



# Order-Independent Transparency in DirectX11

**Justin Hensley, Ph.D.** | May 4, 2010  
Senior Member Of Technical Staff  
Advanced Micro Devices, Inc.



# Motivation

Classical problem in computer graphics

Correct rendering of semi-transparent geometry requires sorting

- Blending is an order dependent operation
- Back-to-Front: For src-alpha blending
- Front-to-Back: For dst-alpha blending



# Example



With Sorting

**Arm appears in front of body**

**Skeleton hidden**

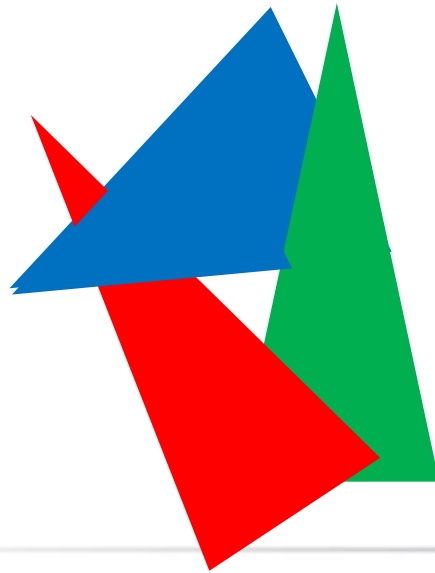
No Sorting



# Sorting Issues

Sometimes sorting triangles is enough but not always

- **Difficult to sort:** Multiple meshes interacting (many draw calls)
- **Impossible to sort:** Intersecting triangles (must sort fragments)



Try doing this  
in PowerPoint!



# Before DirectX® 11

Until now, only real solution has been “depth peeling”

- Expensive (requires many passes over the scene)
- Liu, et al. *Efficient Depth Peeling via Bucket Sort*. HPG 2009.

Other software methods require concurrent read/write to the same buffer

New hardware

- A-buffer
- F-buffer
- K-buffer



# OIT Using Fragment Linked Lists

Two-pass method using reverse linked list

Two UAV buffers required

Works with and without MSAA

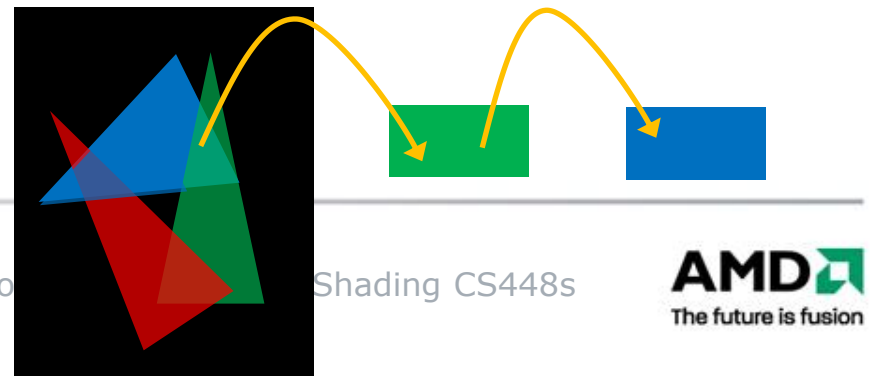
Good performance

Correct transparency



# Algorithm Overview

0. Render opaque scene objects
1. Render transparent scene objects
  - a) All fragments are stored using per-pixel linked lists
  - b) Store fragment's: color, alpha, & depth
2. Screen quad resolves and composites fragment lists
  - a) Pixel shader sorts associated linked list
  - b) Composite fragments in sorted order with background
  - c) Output final fragment



# Fragment and Link Buffer

The “Fragment & Link” buffer contains data and links for all visible transparent fragments

Must be large enough to accommodate the maximum transparent overdraw allowed

RWStructuredBuffer UAV

```
struct Fragment_And_Link_Buffer_STRUCT
{
    uint    uPixelColor;    // Fragment data
    float   fDepth;        // Fragment depth
    uint    uNext;         // Link to next fragment
};
```

UAV counter initialized to zero





# Start Offset Buffer

The "Start Offset" buffer contains the offset of the last fragment written for every pixel position

