$$\frac{\partial u}{\partial t} + u \frac{\partial u}{\partial x} + v \frac{\partial u}{\partial y} + w \frac{\partial u}{\partial z} = -\frac{\partial p}{\partial x} + g_x + \mu \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right)$$

$$\frac{\partial v}{\partial t} + u \frac{\partial v}{\partial x} + v \frac{\partial v}{\partial y} + w \frac{\partial v}{\partial z} = -\frac{\partial p}{\partial y} + g_y + \mu \left( \frac{\partial^2 v}{\partial x^2} + \frac{\partial^2 v}{\partial y^2} + \frac{\partial^2 v}{\partial z^2} \right)$$

$$\frac{\partial w}{\partial t} + u \frac{\partial w}{\partial x} + v \frac{\partial w}{\partial y} + w \frac{\partial w}{\partial z} = -\frac{\partial p}{\partial z} + g_z + \mu \left( \frac{\partial^2 w}{\partial x^2} + \frac{\partial^2 w}{\partial y^2} + \frac{\partial^2 w}{\partial z^2} \right)$$

- Conservation of Mass

$$\frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0$$

# Conservation of Momentum

$$\rho \frac{D\mathbf{V}}{Dt} = -\nabla p + \rho \mathbf{g} + \mu \nabla^2 \mathbf{V}$$

- Vector form

# Conservation of Momentum

$$\rho \frac{D\mathbf{V}}{Dt} = -\nabla p + \rho \mathbf{g} + \mu \nabla^2 \mathbf{V}$$

- Vector form
- Normalize for  $\rho$

# Conservation of Momentum

$$\frac{D\mathbf{V}}{Dt} = -\nabla p + \mathbf{g} + \mu \nabla^2 \mathbf{V}$$

- Vector form
- Normalize for  $\rho$



# Conservation of Momentum

$$\frac{D\mathbf{V}}{Dt} = -\nabla p + \mathbf{g} + \mu \nabla^2 \mathbf{V}$$

- Vector form
- Normalize for  $\rho$
- LHS
  - Inertial force

# Conservation of Momentum

$$\frac{D\mathbf{V}}{Dt} = -\nabla p + \mathbf{g} + \mu \nabla^2 \mathbf{V}$$

- Vector form
- Normalize for  $\rho$
- LHS
  - Inertial force
- RHS
  - Surface forces due to pressure differences

# Conservation of Momentum

$$\frac{D\mathbf{V}}{Dt} = -\nabla p + \mathbf{g} + \mu \nabla^2 \mathbf{V}$$

- Vector form
- Normalize for  $\rho$
- LHS
  - Inertial force
- RHS
  - Surface forces due to pressure differences
  - Gravity

# Conservation of Momentum

$$\frac{D\mathbf{V}}{Dt} = -\nabla p + \mathbf{g} + \mu \nabla^2 \mathbf{V}$$

- Vector form
- Normalize for  $\rho$
- LHS
  - Inertial force
- RHS
  - Surface forces due to pressure differences
  - Gravity
  - Sheer force due to viscosity

# LHS

- Begin with Newton's Second Law

$$\mathbf{F} = m \frac{d\mathbf{V}}{dt}$$

# LHS

- Begin with Newton's Second Law

$$\mathbf{F} = m \frac{d\mathbf{V}}{dt}$$

- Using the Chain Rule

$$\frac{d\mathbf{V}}{dt} = \frac{\partial \mathbf{V}}{\partial x} \frac{dx}{dt} + \frac{\partial \mathbf{V}}{\partial y} \frac{dy}{dt} + \frac{\partial \mathbf{V}}{\partial z} \frac{dz}{dt} + \frac{\partial \mathbf{V}}{\partial t}$$

# LHS

- Begin with Newton's Second Law

$$\mathbf{F} = m \frac{d\mathbf{V}}{dt}$$

- Using the Chain Rule

$$\frac{d\mathbf{V}}{dt} = \frac{\partial \mathbf{V}}{\partial x} \frac{dx}{dt} + \frac{\partial \mathbf{V}}{\partial y} \frac{dy}{dt} + \frac{\partial \mathbf{V}}{\partial z} \frac{dz}{dt} + \frac{\partial \mathbf{V}}{\partial t}$$

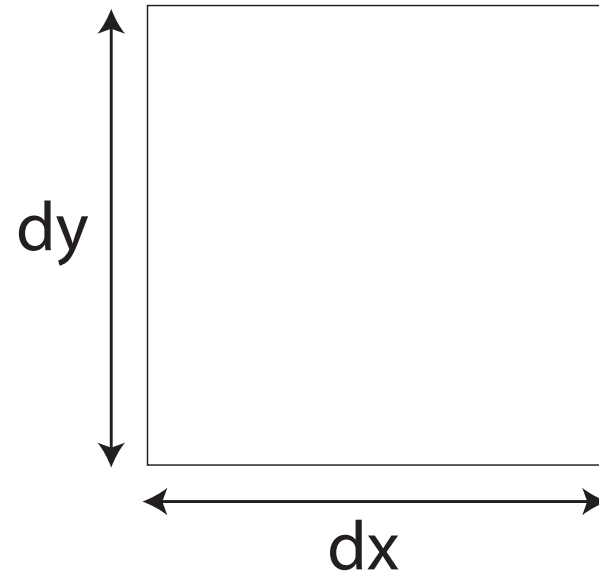
$$= u \frac{\partial \mathbf{V}}{\partial x} + v \frac{\partial \mathbf{V}}{\partial y} + w \frac{\partial \mathbf{V}}{\partial z} + \frac{\partial \mathbf{V}}{\partial t}$$