- Think of this as the "head" buffer pointing to the start of the linked list

Screen-sized (width \* height \* UINT32)

Initialized to magic value (e.g. -1)

- Magic value indicates no more fragments are stored

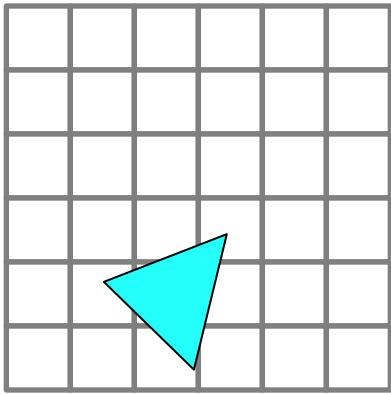
RWByteAddressBuffer UAV



# Step 0 – Render Opaque

Render all opaque geometry normally

Render Target



# Step 1 – Create Linked List (1)

Render transparent geometry via a pixel shader

Color writes are disabled

UAV buffers set as input/output

`[earlydepthstencil]` is used to ensure only visible fragments are stored in linked list

- Depth testing is performed before the PS thus no fragment will be stored if depth test for this fragment fails



# Step 1 – Create Linked List (2)

For every pixel:

- Calculate pixel data (color, depth etc.)
- Retrieve current pixel count from Fragment & Link UAV

```
uint uPixelCount = FragmentAndLinkBuffer.IncrementCounter();
```

- Swap offsets in Start Offset UAV

```
uint uOldStartOffset;
```

```
StartOffsetBuffer.InterlockedExchange(  
    PixelScreenSpacePositionLinearAddress,  
    uPixelCount, uOldStartOffset);
```

- Add new entry to Fragment & Link UAV

```
Fragment_And_Link_Buffer_STRUCT Element;
```

```
Element.uPixelColor = uPixelcolor;
```

```
Element.fDepth = fPixelDepth;
```

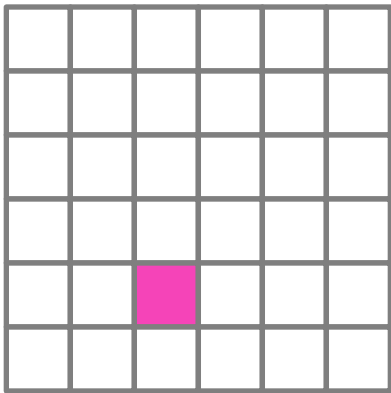
```
Element.uNext = uOldStartOffset;
```

```
FragmentAndLinkBuffer[uPixelCount] = Element;
```



# Step 1 – Create Linked List (3a)

Render Target



Start Offset Buffer

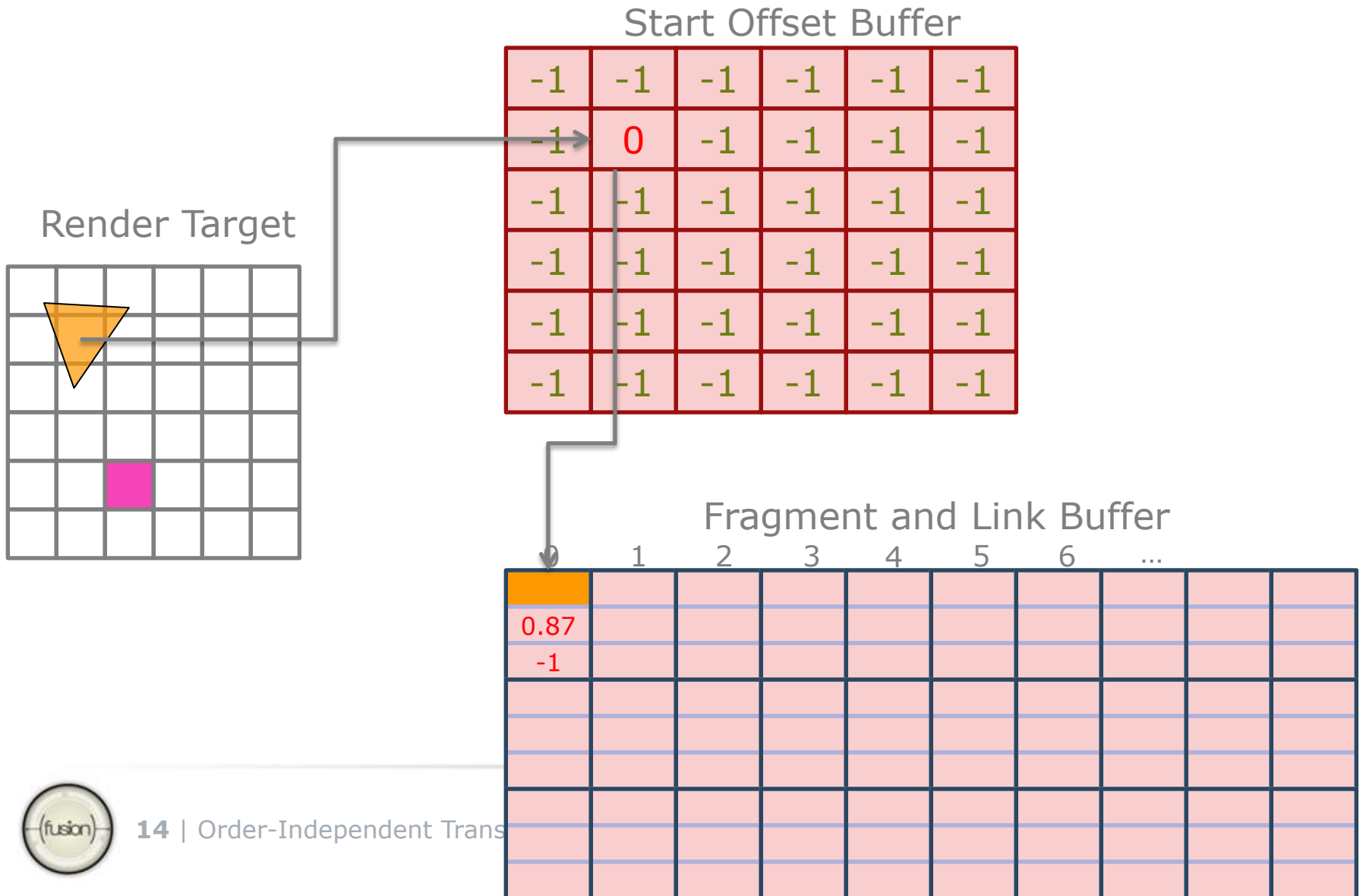
-1	-1	-1	-1	-1	-1
-1	-1	-1	-1	-1	-1
-1	-1	-1	-1	-1	-1
-1	-1	-1	-1	-1	-1
-1	-1	-1	-1	-1	-1
-1	-1	-1	-1	-1	-1