# RHS

- Pressure
- Gravity
- Shear forces

$$F_{yx} = \mu \frac{\partial^2 u}{\partial y^2}$$

$$F_{xx} = \mu \frac{\partial^2 u}{\partial x^2}$$



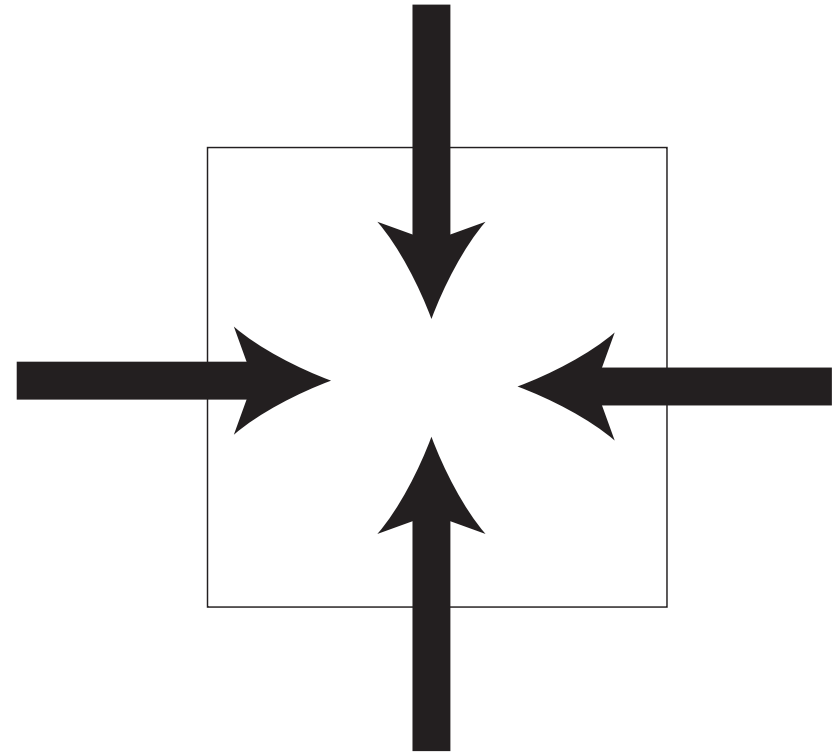


# RHS

- Pressure
- Gravity
- Shear forces

$$F_{yx} = \mu \frac{\partial^2 u}{\partial y^2}$$

$$F_{xx} = \mu \frac{\partial^2 u}{\partial x^2}$$

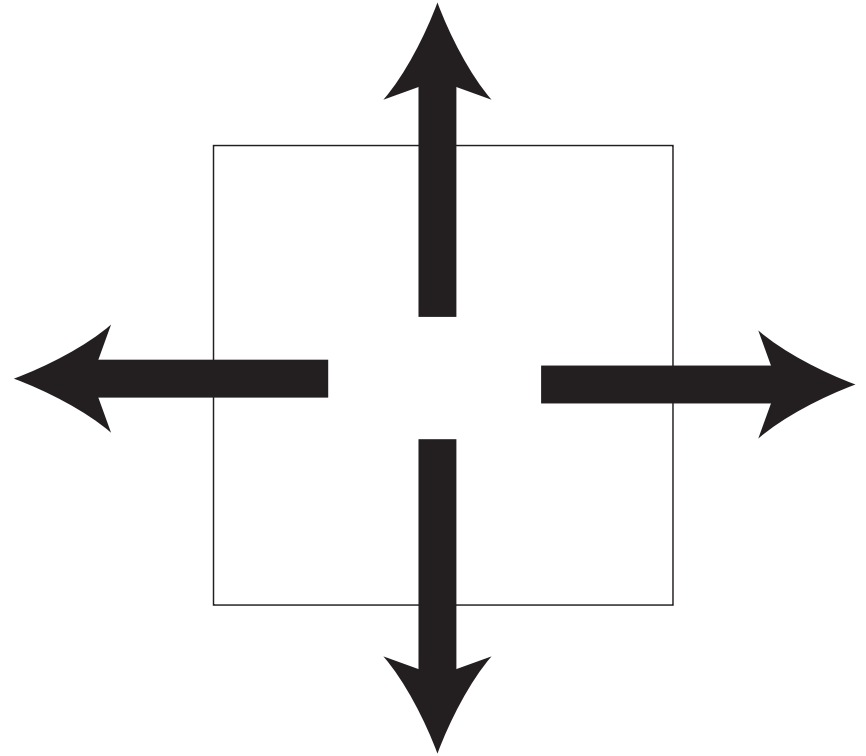


# RHS

- Pressure
- Gravity
- Shear forces

$$F_{yx} = \mu \frac{\partial^2 u}{\partial y^2}$$

$$F_{xx} = \mu \frac{\partial^2 u}{\partial x^2}$$

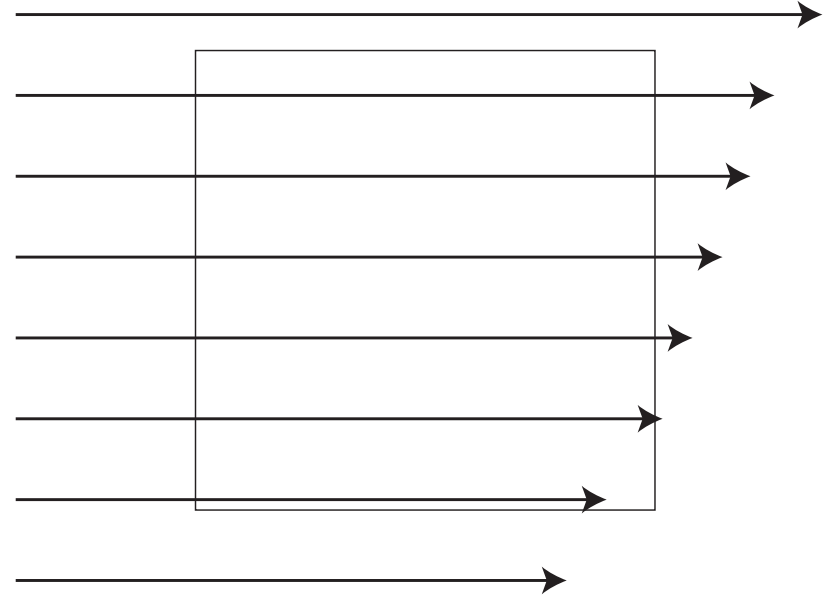


# RHS

- Pressure
- Gravity
- Shear forces

$$F_{yx} = \mu \frac{\partial^2 u}{\partial y^2}$$

$$F_{xx} = \mu \frac{\partial^2 u}{\partial x^2}$$

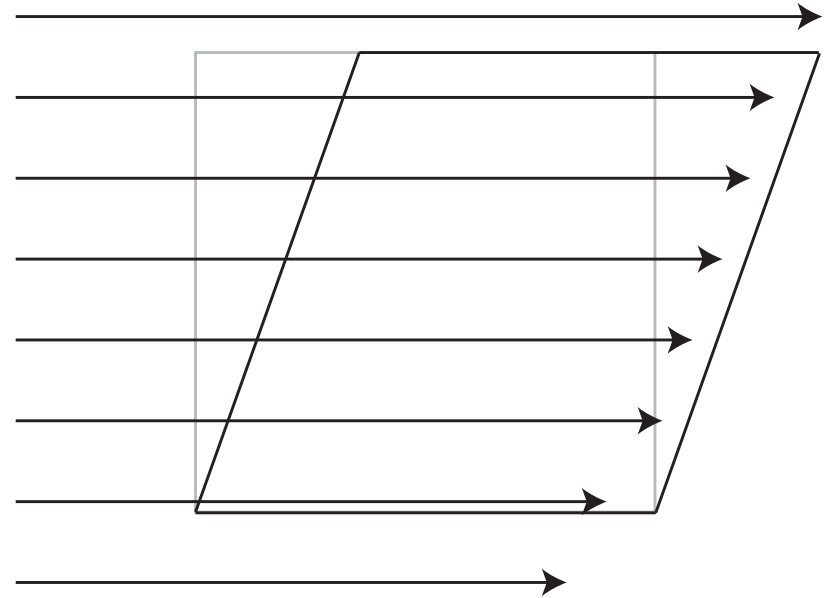


# RHS

- Pressure
- Gravity
- Shear forces

$$F_{yx} = \mu \frac{\partial^2 u}{\partial y^2}$$

$$F_{xx} = \mu \frac{\partial^2 u}{\partial x^2}$$

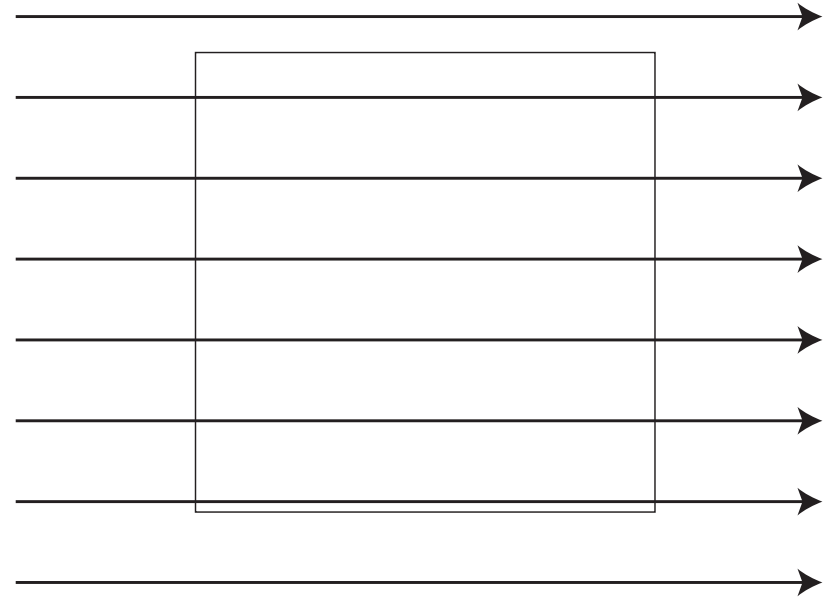


# RHS

- Pressure
- Gravity
- Shear forces

$$F_{yx} = \mu \frac{\partial^2 u}{\partial y^2}$$

$$F_{xx} = \mu \frac{\partial^2 u}{\partial x^2}$$

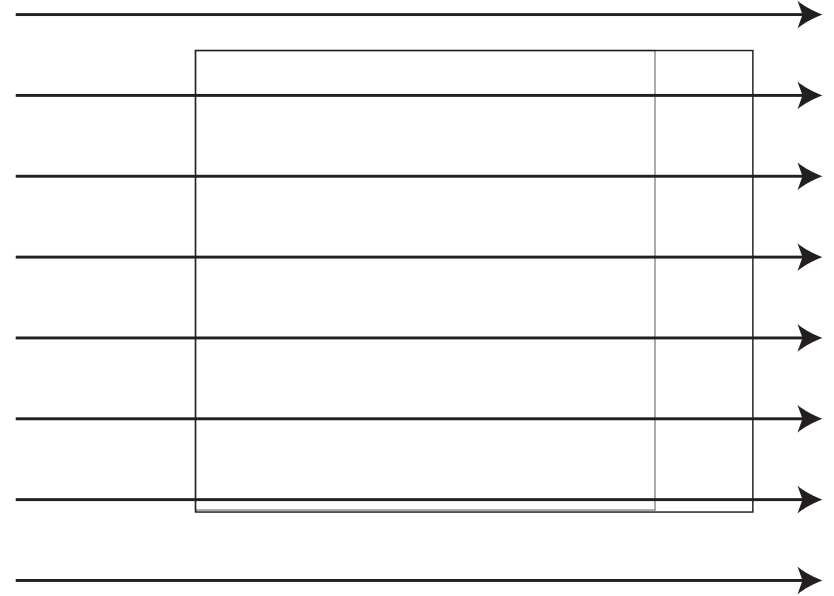


# RHS

- Pressure
- Gravity
- Shear forces

$$F_{yx} = \mu \frac{\partial^2 u}{\partial y^2}$$

$$F_{xx} = \mu \frac{\partial^2 u}{\partial x^2}$$

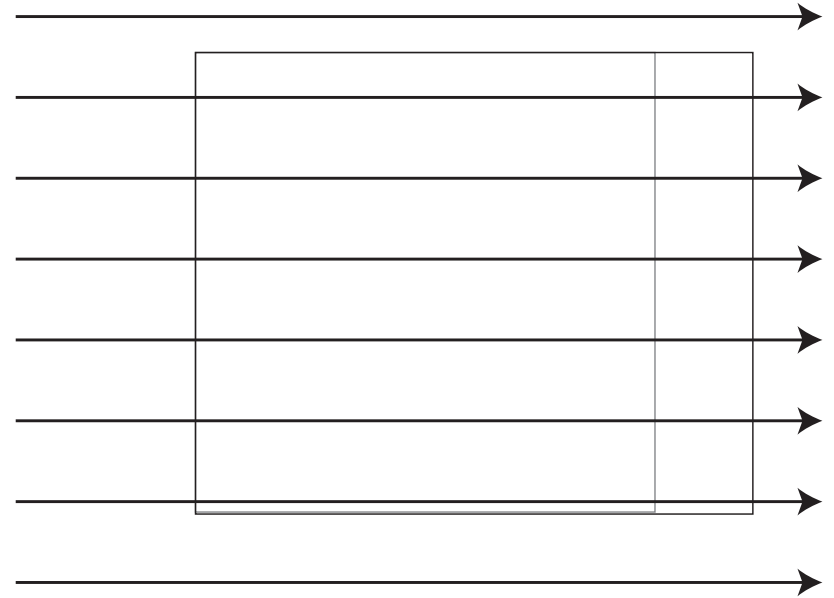


# RHS

- Pressure
- Gravity
- Shear forces

$$F_{yx} = \mu \frac{\partial^2 u}{\partial y^2}$$

$$F_{xx} = \mu \frac{\partial^2 u}{\partial x^2}$$

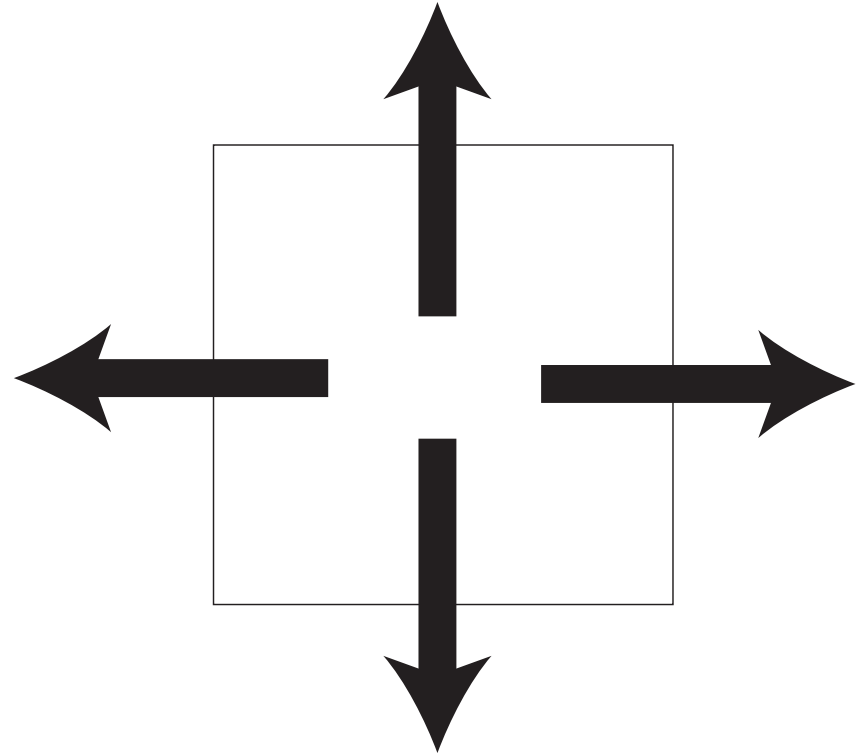


- In 3-D:

$$F_x = \mu \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right)$$

# Conservation of Mass

- Incompressible fluid
- Divergence should be zero

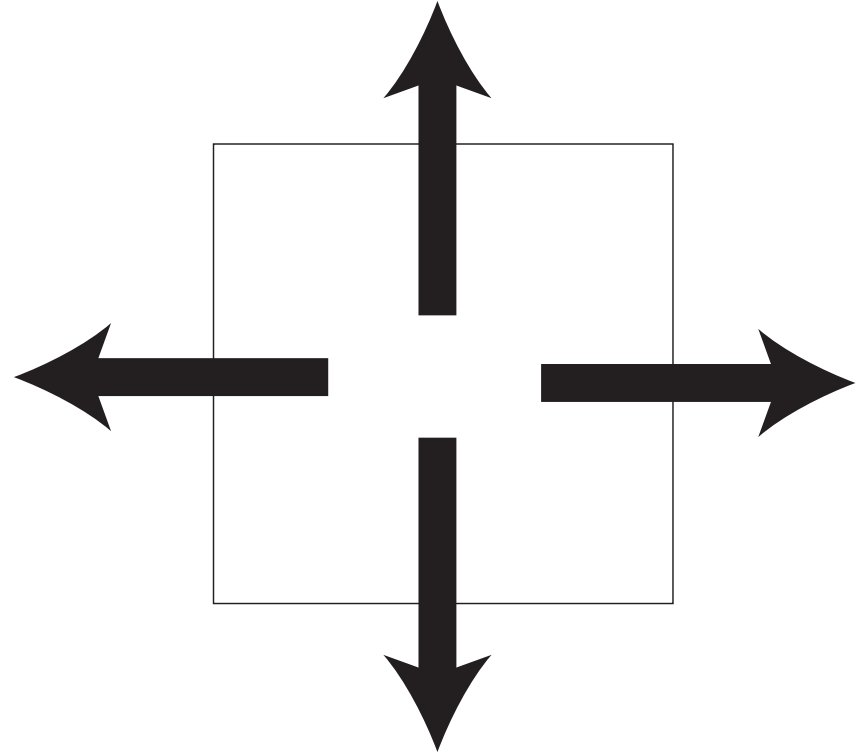




# Conservation of Mass

- Incompressible fluid
- Divergence should be zero

$$\frac{\partial \rho}{\partial t} + \frac{\partial \rho u}{\partial x} + \frac{\partial \rho v}{\partial y} + \frac{\partial \rho w}{\partial z} = 0$$

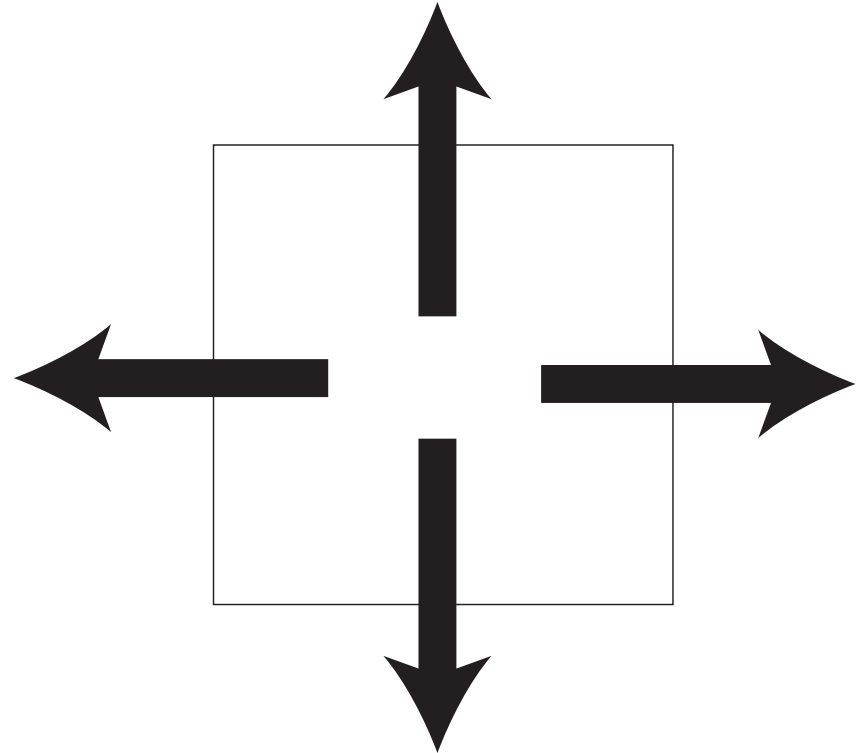


# Conservation of Mass

- Incompressible fluid
- Divergence should be zero

$$\frac{\partial \rho}{\partial t} + \frac{\partial \rho u}{\partial x} + \frac{\partial \rho v}{\partial y} + \frac{\partial \rho w}{\partial z} = 0$$

$$\Rightarrow \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0$$



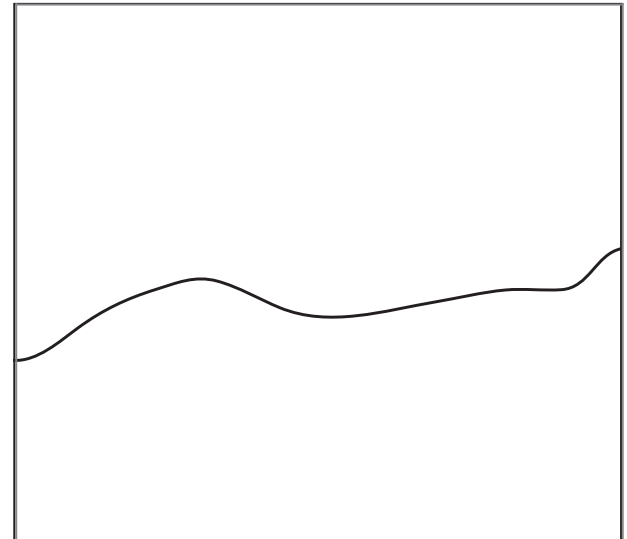
# Solving Navier-Stokes

- Specify obstacle/boundaries
- Discretize on a rough grid
- Solve equations
- Interpolate surface of fluid

# Discretization

- Rectangular Cartesian grid
- Finite differences
- Velocity defined on cell faces
- Pressure defined in cell
- Stability