Fragment and Link Buffer

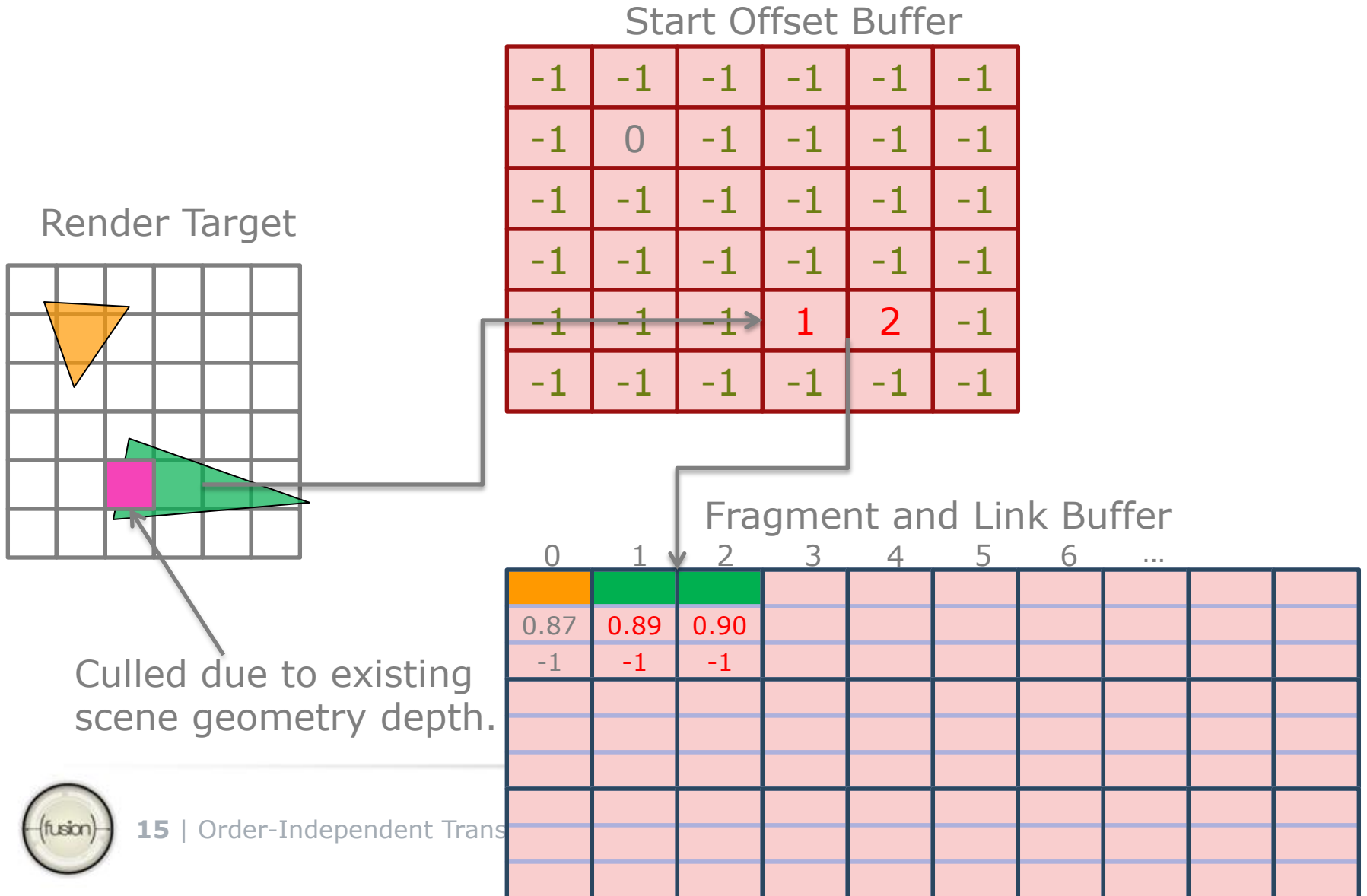
0	1	2	3	4	5	6	...		



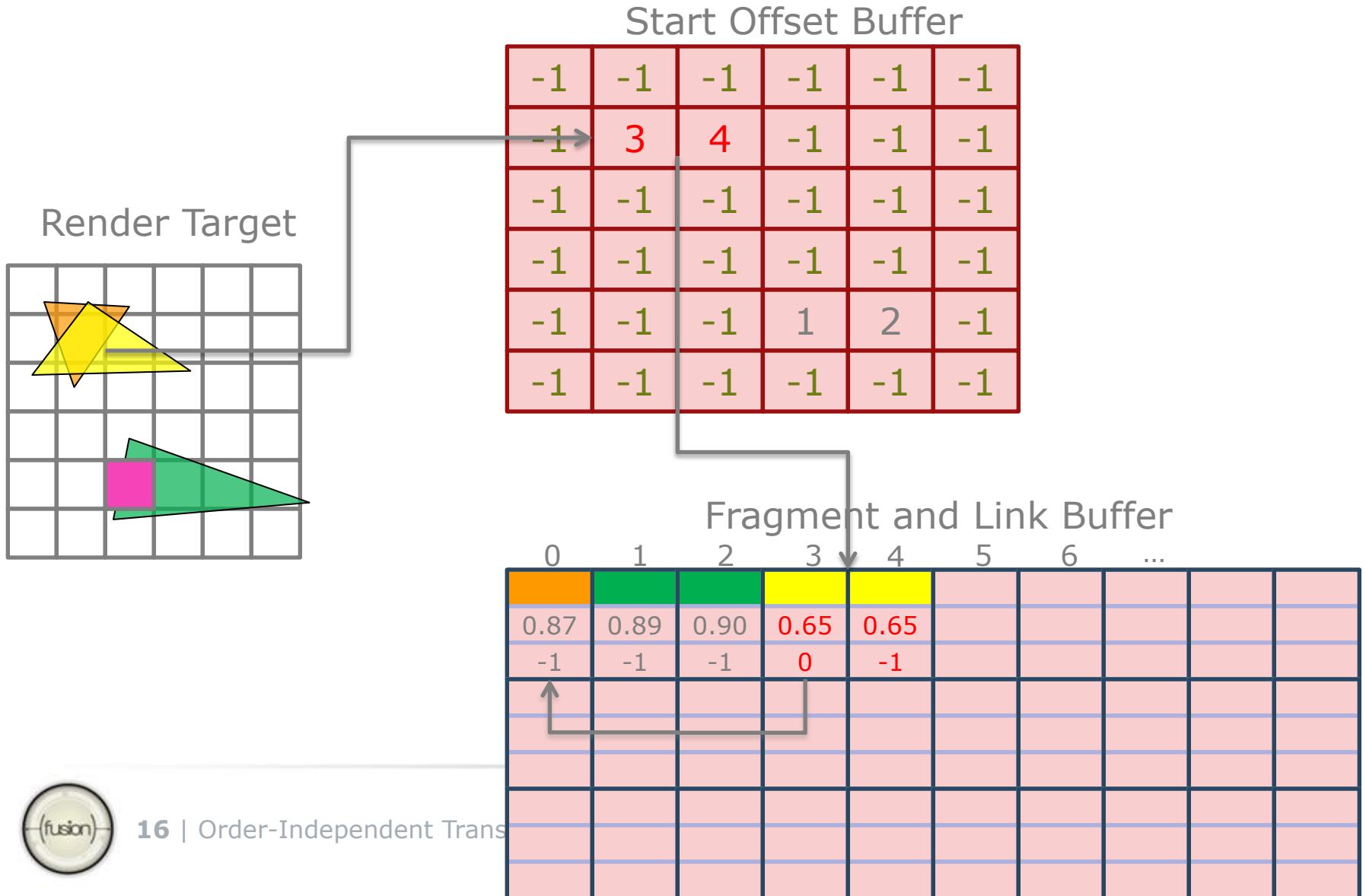
# Step 1 – Create Linked List (3b)