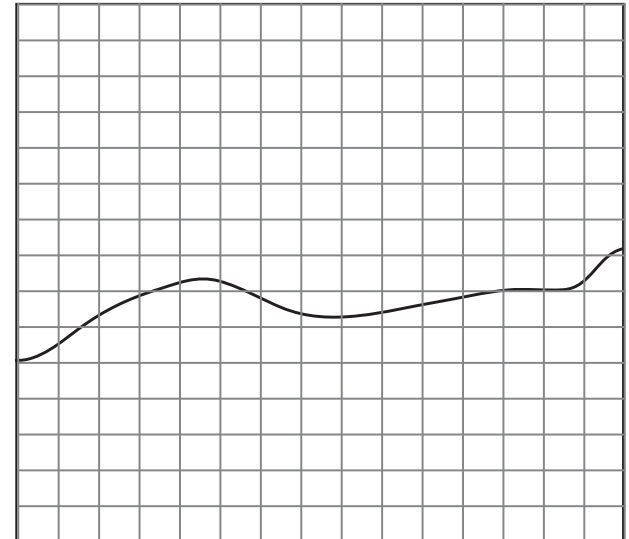
$$1 > \max \left[ u \frac{\delta t}{\delta x}, v \frac{\delta t}{\delta y}, w \frac{\delta t}{\delta z} \right]$$



# Discretization

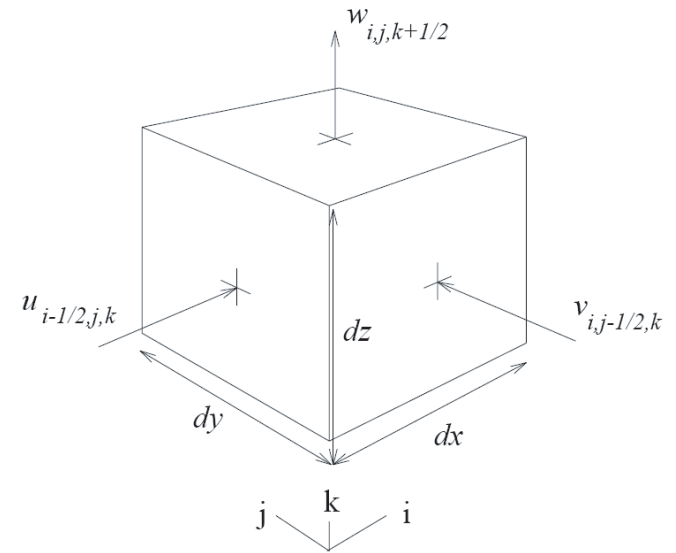
- Rectangular Cartesian grid
- Finite differences
- Velocity defined on cell faces
- Pressure defined in cell
- Stability

$$1 > \max \left[ u \frac{\delta t}{\delta x}, v \frac{\delta t}{\delta y}, w \frac{\delta t}{\delta z} \right]$$

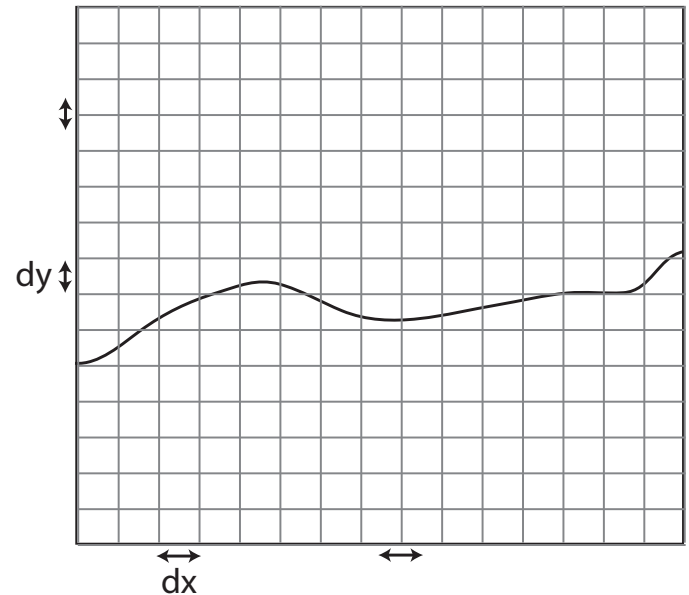


# Discretization

- Rectangular Cartesian grid
- Finite differences
- Velocity defined on cell faces
- Pressure defined in cell
- Stability

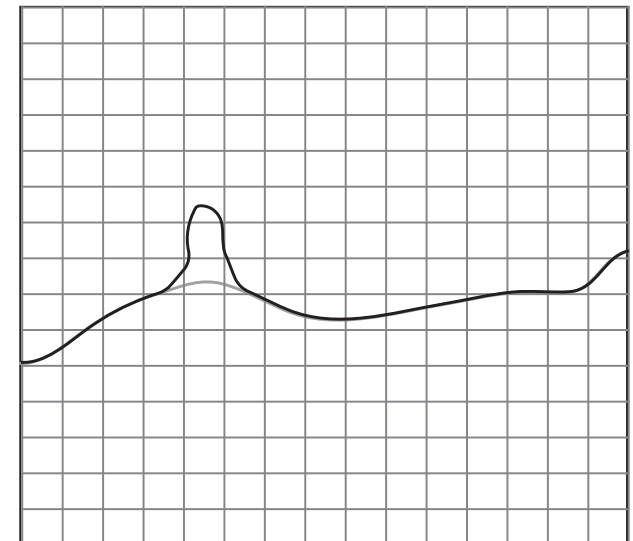
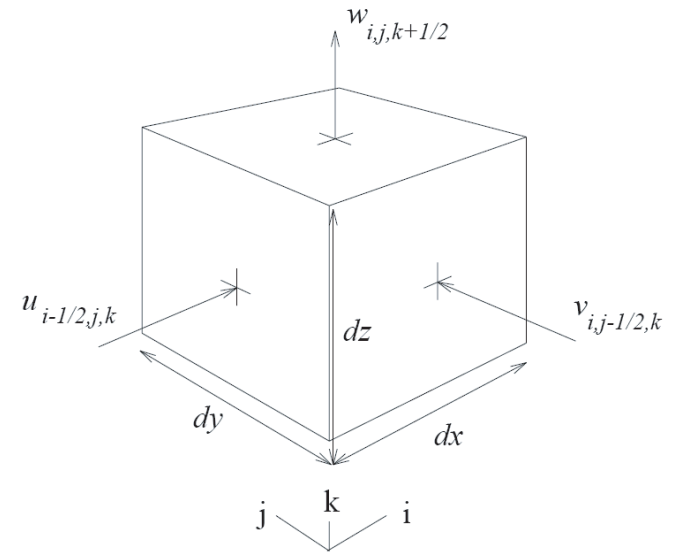


$$1 > \max \left[ u \frac{\delta t}{\delta x}, v \frac{\delta t}{\delta y}, w \frac{\delta t}{\delta z} \right]$$



# Discretization

- Rectangular Cartesian grid
- Finite differences
- Velocity defined on cell faces
- Pressure defined in cell
- Stability



$$1 > \max \left[ u \frac{\delta t}{\delta x}, v \frac{\delta t}{\delta y}, w \frac{\delta t}{\delta z} \right]$$

# Types of Cells

- *Empty*
  - A cell containing no particles
- *Surface*
  - A cell containing at least 1 particle that is adjacent to an *Empty* cell
- *Full*
  - A cell containing at least 1 particle and not a *Surface* cell



# Calculating Velocities

- Velocities from momentum equations

$$\frac{\partial u}{\partial t} = -\frac{\partial p}{\partial t} + g_x - u\frac{\partial u}{\partial x} - v\frac{\partial u}{\partial y} - w\frac{\partial u}{\partial z} + \mu \left( \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2} + \frac{\partial^2 u}{\partial z^2} \right)$$