# Step 1 - Create Linked List (3c)

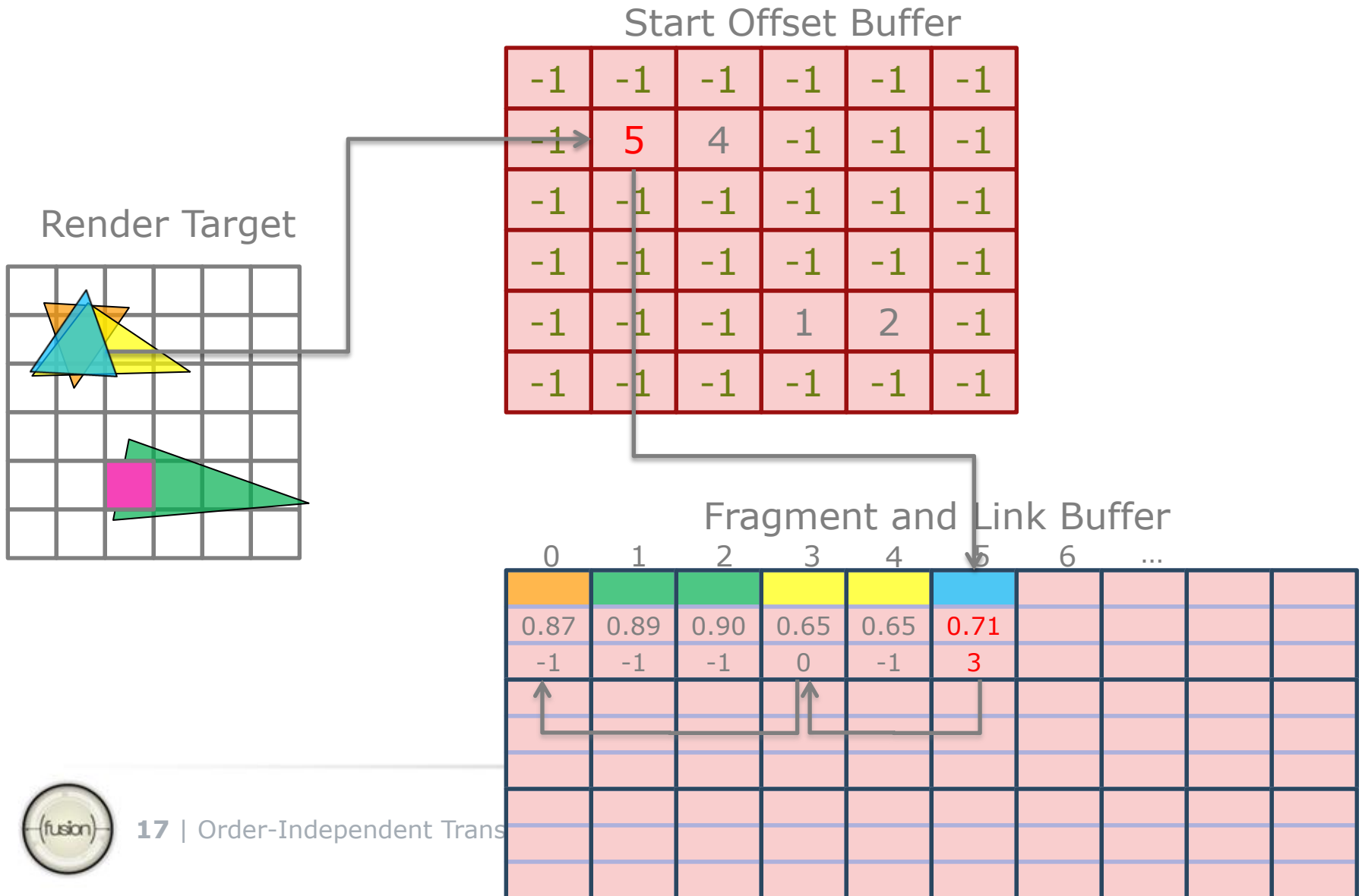


# Step 1 - Create Linked List (3d)





# Step 1 - Create Linked List (3d)



## Step 2 – Render Fragments (1)

Render a fullscreen triangle/quad via a PS

For each pixel:

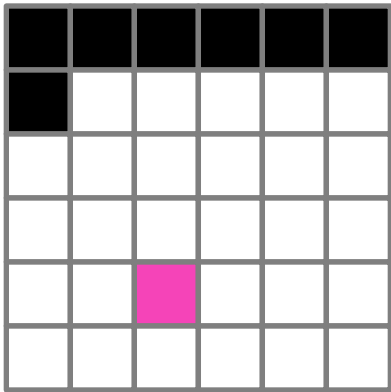
- Fetch offset corresponding to current pixel location from “Start Offset” buffer
- While offset is not -1:
  - Fetch fragment from Fragment & Link buffer at current offset
  - Store fragment in temporary array
  - Retrieve new offset from fragment link
- Sort fragment temporary array back to front
- Perform “manual” blending of fragments in the pixel shader

Optimization: use depthstencil test to only fetch fragments for locations with at least one fragment



# Step 2 – Render Fragments (2a)

Render Target



(0,0)->(1,1):