- Pressure from continuity equations

$$D = \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z}$$

- $\delta p$  is proportional to  $D$

# Consistency

- Velocity and pressure are updated
- Iterate until  $D < \epsilon$

$$\delta p = \beta D$$

$$u_{i+1/2,j,k} = u_{i+1/2,j,k} + (\delta t / \delta x) \delta p$$

$$u_{i-1/2,j,k} = u_{i-1/2,j,k} - (\delta t / \delta x) \delta p$$

$$v_{i,j+1/2,k} = v_{i,j+1/2,k} + (\delta t / \delta y) \delta p$$

$$v_{i,j-1/2,k} = v_{i,j-1/2,k} - (\delta t / \delta y) \delta p$$

$$w_{i,j,k+1/2} = w_{i,j,k+1/2} + (\delta t / \delta z) \delta p$$

$$w_{i,j,k-1/2} = w_{i,j,k-1/2} - (\delta t / \delta z) \delta p$$

$$\tilde{p}_{i,j,k} = p_{i,j,k} + \delta p$$

# Boundary Conditions

- Stationary Obstacles

- Non-slip

- Free-slip

- Inflow and outflow

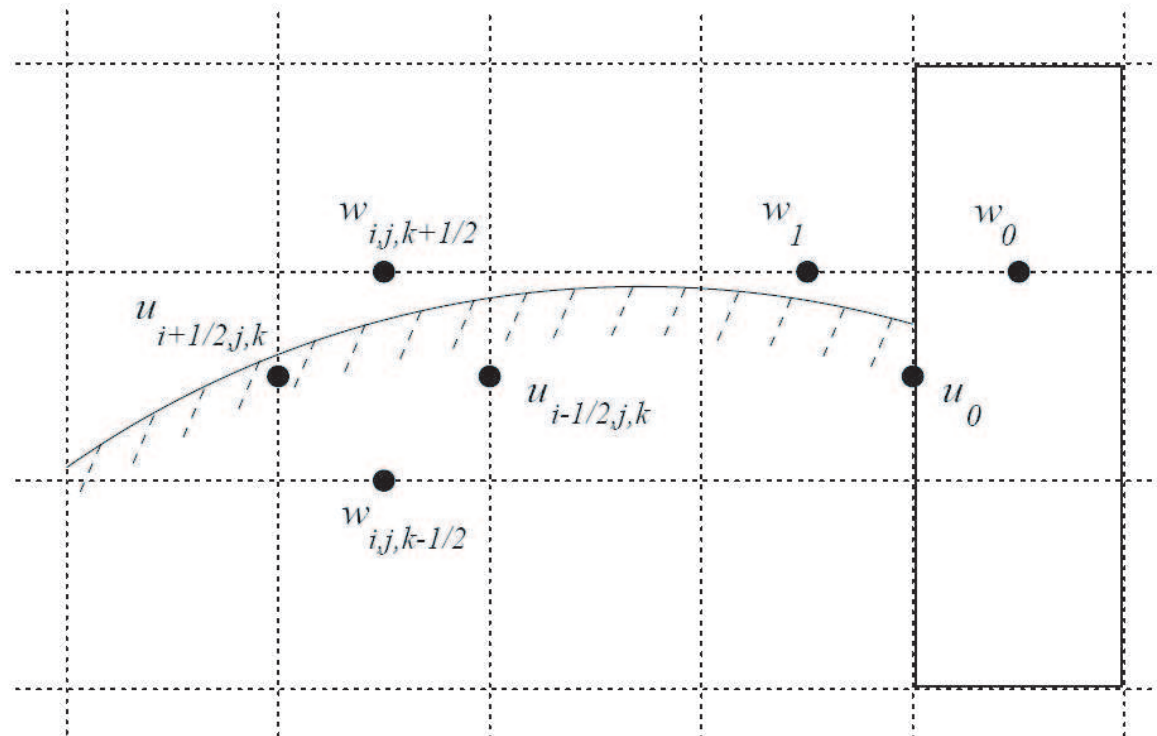
- Free Surfaces

$$u_0 = 0$$

$$p_0 = p_1$$

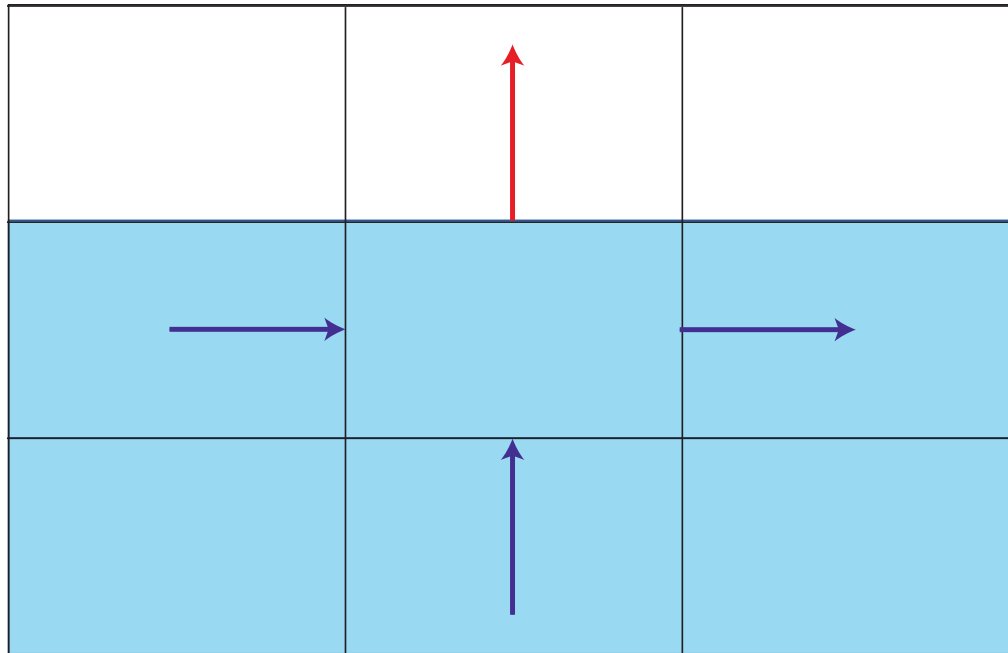
$$w_0 = -w_1$$

$$w_0 = w_1$$



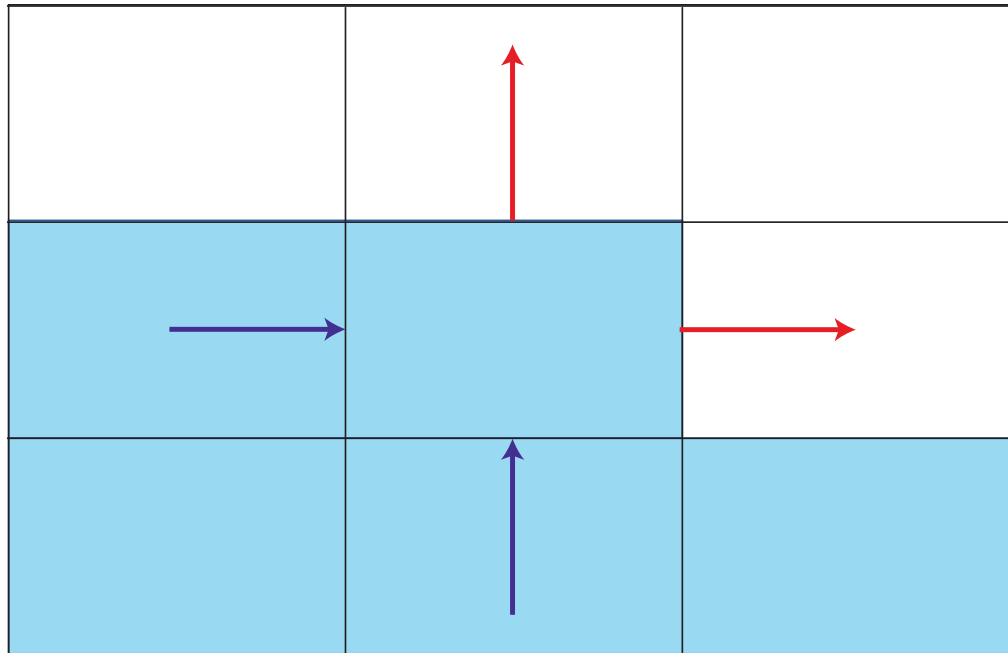
# Free Surface

- Free faces set so divergence zero
- Surface pressure set to atmospheric pressure
- Cases
- 3-D: 64 configurations



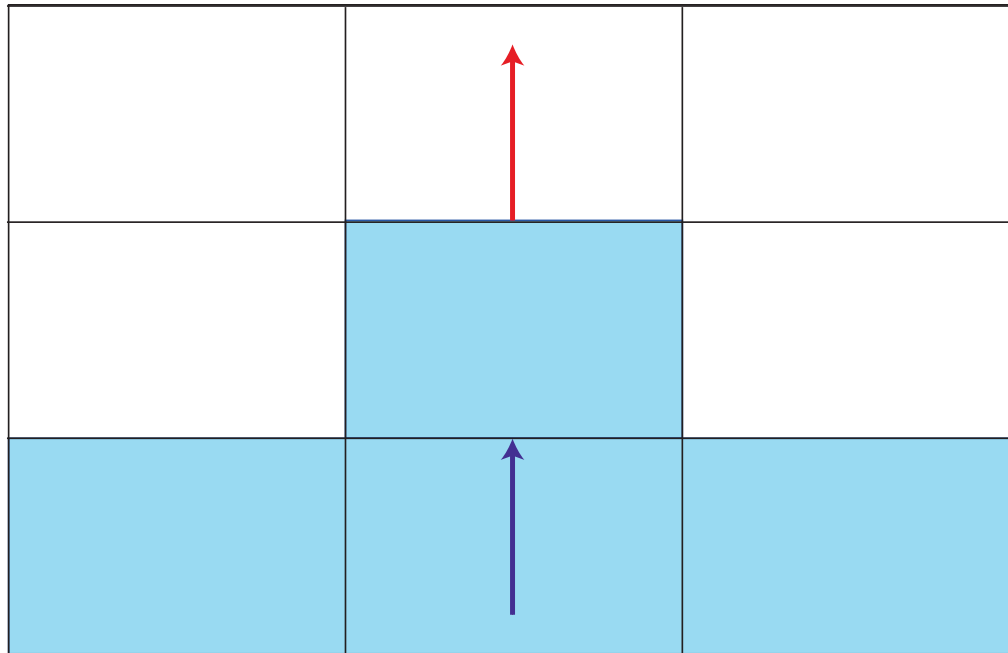
# Free Surface

- Free faces set so divergence zero
- Surface pressure set to atmospheric pressure
- Cases
- 3-D: 64 configurations



# Free Surface

- Free faces set so divergence zero
- Surface pressure set to atmospheric pressure
- Cases
- 3-D: 64 configurations



# Recap

1. Set boundary conditions
2. Classify cells
3. Calculate velocities for *Full* cells
4. Calculate pressures for *Full* cells
5. Update velocities for *Surface* cells
6. Iterate

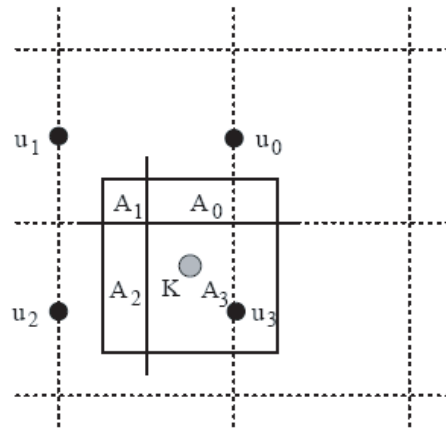
# Problem

- Stability condition
- Limited spatial resolution
- Computational complexity
- Main contribution
  - Interpolating methods for displaying the surface
- 3 methods for tracking fluid positions