Fetch Start Offset: -1

-1 indicates no fragment to render

Start Offset Buffer

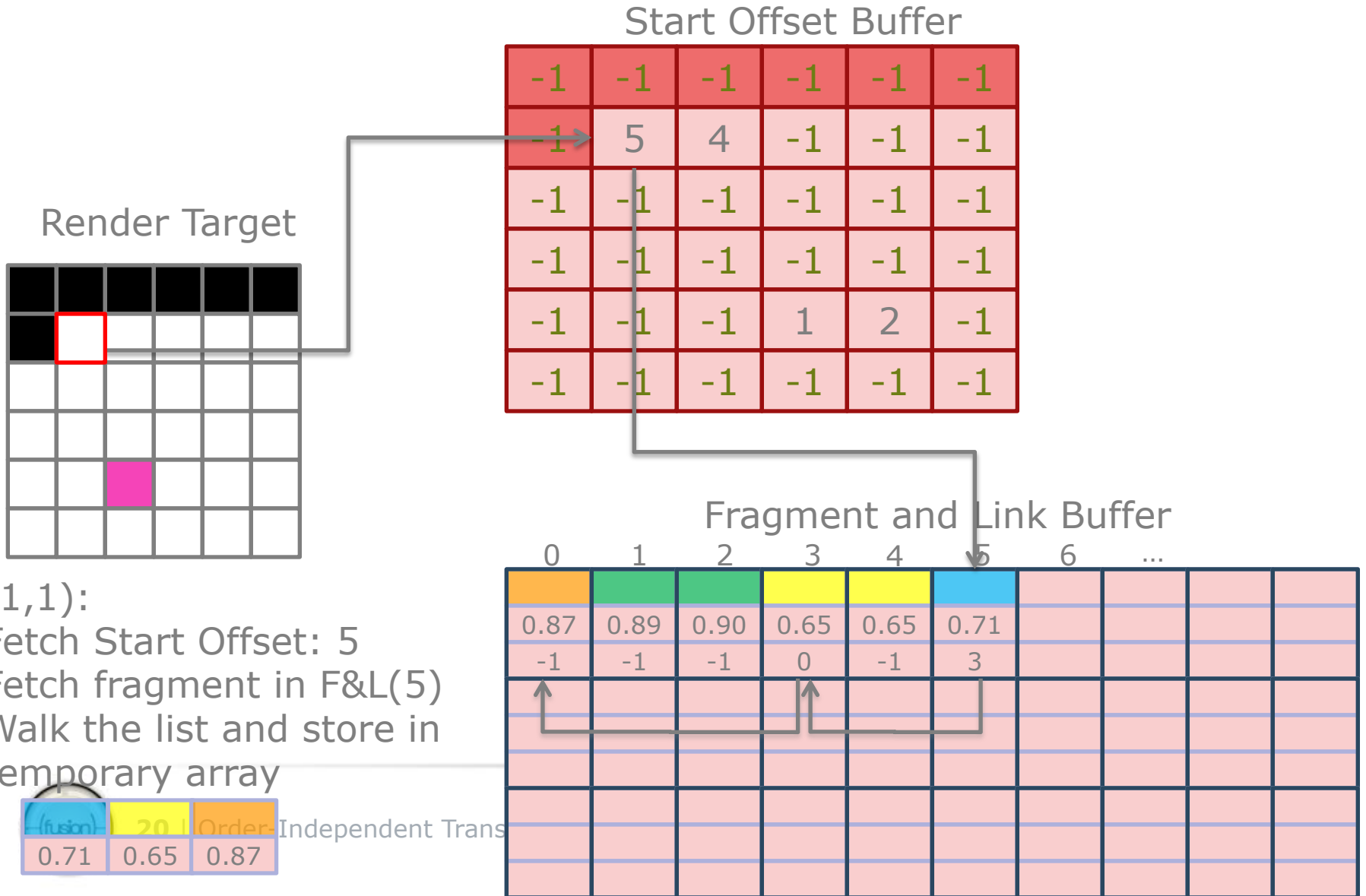
-1	-1	-1	-1	-1	-1
-1	5	4	-1	-1	-1
-1	-1	-1	-1	-1	-1
-1	-1	-1	-1	-1	-1
-1	-1	-1	1	2	-1
-1	-1	-1	-1	-1	-1

Fragment and Link Buffer

0	1	2	3	4	5	6	...		
0.87	0.89	0.90	0.65	0.65	0.71				
-1	-1	-1	0	-1	3				

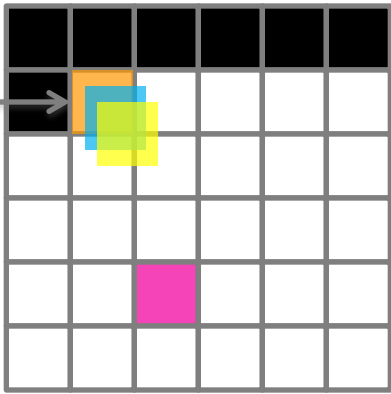


# Step 2 – Render Fragments (2a)



# Step 2 – Render Fragments (2a)

Render Target



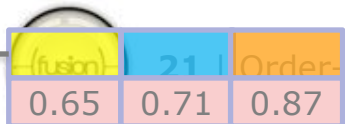
Start Offset Buffer

-1	-1	-1	-1	-1	-1
-1	5	4	-1	-1	-1
-1	-1	-1	-1	-1	-1
-1	-1	-1	-1	-1	-1
-1	-1	-1	1	2	-1
-1	-1	-1	-1	-1	-1