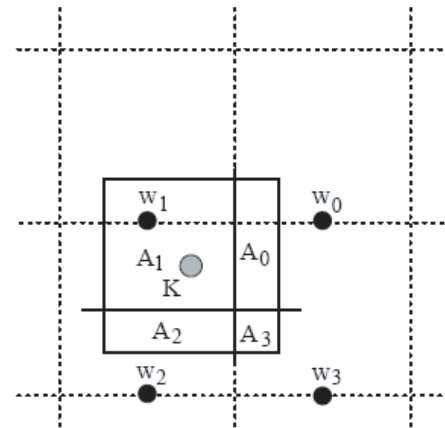


# Marker Particles

- Convect massless particles with local fluid velocity
- Use weighted average of 4 nearest velocities
  - Weighting based on area
  - Multiplied by timestep
- Labeling done based on particles
  - 1 particle test



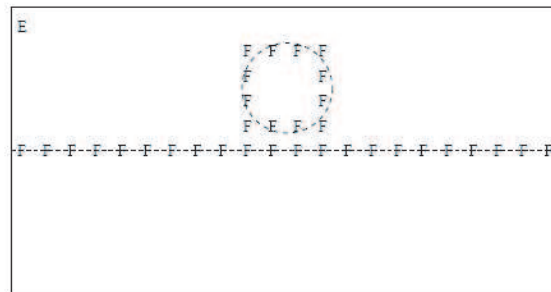
$$u_k = A_0 u_0 + A_1 u_1 + A_2 u_2 + A_3 u_3$$



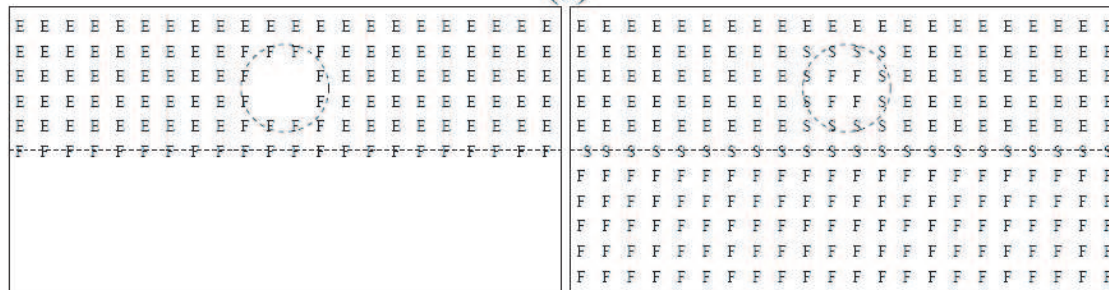
$$w_k = A_0 w_0 + A_1 w_1 + A_2 w_2 + A_3 w_3$$

# Free Surface Particles

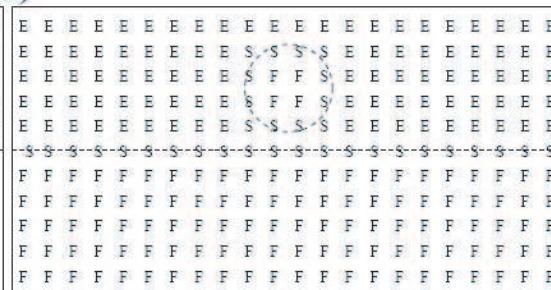
- Only keep particles at surface
- Rules for adding and removing particles
  - If far apart: Insert a particle
  - If close: remove and connect neighbors
- Region growing algorithm



(a)



(b)



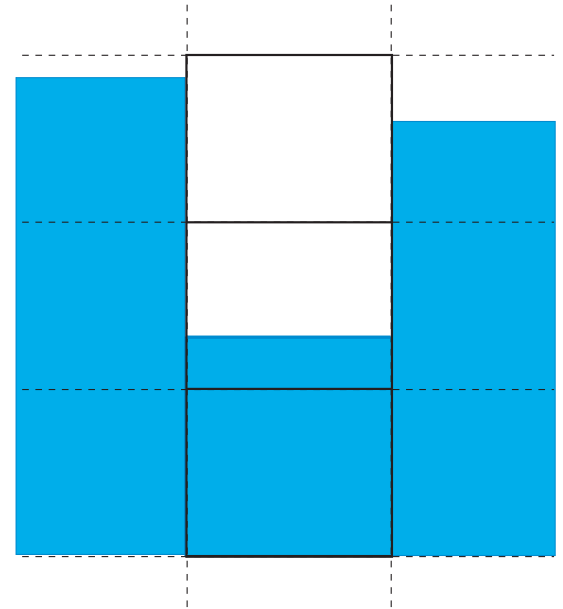
(c)

# Height Field

- Scalar function

$$\frac{\partial h}{\partial t} = w - u \frac{\partial h}{\partial x} - v \frac{\partial h}{\partial y}$$

- Cell configuration trivial
- Need other methods
  - Overturning wave
  - Spray
  - Foam

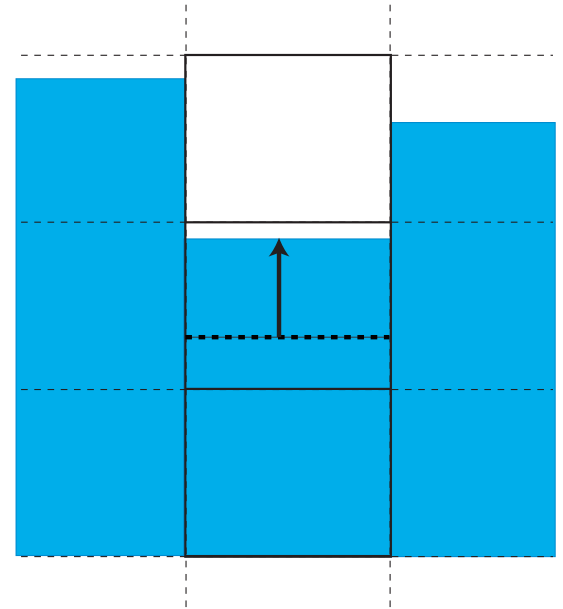


# Height Field

- Scalar function

$$\frac{\partial h}{\partial t} = w - u \frac{\partial h}{\partial x} - v \frac{\partial h}{\partial y}$$

- Cell configuration trivial
- Need other methods
  - Overturning wave
  - Spray
  - Foam



# Buoyancy

- Rigid object
- Force formula

$$\mathbf{f}_{n_i} = -\nabla p_i dV_i + m_i \mathbf{g}$$
$$\mathbf{f}_{fluid} = \sum_i \mathbf{f}_{n_i}$$

- Lagrange equations of motions

$$\mathbf{M}\ddot{\mathbf{q}} + \mathbf{D}\dot{\mathbf{q}} = \mathbf{f}_q + \mathbf{g}_q$$

- Do not affect water flow
- Collisions treated separately

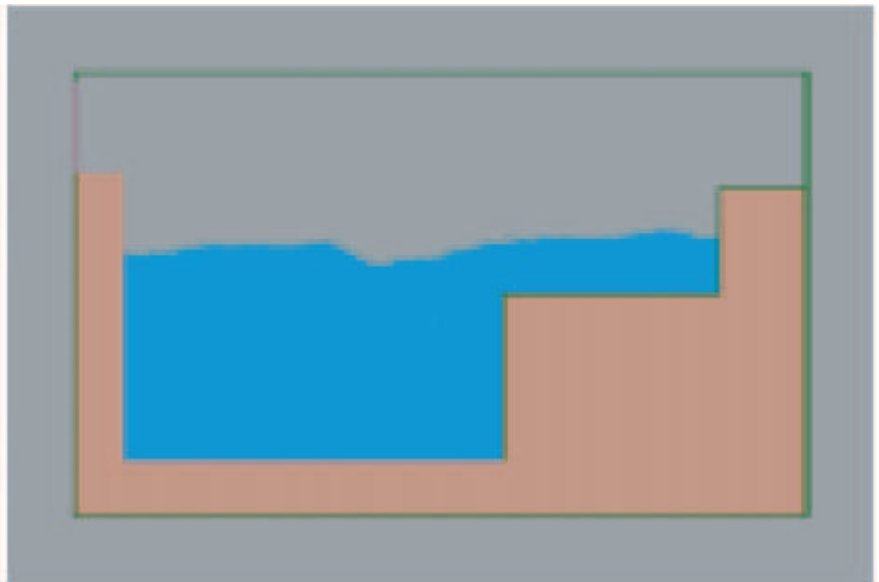
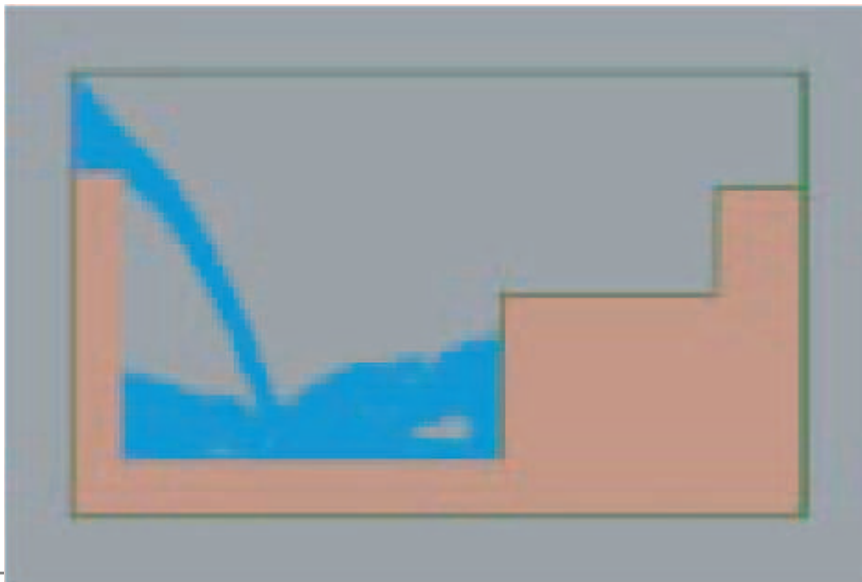
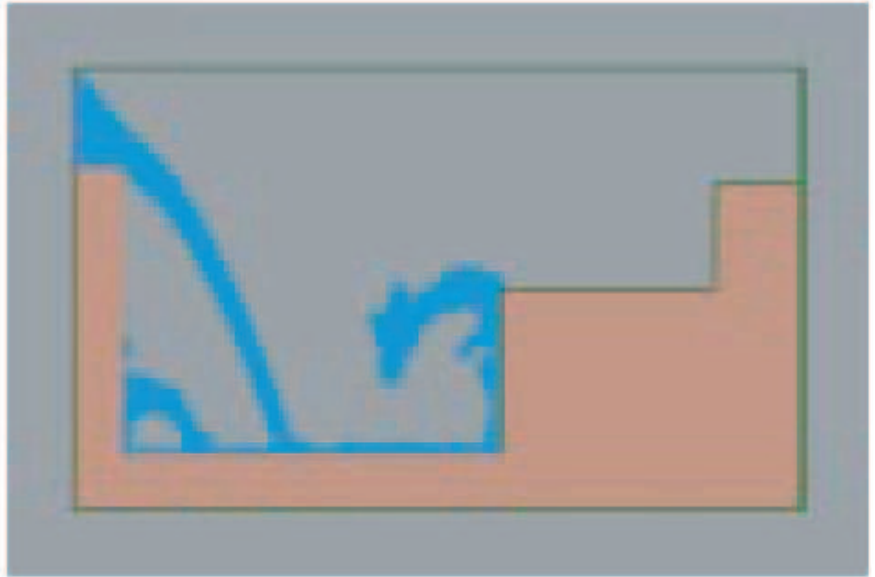
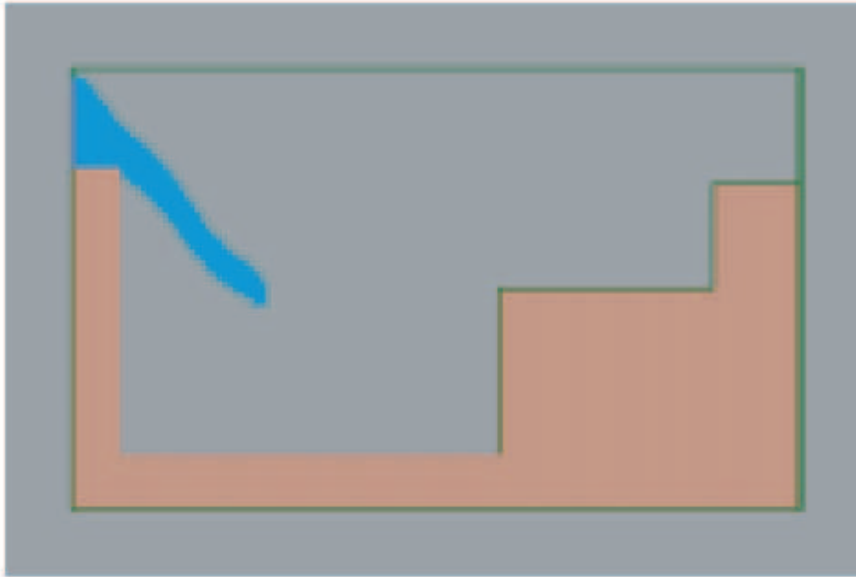
# Control

- Inflow and Outflow
- Instead of atmospheric pressure, apply surface pressure history
  - Constant
  - Time-depedent
  - Height of surface