Fragment and Link Buffer

0	1	2	3	4	5	6	...		
0.87	0.89	0.90	0.65	0.65	0.71				
-1	-1	-1	0	-1	3				

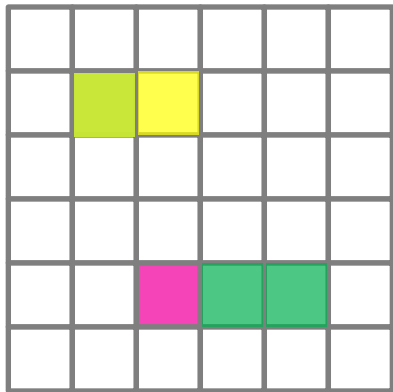
(1,1):  
Sort temporary array  
Blend colors and write out



Independent Trans

# Step 2 – Render Fragments (2a)

Render Target



Start Offset Buffer

-1	-1	-1	-1	-1	-1
-1	5	4	-1	-1	-1
-1	-1	-1	-1	-1	-1
-1	-1	-1	-1	-1	-1
-1	-1	-1	1	2	-1
-1	-1	-1	-1	-1	-1

Fragment and Link Buffer

0	1	2	3	4	5	6	...		
0.87	0.89	0.90	0.65	0.65	0.71				
-1	-1	-1	0	-1	3				



# Demo



# MSAA Support

Minor changes to the algorithm

Step 1 - Sample coverage stored in fragment data (SV\_COVERAGE)

Step 2

- Executed at *sample frequency* (declaring SV\_SAMPLEINDEX)
- Store only covered fragments in temporary buffer

```
if (Element.uCoverage & (1<<input.uSample) )  
{  
    // Store fragment into temporary array for later sorting  
    // ...  
}
```

Pros:

- Can use depthstencil for early rejection for pixels that don't contain any fragments
- Destination Render Target stays multisampled





# MSAA Support (2)

## Step 2 (alternative method)

- Executed at *pixel frequency*
- Store fragments into temporary buffer
- Perform per-sample sorting of fragments
- Manual blending of samples
- Average (resolve) blended samples

## Pros:

- Slightly faster than per-sample execution
- Can be done with a Compute Shader

## Cons:

- Destination Render Target is single sample
- Depthstencil testing is not available for early rejection



# UAV Counter Alternative

Create a 1x1 UAV, this “Global Counter” is used to allocate links in our linked lists. Initialized to 0.

Instead of IncrementCounter(), get the current value of Global Counter and increment it using InterlockedAdd().

All threads will be fighting for atomic access in global memory

- Use a NxN buffer with pixel sub-counters to improve performance

The global counter method is ~30% slower than using the UAV counter



# Linked List Method Limitations

“Start Offset” UAV buffer cannot be Texture2D

- Atomic operations require linear address

Compute Shader cannot write to MSAA RTs

- Would allow CS to be used for rendering phase

Fragment sorting requires fixed-size array

- Imposes a “max overdraw” limit to the algorithm
- Should not be a problem if scene is known or do a “resize”

On-the-fly sorting at fragment storing phase runs into shader compiler limitations (breaking loops on UAV fetch result)



# Future Work

Other potential applications

- Programmable blend
- Motion Blur
- Shadows

More complex data structures



## For More Info

<http://developer.amd.com>

### Demos:

<http://developer.amd.com/samples/demos/pages/ATIRadeonHD5800SeriesRealTimeDemos.aspx>

### HPG:

HIGH-PERFORMANCE GRAPHICS  
SAARBRUCKEN, GERMANY      JUNE 25-27, 2010



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