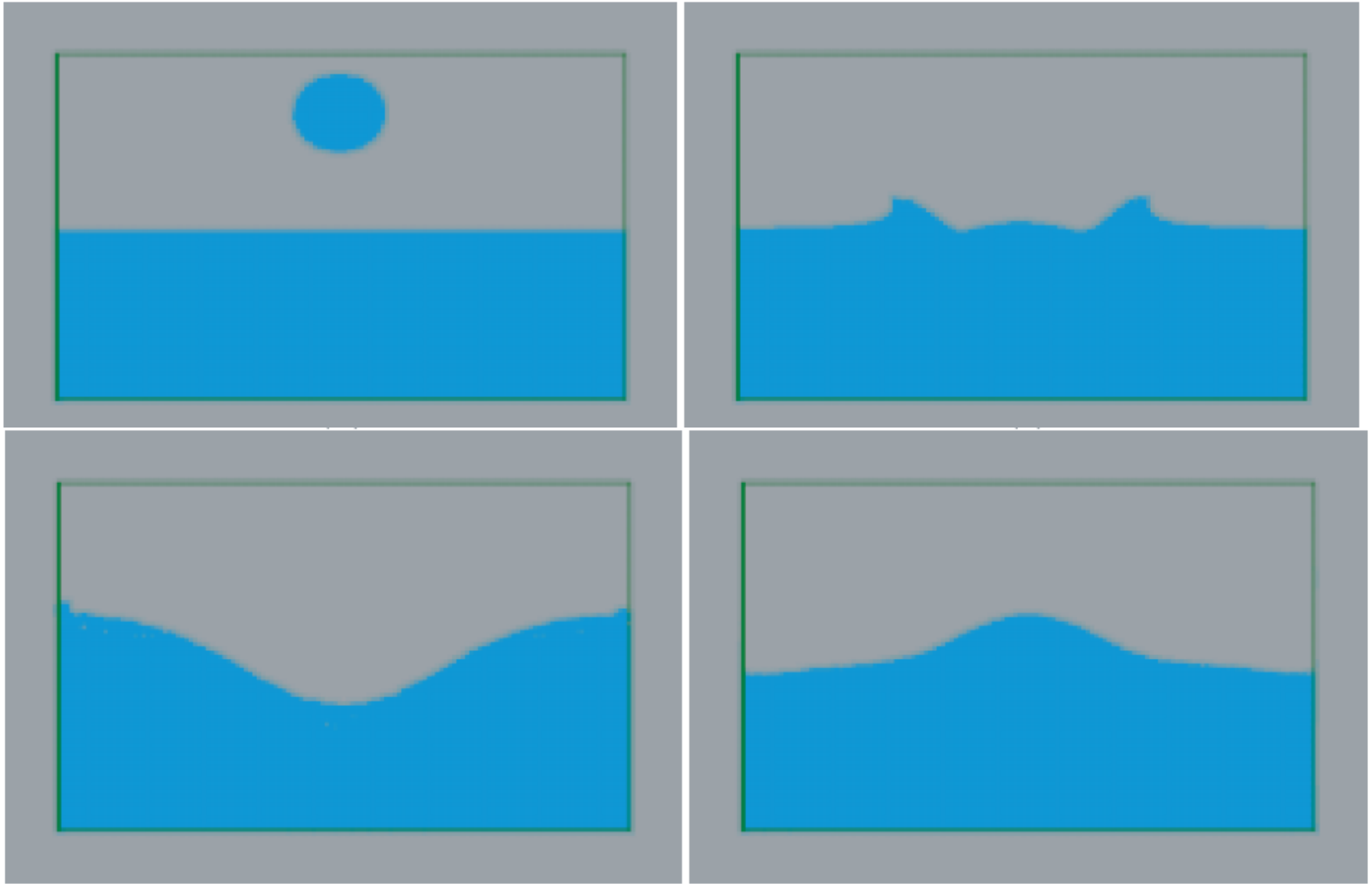
P	P	P
P	P	P

$$p_{applied}(z) = \frac{A + B \cos(Cz - wt)}{\delta t}$$

# Results

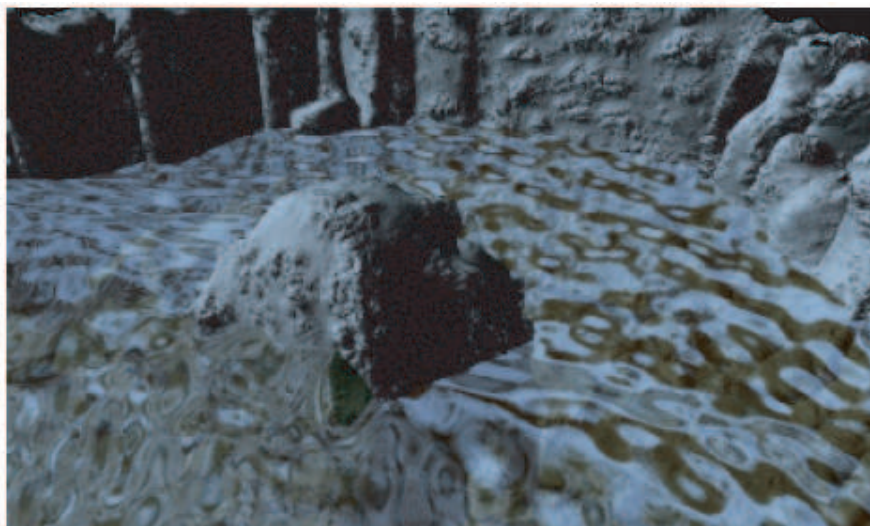
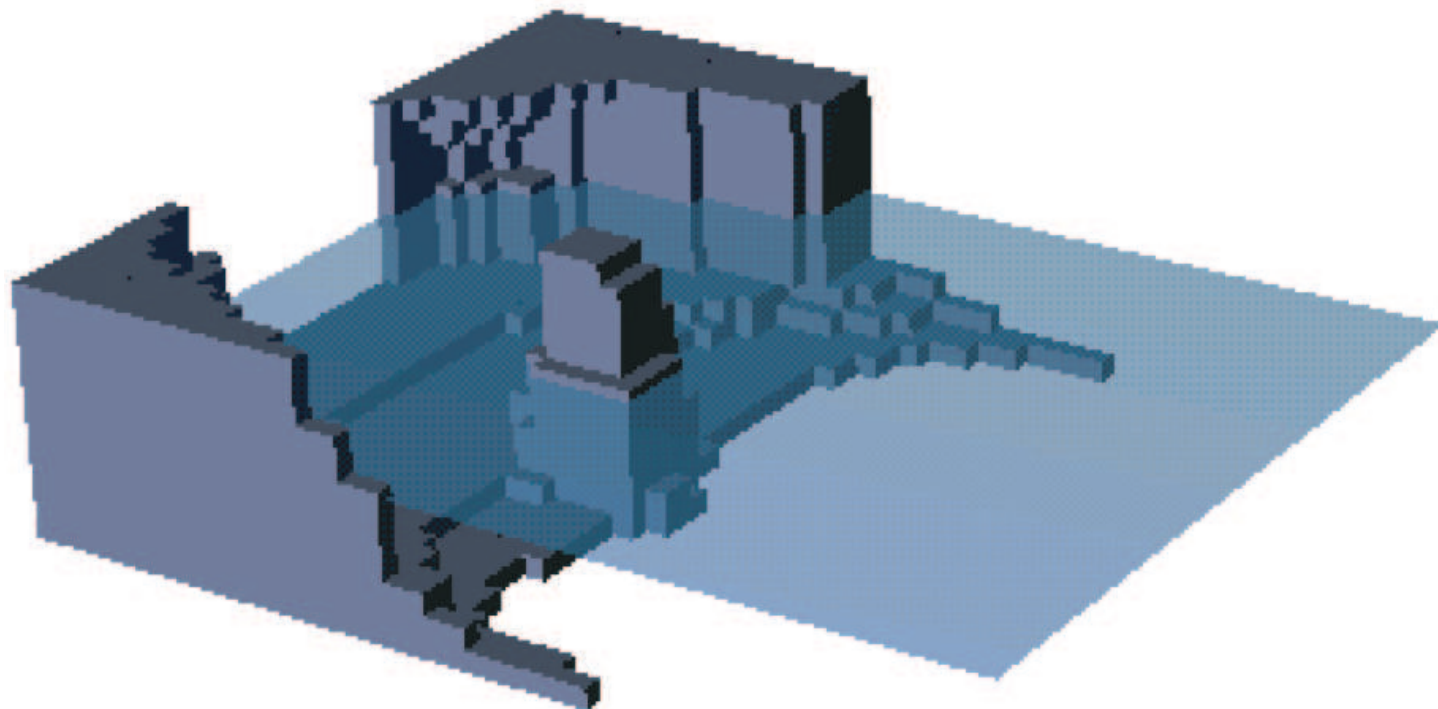


# Results

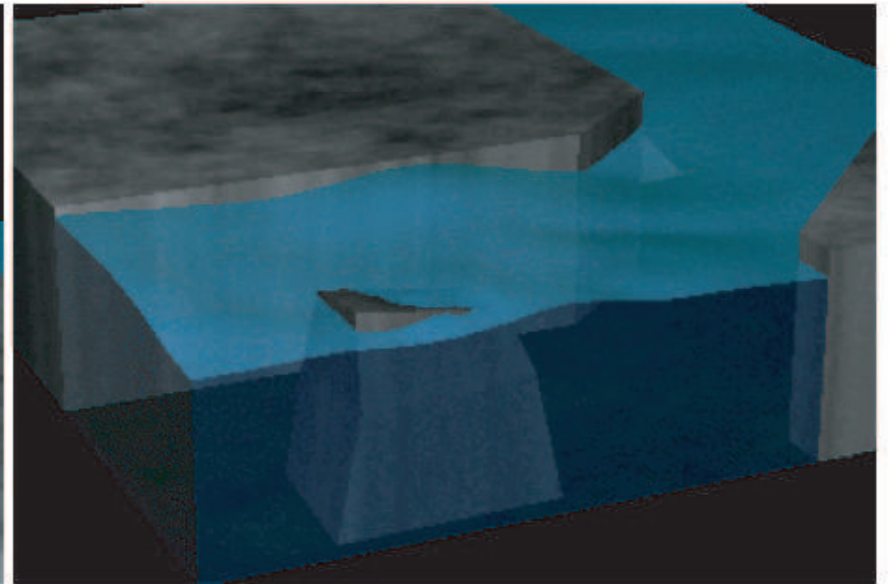
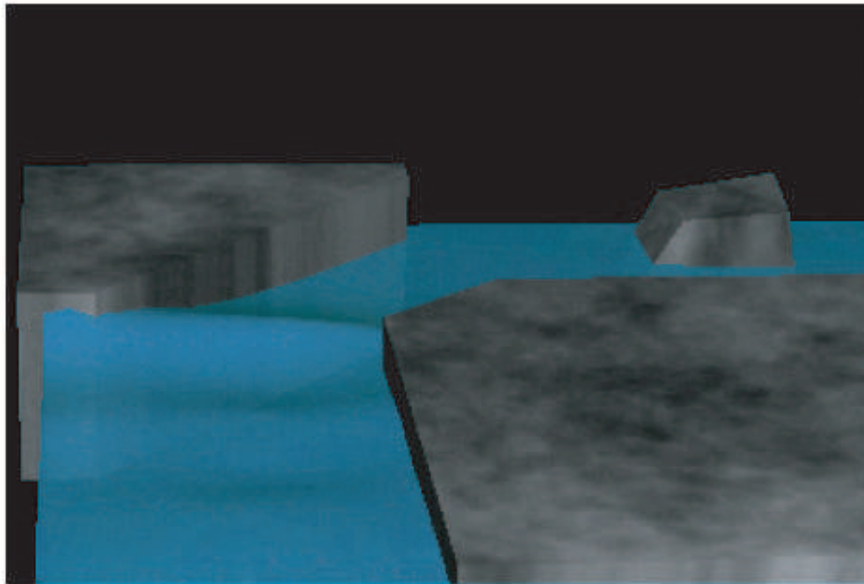
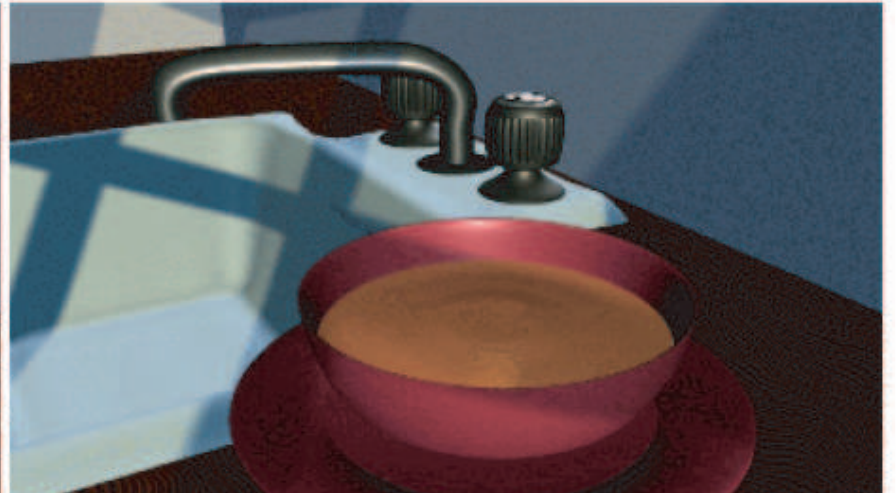
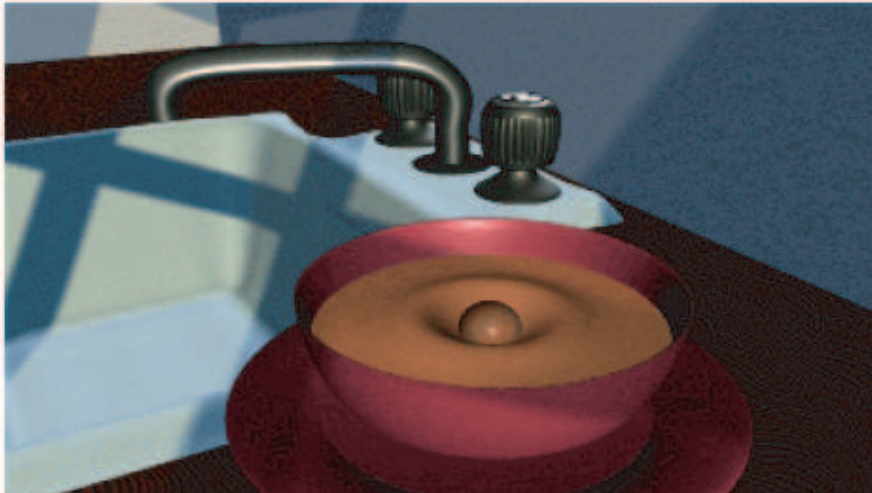




# Results



# Results



# Results

